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Jan R. Magnus

Tilburg University
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# The asymptotic variance of the pseudo maximum likelihood estimator 

Jan R. Magnus*<br>Department of Econometrics \& OR, Tilburg University and Department of Economics, University of Tokyo

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## Abstract:

We present an analytical closed-form expression for the asymptotic variance matrix in the misspecified multivariate regression model.

## Keywords:

Misspecification, Robustness, Multivariate regression.

## Author's address.

Jan R. Magnus, Department of Econometrics \& Operations Research, Tilburg University, P.O. Box 90153, 5000 LE Tilburg, The Netherlands. E-mail: magnus@uvt.nl.

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## 1 Introduction

Since the classic papers of Akaike (1973), White (1982), and Vuong (1989), there exists a growing literature devoted to the study of misspecified models. Furthermore, during the last decade, the "sandwich" variance matrix (also known as the "robust" variance matrix) has been shown to be the proper variance matrix in misspecified models and has been widely used. The sandwich variance matrix estimation procedure was introduced by Huber (1967) and White (1982), and it yields consistent variance matrix estimators, also (and in particular) when the assumed model is misspecified.

The objective of this paper is to derive the analytical closed-form expression of the sandwich variance matrix within the context of the misspecified multivariate regression model. We also derive scalar measures of the asymptotic variance, in particular the trace, determinant, and norm, which play a role in the construction of information criteria. An example of such an application is provided in Bozdogan (2007), where the information complexity (ICOMP) criterion is used to extend Bozdogan and Haughton's (1998) results from the univariate misspecified regression model to the multivariate case.

## 2 Multivariate normal regression

Consider a set of $n$ vectors $y_{1}, \ldots, y_{n}$, each of order $p \times 1$, whose first two moments are given by

$$
\mathrm{E}\left(y_{i}\right)=B^{\prime} x_{i}, \quad \operatorname{var}\left(y_{i}\right)=\Sigma
$$

where $B$ is a $k \times p$ matrix of unknown coefficients, $X:=\left(x_{1}, \ldots, x_{n}\right)^{\prime}$ is a nonrandom $n \times k$ matrix of full column rank $k$, and $\Sigma=\left(\sigma_{i j}\right)$ is a positive definite unknown $p \times p$ matrix. The full set of coefficients is thus $\theta:=$ $\left((\operatorname{vec} B)^{\prime},(\operatorname{vech}(\Sigma))^{\prime}\right)^{\prime}$, of order $\left(k p+\frac{1}{2} p(p+1)\right) \times 1$, where vech $(\cdot)$ denotes the half-vec operator defined in the Appendix. Assume that $y_{i}$ and $y_{j}$ are uncorrelated for all $i \neq j$, and let $Y:=\left(y_{1}, \ldots, y_{n}\right)^{\prime}$, of order $n \times p$. Finally, let $n \geq p+k$; this is a necessary condition without which the estimator $\hat{\Sigma}$ in (3) below would be singular. These assumptions imply that

$$
\mathrm{E}(Y)=X B, \quad \operatorname{var}(\operatorname{vec} Y)=\Sigma \otimes I_{n}
$$

If, in addition, we assume normality, then the log-likelihood function of the sample $y_{1}, \ldots, y_{n}$ is given by

$$
\begin{equation*}
\ell(\theta)=-\frac{n p}{2} \log 2 \pi-\frac{n}{2} \log |\Sigma|-\frac{1}{2} \operatorname{tr}(Y-X B) \Sigma^{-1}(Y-X B)^{\prime}, \tag{1}
\end{equation*}
$$

see, for example, Magnus and Neudecker (1988, p. 321). The first differential of the log-likelihood is

$$
\begin{align*}
\mathrm{d} \ell= & -\frac{n}{2} \operatorname{tr} \Sigma^{-1} \mathrm{~d} \Sigma+\frac{1}{2} \operatorname{tr}(Y-X B) \Sigma^{-1}(\mathrm{~d} \Sigma) \Sigma^{-1}(Y-X B)^{\prime} \\
& +\operatorname{tr} X(\mathrm{~d} B) \Sigma^{-1}(Y-X B)^{\prime} \\
= & \frac{1}{2} \operatorname{tr}\left(\Sigma^{-1}(Y-X B)^{\prime}(Y-X B) \Sigma^{-1}-n \Sigma^{-1}\right) \mathrm{d} \Sigma \\
& +\operatorname{tr} \Sigma^{-1}(Y-X B)^{\prime} X \mathrm{~d} B, \tag{2}
\end{align*}
$$

leading to the first-order conditions

$$
\Sigma^{-1}(Y-X B)^{\prime}(Y-X B) \Sigma^{-1}=n \Sigma^{-1}, \quad X^{\prime}(Y-X B) \Sigma^{-1}=0
$$

