CIRJE-F-723

# Minimax Estimation of Linear Combinations of Restricted Location Parameters 

Tatsuya Kubokawa<br>University of Tokyo

March 2010

CIRJE Discussion Papers can be downloaded without charge from:
http://www.e.u-tokyo.ac.jp/cirje/research/03research02dp.html

Discussion Papers are a series of manuscripts in their draft form. They are not intended for circulation or distribution except as indicated by the author. For that reason Discussion Papers may not be reproduced or distributed without the written consent of the author.

# Minimax Estimation of Linear Combinations of Restricted Location Parameters 

Tatsuya Kubokawa *<br>University of Tokyo

March 10, 2010

The estimation of a linear combination of several restricted location parameters is addressed from a decision-theoretic point of view. A bench-mark estimator of the linear combination is an unbiased estimator, which is minimax, but inadmissible relative to the mean squared error. An interesting issue is what is a prior distribution which results in the generalized Bayes and minimax estimator. Although it seems plausible that the generalized Bayes estimator against the uniform prior over the restricted space should be minimax, it is shown to be not minimax when the number of the location parameters, $k$, is more than or equal to three, while it is minimax for $k=1$. In the case of $k=2$, a necessary and sufficient condition for the minimaxity is given, namely, the minimaxity depends on signs of coefficients of the linear combination. When the underlying distributions are normal, we can obtain a prior distribution which results in the generalized Bayes estimator satisfying minimaxity and admissibility. Finally, it is demonstrated that the estimation of ratio of normal variances converges to the estimation of difference of the normal positive means, which gives a motivation of the issue studied here.

Key words and phrases: Admissibility, decision theory, generalized Bayes estimator, minimaxity, restricted parameters, Stein estimation.

## 1 Introduction

The point estimation of restricted parameters has been studied from a decision-theoretic point of view since Katz (1961), who showed that the generalized Bayes estimator of a restricted parameter is minimax and admissible in a one-parameter exponential family. Farrell (1964) established the minimaxity and admissibility in the general location family. This classical problem was revisited by Marchand and Strawderman (2004, 2005) and Kubokawa (1990, 2004). Hartigan (2004) considered the simultaneous estimation of a mean vector restricted to a convex cone in a $k$-variate normal distribution and used the Gauss divergence theorem to show that the generalized Bayes estimator against the

[^0]uniform prior dominates the unbiased estimator. Tsukuma and Kubokawa (2008) established the minimaxity of the generalized Bayes estimator and proved that it is admissible for $k=1,2$ and inadmissible for $k \geq 3$. This is an extension of the Stein result to the restricted case.

In this paper, we consider the estimation of the linear combination of the several location parameters where each location parameter is restricted to the space of positive real number. More specifically, we consider the following simple model: Let $X_{1}, \ldots, X_{k}$ be mutually independent random variables where $X_{i}$ has probability density function $f_{i}\left(x_{i}-\mu_{i}\right)$ with location parameter $\mu_{i}$ restricted to $\mu_{i}>0$ for $i=1, \ldots, k$. It is assumed that $E\left[X_{i}^{2}\right]<\infty$ for $i=1, \ldots, k$. To express the model in matrix notations, let $\boldsymbol{X}=$ $\left(X_{1}, \ldots, X_{k}\right)^{t}, \boldsymbol{x}=\left(x_{1}, \ldots, x_{k}\right)^{t}$ and $\boldsymbol{\mu}=\left(\mu_{1}, \ldots, \mu_{k}\right)^{t}$ where $\boldsymbol{X}^{t}$ denotes the transpose of $\boldsymbol{X}$. Then, the joint density of $\boldsymbol{X}$ is denoted by

$$
\begin{equation*}
f(\boldsymbol{x}-\boldsymbol{\mu})=\prod_{i=1}^{k} f_{i}\left(x_{i}-\mu_{i}\right) \tag{1.1}
\end{equation*}
$$

and $\boldsymbol{\mu}$ is restricted on the space

$$
D=\left\{\boldsymbol{\mu} \mid \mu_{i}>0, i=1, \ldots, k\right\}
$$

For real constants $a_{i}$ 's and $\boldsymbol{a}=\left(a_{1}, \ldots, a_{k}\right)^{t}$, consider a linear combination of $\boldsymbol{\mu}$ given by

$$
\theta=\sum_{i=1}^{k} a_{i} \mu_{i}=\boldsymbol{a}^{t} \boldsymbol{\mu}
$$

and we want to study the estimation of $\theta$ in a decision-theoretic framework, where an estimator $\hat{\theta}$ of $\theta$ is evaluated in terms of the mean squared error $R(\boldsymbol{\mu}, \hat{\theta})=E\left[(\hat{\theta}-\theta)^{2}\right]$.