and hence to the maximum likelihood estimators

$$
\begin{equation*}
\hat{B}=\left(X^{\prime} X\right)^{-1} X^{\prime} Y, \quad \hat{\Sigma}=\frac{(Y-X \hat{B})^{\prime}(Y-X \hat{B})}{n}=\frac{Y^{\prime} M Y}{n} \tag{3}
\end{equation*}
$$

where $M:=I_{n}-X\left(X^{\prime} X\right)^{-1} X^{\prime}$ is the usual idempotent matrix.
Taking the differential of (2), we obtain the second differential of the log-likelihood as

$$
\begin{aligned}
\mathrm{d}^{2} \ell= & \operatorname{tr}\left(\mathrm{d} \Sigma^{-1}\right)(Y-X B)^{\prime}(Y-X B) \Sigma^{-1} \mathrm{~d} \Sigma-\frac{n}{2} \operatorname{tr}\left(\mathrm{~d} \Sigma^{-1}\right) \mathrm{d} \Sigma \\
& +2 \operatorname{tr}\left(\mathrm{~d} \Sigma^{-1}\right)(Y-X B)^{\prime} X \mathrm{~d} B-\operatorname{tr} \Sigma^{-1}(\mathrm{~d} B)^{\prime} X^{\prime} X \mathrm{~d} B .
\end{aligned}
$$

Then, using the fact that $\mathrm{E}(Y-X B)=0$ and $\mathrm{E}(Y-X B)^{\prime}(Y-X B)=n \Sigma$, we find

$$
\begin{align*}
-\mathrm{Ed}^{2} \ell= & \frac{n}{2} \operatorname{tr} \Sigma^{-1}(\mathrm{~d} \Sigma) \Sigma^{-1} \mathrm{~d} \Sigma+\operatorname{tr} \Sigma^{-1}(\mathrm{~d} B)^{\prime} X^{\prime} X \mathrm{~d} B \\
= & \frac{n}{2}(\mathrm{~d} \operatorname{vech}(\Sigma))^{\prime} D_{p}^{\prime}\left(\Sigma^{-1} \otimes \Sigma^{-1}\right) D_{p} \mathrm{~d} \operatorname{vech}(\Sigma) \\
& +(\mathrm{d} \operatorname{vec} B)^{\prime}\left(\Sigma^{-1} \otimes X^{\prime} X\right) \mathrm{d} \operatorname{vec} B, \tag{4}
\end{align*}
$$

where $D_{p}$ denotes the $p^{2} \times \frac{1}{2} p(p+1)$ duplication matrix, defined in the Appendix. Hence we obtain

Theorem 1: In the correctly specified case, the information matrix is given by

$$
\mathcal{I}=\left(\begin{array}{cc}
\Sigma^{-1} \otimes X^{\prime} X & 0 \\
0 & \frac{n}{2} D_{p}^{\prime}\left(\Sigma^{-1} \otimes \Sigma^{-1}\right) D_{p}
\end{array}\right)
$$

and its inverse by

$$
\mathcal{I}^{-1}=\left(\begin{array}{cc}
\Sigma \otimes\left(X^{\prime} X\right)^{-1} & 0 \\
0 & \frac{2}{n} D_{p}^{+}(\Sigma \otimes \Sigma) D_{p}^{+\prime}
\end{array}\right)
$$

where $D_{p}^{+}=\left(D_{p}^{\prime} D_{p}\right)^{-1} D_{p}^{\prime}$. Furthermore,

$$
\operatorname{tr} \mathcal{I}^{-1}=(\operatorname{tr} \Sigma)\left(\operatorname{tr}\left(X^{\prime} X\right)^{-1}\right)+\frac{1}{2 n}\left(\operatorname{tr} \Sigma^{2}+(\operatorname{tr} \Sigma)^{2}+2 \sum_{j=1}^{p} \sigma_{j j}^{2}\right)
$$

and

$$
\left|\mathcal{I}^{-1}\right|=2^{p} n^{-\frac{1}{2} p(p+1)}|\Sigma|^{p+k+1}\left|X^{\prime} X\right|^{-p} .
$$

Proof: The information matrix $\mathcal{I}$ follows from the fact that we can write (4) as $-\mathrm{Ed}^{2} \ell=(\mathrm{d} \theta)^{\prime} \mathcal{I}(\mathrm{d} \theta)$. Its inverse follows from Magnus and Neudecker (1988, Theorem 3.13(d), p. 50), and the trace and determinant follow from Lemma A1 in the Appendix.

The inverse $\mathcal{I}^{-1}$ of the information matrix provides the asymptotic variance of the ML estimator in the correctly specified case. Its trace and determinant provide scalar measures of the asymptotic variance, and they play a role, inter alia, in the construction of information criteria.

## 3 Multivariate regression under misspecification

We next assume the same model as in Section 2, except that we do not assume normality. The first two moments of $Y$ are still given by $\mathrm{E}(Y)=X B$ and $\operatorname{var}(\operatorname{vec} Y)=\Sigma \otimes I_{n}$, but the third and fourth moments of $Y$ are not necessarily equal to the moments that would have been implied by normality.

We estimate the unknown parameters by pseudo maximum likelihood (PML), that is, we take the normal log-likelihood function (1) as our starting point. The PML estimators are given by (3). The expectation of the first differential is still zero (first-order regularity), but it is no longer true that $\mathrm{E}(\mathrm{d} \ell)^{2}=-\mathrm{Ed}^{2} \ell$ (second-order regularity). This is because the evaluation of $\mathrm{E}(\mathrm{d} \ell)^{2}$ involves third and fourth moments.

Let us standardize $Y$ by defining $V:=(Y-X B) \Sigma^{-1 / 2}$, so that

$$
\mathrm{E}(V)=0, \quad \operatorname{var}(\operatorname{vec} V)=I_{p n} .
$$

Let us also introduce matrix generalizations of the usual skewness and kurtosis measures by defining

$$
\Gamma_{1}:=\mathrm{E}(\operatorname{vec} V)\left(\operatorname{vec}\left(V^{\prime} V-n I_{p}\right)\right)^{\prime}, \quad \Gamma_{2}:=\mathrm{E}\left(\operatorname{vec} V^{\prime} V\right)\left(\operatorname{vec} V^{\prime} V\right)^{\prime}
$$

In the special case of correct specification, this specializes to

$$
\Gamma_{1}=0, \quad \Gamma_{2}=2 n N_{p}+n^{2}\left(\operatorname{vec} I_{p}\right)\left(\operatorname{vec} I_{p}\right)^{\prime}
$$

where $N_{p}$ denotes the $p^{2} \times p^{2}$ symmetrizer matrix defined in the Appendix. If $n=p=1$, the kurtosis further specializes to $\Gamma_{2}=3$, as expected.

We now evaluate $\mathrm{E}(\mathrm{d} \ell)^{2}$. Squaring Equation (2) gives

$$
(\mathrm{d} \ell)^{2}=\left(\frac{1}{2} \operatorname{tr}\left(\Sigma^{-1 / 2} V^{\prime} V \Sigma^{-1 / 2}-n \Sigma^{-1}\right) \mathrm{d} \Sigma+\operatorname{tr} \Sigma^{-1 / 2} V^{\prime} X \mathrm{~d} B\right)^{2} .
$$

Then, letting $\Delta:=D_{p}^{\prime}\left(\Sigma^{-1 / 2} \otimes \Sigma^{-1 / 2}\right) D_{p}$, we find

$$
\begin{align*}
\mathrm{E}(\mathrm{~d} \ell)^{2}= & \frac{1}{4} \mathrm{E}\left(\operatorname{tr}\left(\Sigma^{-1 / 2} V^{\prime} V \Sigma^{-1 / 2}-n \Sigma^{-1}\right) \mathrm{d} \Sigma\right)^{2}+\mathrm{E}\left(\operatorname{tr} \Sigma^{-1 / 2} V^{\prime} X \mathrm{~d} B\right)^{2} \\
& +\mathrm{E}\left(\operatorname{tr}\left(\Sigma^{-1 / 2} V^{\prime} V \Sigma^{-1 / 2}-n \Sigma^{-1}\right) \mathrm{d} \Sigma\right)\left(\operatorname{tr} \Sigma^{-1 / 2} V^{\prime} X \mathrm{~d} B\right) \\
= & \frac{1}{4}(\mathrm{~d} \operatorname{vec} \Sigma)^{\prime}\left(\Sigma^{-1 / 2} \otimes \Sigma^{-1 / 2}\right) \operatorname{var}\left(\operatorname{vec} V^{\prime} V\right)\left(\Sigma^{-1 / 2} \otimes \Sigma^{-1 / 2}\right) \mathrm{d} \operatorname{vec} \Sigma \\
& +(\mathrm{d} \operatorname{vec} B)^{\prime}\left(\Sigma^{-1 / 2} \otimes X^{\prime}\right) \operatorname{var}(\operatorname{vec} V)\left(\Sigma^{-1 / 2} \otimes X\right) \mathrm{d} \operatorname{vec} B \\
& +(\mathrm{d} \operatorname{vec} \Sigma)^{\prime}\left(\Sigma^{-1 / 2} \otimes \Sigma^{-1 / 2}\right) \Gamma_{1}^{\prime}\left(\Sigma^{-1 / 2} \otimes X\right) \mathrm{d} \operatorname{vec} B \\
= & \frac{1}{4}(\mathrm{~d} \operatorname{vech}(\Sigma))^{\prime} \Delta D_{p}^{+}\left(\Gamma_{2}-n^{2}\left(\operatorname{vec} I_{p}\right)\left(\operatorname{vec} I_{p}\right)^{\prime}\right) D_{p}^{+\prime} \Delta \mathrm{d} \operatorname{vech}(\Sigma) \\
& +(\mathrm{d} \operatorname{vec} B)^{\prime}\left(\Sigma^{-1} \otimes X^{\prime} X\right) \mathrm{d} \operatorname{vec} B \\
& +(\mathrm{d} \operatorname{vech}(\Sigma))^{\prime} \Delta D_{p}^{+} \Gamma_{1}^{\prime}\left(\Sigma^{-1 / 2} \otimes X\right) \mathrm{d} \operatorname{vec} B . \tag{5}
\end{align*}
$$

Thus we obtain

Theorem 2: In the misspecified case, we have

$$
-\mathrm{E}\left(\mathrm{~d}^{2} \ell\right)=(\mathrm{d} \theta)^{\prime} \mathcal{I} \mathrm{d} \theta, \quad \mathrm{E}(\mathrm{~d} \ell)^{2}=(\mathrm{d} \theta)^{\prime} \mathcal{R} \mathrm{d} \theta
$$

where $\mathcal{I}$ is given in Theorem 1,

$$
\mathcal{R}:=\left(\begin{array}{cc}
\Sigma^{-1} \otimes X^{\prime} X & \frac{1}{2}\left(\Sigma^{-1 / 2} \otimes X^{\prime}\right) \Gamma_{1} D_{p}^{+^{\prime}} \Delta \\
\frac{1}{2} \Delta D_{p}^{+} \Gamma_{1}^{\prime}\left(\Sigma^{-1 / 2} \otimes X\right) & \frac{1}{4} \Delta D_{p}^{+} \Gamma_{2}^{*} D_{p}^{+\prime} \Delta^{+}
\end{array}\right),
$$

and $\Gamma_{2}^{*}:=\Gamma_{2}-n^{2}\left(\operatorname{vec} I_{p}\right)\left(\operatorname{vec} I_{p}\right)^{\prime}$.
Proof: The expression $-\mathrm{E}\left(\mathrm{d}^{2} \ell\right)$ is not affected by the misspecification, because it uses the first two moments only. Hence the matrix $\mathcal{I}$ is the same as in Theorem 1. In contrast, Equation (5) implies the expression for $\mathcal{R}$.

The matrix $\mathcal{R}$ is sometimes called the "outer-product form" of the information matrix, because it is based on $\mathrm{E}(\mathrm{d} \ell)^{2}$. The "Hessian form" $\mathcal{I}$ is based on $-\mathrm{E}\left(\mathrm{d}^{2} \ell\right)$. In the correctly specified case where $\Gamma_{1}=0$ and $\Gamma_{2}^{*}=2 n N_{p}$, one verifies that $\mathcal{R}=\mathcal{I}$.

## 4 Asymptotic variance of the PML estimator

We have seen that, in the presence of misspecification, second-order regularity does not hold and that therefore $\mathcal{I}$ and $\mathcal{R}$ are not the same. The asymptotic variance of the PML estimator $\hat{\theta}$ is therefore not given by either $\mathcal{I}^{-1}$ or $\mathcal{R}^{-1}$, but by $\mathcal{V}:=\mathcal{I}^{-1} \mathcal{R} \mathcal{I}^{-1}$. This important result was implied or proved in papers by Huber (1967), Jennrich (1969), Malinvaud (1970), Gallant and Holly (1980), Burguete, Gallant, and Souza (1982), White (1982), and Gouriéroux, Monfort, and Trognon (1984), and more recently by Gouriéroux and Monfort (1995a, p. 237), Gouriéroux and Monfort (1995b, p. 170), Hendry (1995, p. 391), and White (1996).

While the sandwich matrix $\hat{\mathcal{V}}:=\mathcal{V}(\hat{\theta})$ evaluated at the ML estimator $\hat{\theta}$ provides a consistent estimator of the variance of $\hat{\theta}$, it is not the only consistent estimator. An alternative would be to evaluate minus the Hessian matrix $H$ (instead of $\mathcal{I}$ ) and the sample variance of the score contributions $R$ (instead of $\mathcal{R}$ ), and to use these in constructing $V:=H^{-1} R H^{-1}$, as in White (1982). The estimator $\hat{V}:=V(\hat{\theta})$ is also consistent and hence an alternative to $\hat{\mathcal{V}}$. It is difficult to judge, in general, which estimator is to be preferred. In our case, the alternative estimator $\hat{V}$ allows for heteroskedasticity and "hetero-skewness" which is excluded by our model assumptions, and this might be one reason to prefer $\hat{\mathcal{V}}$ over $\hat{V}$. Our main result is

Theorem 3: The sandwich matrix $\mathcal{V}$ is given by

$$
\mathcal{V}=\left(\begin{array}{cc}
\Sigma \otimes\left(X^{\prime} X\right)^{-1} & \frac{1}{n}\left(\Sigma^{1 / 2} \otimes\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1} D_{p} \Delta^{-1} \\
\frac{1}{n} \Delta^{-1} D_{p}^{\prime} \Gamma_{1}^{\prime}\left(\Sigma^{1 / 2} \otimes X\left(X^{\prime} X\right)^{-1}\right) & \frac{1}{n^{2}} \Delta^{-1} D_{p}^{\prime} \Gamma_{2}^{*} D_{p} \Delta^{-1}
\end{array}\right)
$$

The trace and determinant of $\mathcal{V}$ are

$$
\begin{aligned}
\operatorname{tr}(\mathcal{V})= & (\operatorname{tr} \Sigma)\left(\operatorname{tr}\left(X^{\prime} X\right)^{-1}\right) \\
& +\frac{1}{n^{2}} \operatorname{tr} D_{p}^{+}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right) \Gamma_{2}^{*}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right) D_{p}^{+^{\prime}}
\end{aligned}
$$

and

$$
\begin{aligned}
|\mathcal{V}|= & 2^{-p(p-1)} n^{-p(p+1)}|\Sigma|^{p+k+1}\left|X^{\prime} X\right|^{-p} \\
& \times\left|D_{p}^{\prime}\left(\Gamma_{2}^{*}-\Gamma_{1}^{\prime}\left(I_{p} \otimes X\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1}\right) D_{p}\right|
\end{aligned}
$$

and the norm of $\mathcal{V}$, defined as $\|\mathcal{V}\|:=\sqrt{\operatorname{tr}\left(\mathcal{V}^{2}\right)}$, is the square root of

$$
\begin{aligned}
\operatorname{tr}\left(\mathcal{V}^{2}\right)= & \operatorname{tr}\left(\Sigma^{2}\right) \operatorname{tr}\left(\left(X^{\prime} X\right)^{-2}\right)+\frac{1}{n^{4}} \operatorname{tr}\left(\Gamma_{2}^{*} Q\right)^{2} \\
& +\frac{2}{n^{2}} \operatorname{tr}\left[\left(\Sigma \otimes X\left(X^{\prime} X\right)^{-2} X^{\prime}\right)\left(\Gamma_{1} Q \Gamma_{1}^{\prime}\right)\right]
\end{aligned}
$$

where

$$
Q:=\frac{1}{2} N_{p}(\Sigma \otimes \Sigma) N_{p}+\frac{1}{2}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right) \Xi_{p}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right)
$$

and $\Xi_{p}:=\sum_{i=1}^{p}\left(e_{i} e_{i}^{\prime} \otimes e_{i} e_{i}^{\prime}\right)$. The vectors $e_{i}$ are unit vectors, that is, so that $e_{i}$ denotes the $i$-th column of the identity matrix $I_{p}$.

Proof: From Theorems 1 and 2 it follows that the matrix $\mathcal{I}^{-1} \mathcal{R}$ is equal to

$$
\left(\begin{array}{cc}
I_{p k} & \frac{1}{2}\left(\Sigma^{1 / 2} \otimes\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1} D_{p}^{+\prime} \Delta \\
\frac{1}{n} D_{p}^{+}(\Sigma \otimes \Sigma) D_{p}^{+\prime} \Delta D_{p}^{+} \Gamma_{1}^{\prime}\left(\Sigma^{-1 / 2} \otimes X\right) & \frac{1}{2 n} D_{p}^{+}(\Sigma \otimes \Sigma) D_{p}^{+\prime} \Delta D_{p}^{+} \Gamma_{2}^{*} D_{p}^{+\prime} \Delta
\end{array}\right),
$$

so that the expression for $\mathcal{V}$ follows from the properties of $N_{p}$ and $D_{p}$ and the fact that $D_{p}^{+^{\prime}} \Delta D_{p}^{+}(\Sigma \otimes \Sigma) D_{p}^{+^{\prime}}=D_{p} \Delta^{-1}$. Furthermore,

$$
\begin{aligned}
\operatorname{tr}(\mathcal{V})= & \operatorname{tr} \Sigma \otimes\left(X^{\prime} X\right)^{-1}+\frac{1}{n^{2}} \operatorname{tr} \Delta^{-1} D_{p}^{\prime} \Gamma_{2}^{*} D_{p} \Delta^{-1} \\
= & (\operatorname{tr} \Sigma)\left(\operatorname{tr}\left(X^{\prime} X\right)^{-1}\right) \\
& +\frac{1}{n^{2}} \operatorname{tr} D_{p}^{+}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right) \Gamma_{2}^{*}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right) D_{p}^{+^{\prime}}
\end{aligned}
$$

and

$$
\begin{aligned}
|\mathcal{V}|= & \left|\Sigma \otimes\left(X^{\prime} X\right)^{-1}\right| \cdot\left|\frac{1}{n^{2}} \Delta^{-1} D_{p}^{\prime}\left(\Gamma_{2}^{*}-\Gamma_{1}^{\prime}\left(I_{p} \otimes X\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1}\right) D_{p} \Delta^{-1}\right| \\
= & 2^{-p(p-1)} n^{-p(p+1)}|\Sigma|^{p+k+1}\left|X^{\prime} X\right|^{-p} \\
& \times\left|D_{p}^{\prime}\left(\Gamma_{2}^{*}-\Gamma_{1}^{\prime}\left(I_{p} \otimes X\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1}\right) D_{p}\right| .
\end{aligned}
$$

Next we compute $\operatorname{tr}\left(\mathcal{V}^{2}\right)$. Denote the four blocks of $\mathcal{V}$ by $\mathcal{V}_{i j}(i, j=1,2)$. Then,

$$
\operatorname{tr}\left(\mathcal{V}^{2}\right)=\operatorname{tr}\left(\mathcal{V}_{11}^{2}\right)+\operatorname{tr}\left(\mathcal{V}_{22}^{2}\right)+2 \operatorname{tr}\left(\mathcal{V}_{12} \mathcal{V}_{21}\right)
$$

Now,

$$
\operatorname{tr}\left(\mathcal{V}_{11}^{2}\right)=\operatorname{tr}\left(\Sigma \otimes\left(X^{\prime} X\right)^{-1}\right)^{2}=\operatorname{tr}\left(\Sigma^{2}\right) \operatorname{tr}\left(\left(X^{\prime} X\right)^{-2}\right),
$$

and, using Lemma A2 in the Appendix,

$$
\begin{aligned}
\operatorname{tr}\left(\mathcal{V}_{22}^{2}\right) & =\frac{1}{n^{4}} \operatorname{tr}\left(\Delta^{-1} D_{p}^{\prime} \Gamma_{2}^{*} D_{p} \Delta^{-1}\right)^{2} \\
& =\frac{1}{n^{4}} \operatorname{tr}\left[\Gamma_{2}^{*}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right)\left(D_{p} D_{p}^{\prime}\right)^{+}\left(\Sigma^{1 / 2} \otimes \Sigma^{1 / 2}\right)\right]^{2}=\frac{1}{n^{4}} \operatorname{tr}\left(\Gamma_{2}^{*} Q\right)^{2}
\end{aligned}
$$

and

$$
\begin{aligned}
& \operatorname{tr}\left(\mathcal{V}_{12} \mathcal{V}_{21}\right) \\
& \quad=\frac{1}{n^{2}} \operatorname{tr}\left[\left(\Sigma^{1 / 2} \otimes\left(X^{\prime} X\right)^{-1} X^{\prime}\right) \Gamma_{1} D_{p} \Delta^{-2} D_{p}^{\prime} \Gamma_{1}^{\prime}\left(\Sigma^{1 / 2} \otimes X\left(X^{\prime} X\right)^{-1}\right)\right] \\
& \quad=\frac{1}{n^{2}} \operatorname{tr}\left[\left(\Sigma \otimes X\left(X^{\prime} X\right)^{-2} X^{\prime}\right)\left(\Gamma_{1} Q \Gamma_{1}^{\prime}\right)\right]
\end{aligned}
$$

This completes the proof.
The sandwich matrix $\mathcal{V}$ thus provides the asymptotic variance of the PML estimator in the misspecified case. As in Theorem 1, its trace, determinant, and norm provide scalar measures of the asymptotic variance. These measures, together with other scalars such as $\operatorname{tr}\left(\mathcal{I}^{-1} \mathcal{R}\right)$, play a crucial role in the construction of information criteria.

An interesting special case is obtained when the true joint distribution belongs to the linear exponential family, giving rise to the well-known quasigeneralized PML estimators; see Gouriéroux, Monfort, and Trognon (1984, Section 5). We do not, however, investigate this avenue in this paper.

We notice, after a little algebra, that

$$
\begin{align*}
\operatorname{tr}\left(\mathcal{I}^{-1} \mathcal{R}\right) & =\operatorname{tr}\left(I_{p k}\right)+\frac{1}{2 n} \operatorname{tr}\left(D_{p}^{+}(\Sigma \otimes \Sigma) D_{p}^{+\prime} \Delta D_{p}^{+} \Gamma_{2}^{*} D_{p}^{+\prime} \Delta\right) \\
& =p k+\frac{1}{2 n} \operatorname{tr} N_{p} \Gamma_{2}^{*}=p k+\frac{1}{2 n} \operatorname{tr} \Gamma_{2}^{*}, \tag{6}
\end{align*}
$$

which simplifies to

$$
\begin{equation*}
\operatorname{tr}\left(\mathcal{I}^{-1} \mathcal{R}\right)=p k+\frac{1}{2} p(p+1) \tag{7}
\end{equation*}
$$

in the special case of correct specification where $\Gamma_{1}=0$ and $\Gamma_{2}^{*}=2 n N_{p}$.
We also notice that, in the case of correct specification,

$$
\begin{align*}
\operatorname{tr}\left(\mathcal{V}^{2}\right)= & \operatorname{tr}\left(\Sigma^{2}\right) \operatorname{tr}\left(\left(X^{\prime} X\right)^{-2}\right)+\frac{4}{n^{2}} \operatorname{tr}\left(Q^{2}\right) \\
= & \operatorname{tr}\left(\Sigma^{2}\right) \operatorname{tr}\left(\left(X^{\prime} X\right)^{-2}\right)+\frac{1}{2 n^{2}}\left(\operatorname{tr} \Sigma^{2}\right)^{2}+\frac{1}{2 n^{2}} \operatorname{tr}\left(\Sigma^{4}\right) \\
& +\frac{1}{n^{2}} \sum_{i j} \sigma_{i j}^{4}+\frac{2}{n^{2}} \sum_{i}\left(\sum_{j} \sigma_{i j}^{2}\right)^{2} . \tag{8}
\end{align*}
$$

## Appendix: The duplication matrix-some new results

Let $A$ be a square matrix of order $p \times p$. The two vectors vec $A$ and vec $A^{\prime}$ contain the same $p^{2}$ components, but in a different order. Hence there exists a unique permutation matrix that transforms vec $A$ into vec $A^{\prime}$. This $p^{2} \times p^{2}$ matrix is (a special case of) the commutation matrix and is denoted by $K_{p}$; it is implicitly defined by the operation $K_{p} \operatorname{vec} A=\operatorname{vec} A^{\prime}$.

Closely related to the commutation matrix is the $p^{2} \times p^{2}$ symmetrizer matrix $N_{p}$ with the property $N_{p} \operatorname{vec} A=\frac{1}{2} \operatorname{vec}\left(A+A^{\prime}\right)$ for every square $p \times p$ $\operatorname{matrix} A$. It is easy to see that $N_{p}=\frac{1}{2}\left(I_{p^{2}}+K_{p}\right)$.

We now introduce the half-vec operator vech $(\cdot)$. For any $p \times p$ matrix $A$, the vector $\operatorname{vech}(A)$ denotes the $\frac{1}{2} p(p+1) \times 1$ vector that is obtained from vec $A$ by eliminating all supradiagonal elements of $A$. For example, for $p=2$,

$$
\operatorname{vec} A=\left(a_{11}, a_{21}, a_{12}, a_{22}\right)^{\prime} \quad \text { and } \quad \operatorname{vech}(A)=\left(a_{11}, a_{21}, a_{22}\right)^{\prime},
$$

where the supradiagonal element $a_{12}$ has been removed. Thus, for symmetric $A$, $\operatorname{vech}(A)$ only contains the distinct elements of $A$. Now, if $A$ is symmetric, the elements of $\operatorname{vec} A$ are those of $\operatorname{vech}(A)$ with some repetitions. Hence, there exists a unique $p^{2} \times \frac{1}{2} p(p+1)$ matrix $D_{p}$, called the duplication matrix, that transforms, for symmetric $A$, $\operatorname{vech}(A)$ into vec $A$, that is,

$$
D_{p} \operatorname{vech}(A)=\operatorname{vec} A \quad\left(A=A^{\prime}\right)
$$

The matrices $D_{p}$ and $N_{p}$ are connected through $D_{p} D_{p}^{+}=N_{p}$. The duplication matrix was introduced by Magnus and Neudecker (1980). A systematic treatment of $K_{p}, N_{p}$, and $D_{p}$, among others, is given in Magnus (1988).

We now present two new properties, both of which are being used in this note.

Lemma A1: Let $A=\left(a_{i j}\right)$ be a square matrix of order $p \times p$. The determinant and trace of the matrix $D_{p}^{+}(A \otimes A) D_{p}^{+\prime}$ are given by

$$
\left|D_{p}^{+}(A \otimes A) D_{p}^{+\prime}\right|=2^{-\frac{1}{2} p(p-1)}|A|^{p+1}
$$

and

$$
\operatorname{tr}\left(D_{p}^{+}(A \otimes A) D_{p}^{+\prime}\right)=\frac{1}{4} \operatorname{tr}\left(A^{\prime} A\right)+\frac{1}{4}(\operatorname{tr} A)^{2}+\frac{1}{2} \sum_{j=1}^{p} a_{j j}^{2} .
$$

Proof: Since

$$
D_{p}^{+}(A \otimes A) D_{p}^{+\prime}=\left(D_{p}^{\prime} D_{p}\right)^{-1} D_{p}^{\prime}(A \otimes A) D_{p}\left(D_{p}^{\prime} D_{p}\right)^{-1}
$$

we obtain, from Magnus (1988, Theorem 4.11(i)),

$$
\begin{aligned}
\left|D_{p}^{+}(A \otimes A) D_{p}^{+\prime}\right| & =\left|D_{p}^{\prime} D_{p}\right|^{-1}\left|D_{p}^{\prime}(A \otimes A) D_{p}\right|\left|D_{p}^{\prime} D_{p}\right|^{-1} \\
& =2^{-\frac{1}{2} p(p-1)} 2^{\frac{1}{2} p(p-1)}|A|^{p+1} 2^{-\frac{1}{2} p(p-1)}=2^{-\frac{1}{2} p(p-1)}|A|^{p+1} .
\end{aligned}
$$

This proves the first result. To prove the second result, let $\delta_{s t}$ denote the Kronecker delta, and write $u_{i j}=\operatorname{vech}\left(e_{i} e_{j}^{\prime}\right)$, where $e_{i}$ denotes the $i$-th column of the identity matrix $I_{p}$. Then,

$$
\begin{aligned}
\operatorname{tr} & \left(D_{p}^{+}(A \otimes A) D_{p}^{+\prime}\right)=\operatorname{tr}\left(D_{p}^{+}(A \otimes A) D_{p}\right)\left(D_{p}^{\prime} D_{p}\right)^{-1} \\
& =\frac{1}{2} \operatorname{tr}\left(\sum_{i \geq j} \sum_{s \geq t}\left(a_{i t} a_{j s}+a_{i s} a_{j t}-\delta_{s t} a_{i s} a_{j s}\right) u_{i j} u_{s t}^{\prime}\right)\left(I_{\frac{1}{2} p(p+1)}+\sum_{k=1}^{p} u_{k k} u_{k k}^{\prime}\right) \\
& =\frac{1}{2} \sum_{i \geq j}\left(a_{i j} a_{j i}+a_{i i} a_{j j}-\delta_{i j} a_{i i} a_{j j}\right)+\frac{1}{2} \sum_{j=1}^{p} a_{j j}^{2} \\
& =\frac{1}{4} \sum_{i j} a_{i j} a_{j i}+\frac{1}{4} \sum_{i j} a_{i i} a_{j j}+\frac{1}{2} \sum_{j=1}^{p} a_{j j}^{2} \\
& =\frac{1}{4} \operatorname{tr}\left(A^{\prime} A\right)+\frac{1}{4}(\operatorname{tr} A)^{2}+\frac{1}{2} \sum_{j=1}^{p} a_{j j}^{2}
\end{aligned}
$$

where the second equality follows from the proof of Theorem 4.9 and Theorem 4.4(ii) in Magnus (1988).

Lemma A2: Letting $\Xi_{p}:=\sum_{i=1}^{p}\left(e_{i} e_{i}^{\prime} \otimes e_{i} e_{i}^{\prime}\right)$ and $\alpha_{k}:=1 / 2^{k}$, we have

$$
\left[\left(D_{p} D_{p}^{\prime}\right)^{+}\right]^{k}=\alpha_{k} N_{p}+\left(1-\alpha_{k}\right) \Xi_{p} \quad(k=1,2, \ldots)
$$

a weighted average of two idempotent matrices.
Proof: We prove the result first for $k=1$. Let $S_{i j}:=\left(e_{i} e_{j}^{\prime}+e_{j} e_{i}^{\prime}\right) / 2$.

Then, using Theorem 4.6(ii) of Magnus (1988),

$$
\begin{aligned}
& \left(D_{p} D_{p}^{\prime}\right)^{+}=\sum_{i \geq j}\left(\operatorname{vec} S_{i j}\right)\left(\operatorname{vec} S_{i j}\right)^{\prime} \\
& \quad=\frac{1}{2} \sum_{i=1}^{p}\left(\operatorname{vec} S_{i i}\right)\left(\operatorname{vec} S_{i i}\right)^{\prime}+\frac{1}{2} \sum_{i=1}^{p} \sum_{j=1}^{p}\left(\operatorname{vec} S_{i j}\right)\left(\operatorname{vec} S_{i j}\right)^{\prime} \\
& \quad=\frac{1}{2} \sum_{i=1}^{p}\left(\operatorname{vec} e_{i} e_{i}^{\prime}\right)\left(\operatorname{vec} e_{i} e_{i}^{\prime}\right)^{\prime}+\frac{1}{8} \sum_{i, j}\left(\operatorname{vec}\left(e_{i} e_{j}^{\prime}+e_{j} e_{i}^{\prime}\right)\right)\left(\operatorname{vec}\left(e_{i} e_{j}^{\prime}+e_{j} e_{i}^{\prime}\right)\right)^{\prime} \\
& \quad=\frac{1}{2} \sum_{i=1}^{p}\left(e_{i} e_{i}^{\prime} \otimes e_{i} e_{i}^{\prime}\right)+\frac{1}{4} \sum_{i, j}\left(e_{i} e_{i}^{\prime} \otimes e_{j} e_{j}+e_{i} e_{j}^{\prime} \otimes e_{j} e_{i}^{\prime}\right) \\
& \quad=\frac{1}{2} \Xi_{p}+\frac{1}{4}\left(I_{p^{2}}+K_{p}\right)=\frac{1}{2}\left(\Xi_{p}+N_{p}\right)
\end{aligned}
$$

since $K_{p}=\sum_{i=1}^{p} \sum_{j=1}^{p}\left(e_{i} e_{j}^{\prime} \otimes e_{j} e_{i}^{\prime}\right)$ by Theorem 3.2 in Magnus (1988). This proves the result for $k=1$. The general result follows by induction, using the facts that both $N_{p}$ and $\Xi_{p}$ are idempotent, and that $N_{p} \Xi_{p}=\Xi_{p} N_{p}=\Xi_{p}$.

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