An unbiased estimator of $\theta$ is given by

$$
\begin{equation*}
\hat{\theta}^{U}=\sum_{i=1}^{k} a_{i} \widehat{\mu}_{i}^{U} \tag{1.2}
\end{equation*}
$$

where $\widehat{\mu}_{i}^{U}$ is the unbiased estimator of $\mu_{i}$ given by

$$
\widehat{\mu}_{i}^{U}=X_{i}-c_{i}, \quad \text { for } \quad c_{i}=E\left[X_{i}-\mu_{i}\right]
$$

As shown in Section 2, $\hat{\theta}^{U}$ is minimax, but inadmissible because of the restriction of the parameter $\boldsymbol{\mu}$ on $D$. Thus, it is of great interest to obtain the admissible and minimax estimator of $\theta$. To this end, it is plausible to consider the uniform prior

$$
\begin{equation*}
\pi(\boldsymbol{\mu}) \mathrm{d} \boldsymbol{\mu}=\mathrm{d} \boldsymbol{\mu} I(\boldsymbol{\mu} \in D) \tag{1.3}
\end{equation*}
$$

where $\mathrm{d} \boldsymbol{\mu}=\prod_{i=1}^{k} \mathrm{~d} \mu_{i}$ and $I(\boldsymbol{\mu} \in D)$ is the indicator function such that $I(\boldsymbol{\mu} \in D)=1$ if $\boldsymbol{\mu} \in D$, otherwise $I(\boldsymbol{\mu} \in D)=0$. The resulting generalized Bayes estimator of $\theta$ is

$$
\begin{align*}
\hat{\theta}^{G B} & =\int_{D} \boldsymbol{a}^{t} \boldsymbol{\mu} f(\boldsymbol{X}-\boldsymbol{\mu}) \mathrm{d} \boldsymbol{\mu} / \int_{D} f(\boldsymbol{X}-\boldsymbol{\mu}) \mathrm{d} \boldsymbol{\mu} \\
& =\sum_{i=1}^{k} a_{i} \int_{0}^{\infty} \mu_{i} f_{i}\left(X_{i}-\mu_{i}\right) \mathrm{d} \mu_{i} / \int_{0}^{\infty} f_{i}\left(X_{i}-\mu_{i}\right) \mathrm{d} \mu_{i}, \tag{1.4}
\end{align*}
$$

and our first concern is whether $\hat{\theta}^{G B}$ is minimax or not. We investigate this problem in Section 3 and show that $\hat{\theta}^{G B}$ is not minimax for $k \geq 3$, but minimax for $k=1$. The minimaxity in the case of $k=2$ depends on the signs of the coefficients $a_{1}$ and $a_{2}$, and a necessary and sufficient condition for the minimaxity of $\hat{\theta}^{G B}$ is that $a_{1} a_{2} \leq 0$. This means that, for example, the generalized Bayes estimator $\hat{\theta}^{G B}$ is not minimax in the estimation of the sum $\mu_{1}+\mu_{2}$, but minimax in the estimation of the difference $\mu_{1}-\mu_{2}$.

Concerning the minimaxity of the generalized Bayes estimator against the uniform prior, it is interesting to note that we have different stories between the simultaneous estimation of $\boldsymbol{\mu}$ and the estimation of the linear combination $\boldsymbol{a}^{t} \boldsymbol{\mu}$, namely, $\widehat{\boldsymbol{\mu}}^{G B}=$ $\int_{D} \boldsymbol{\mu} f(\boldsymbol{X}-\boldsymbol{\mu}) \mathrm{d} \boldsymbol{\mu} / \int_{D} f(\boldsymbol{X}-\boldsymbol{\mu}) \mathrm{d} \boldsymbol{\mu}$ is always minimax in the simultaneous estimation of $\boldsymbol{\mu}$ under a quadratic loss, while $\hat{\theta}^{G B}$ is not necessarily minimax and it depends on the dimension of $\boldsymbol{\mu}$.

In Section 4, we focus on normal distributions, and suggests a specific prior distribution such that the resulting generalized Bayes estimator is minimax and admissible. In Section 5, we use the arguments as in Rukhin (1992) to show that the estimation of ratio of normal variances asymptotically converges to the estimation of difference of positive normal means, which gives a motivation of the estimation problem studied here.

## 2 Minimaxity and Inadmissibility of the Unbiased Estimator

In this section, we show that the unbiased estimator $\hat{\theta}^{U}$ given in (1.2) is minimax, but inadmissible under the assumption that $E\left[X_{i}^{2}\right]<\infty$ for $i=1, \ldots, k$. The minimaxity of $\hat{\theta}^{U}$ can be verified by using similar arguments as in Girshick and Savage (1951).

Proposition 2.1 (minimaxity of the unbiased estimator) The unbiased estimator $\hat{\theta}^{U}$ of $\theta=\sum_{i-1}^{k} a_{i} \mu_{i}$ is minimax in the estimation of the restricted parameters on $D$, and the risk function $R_{0}=R\left(\boldsymbol{\mu}, \hat{\theta}^{U}\right)$ is a constant.

Proof. Let $D_{m}=\left\{\boldsymbol{\mu} \mid 0<\mu_{i}<m, i=1, \ldots, k\right\}$ for $m=1,2, \ldots$, and consider the sequence of prior distributions given by

$$
\pi_{m}(\boldsymbol{\mu})=\left\{\begin{array}{cl}
m^{-k} & \text { if } \boldsymbol{\mu} \in D_{m} \\
0 & \text { otherwise }
\end{array}\right.
$$

which yields the Bayes estimators

$$
\hat{\theta}_{m}^{\pi}=\hat{\theta}_{m}^{\pi}(\boldsymbol{X})=\int_{D_{m}} \boldsymbol{a}^{t} \boldsymbol{u} f(\boldsymbol{X}-\boldsymbol{u}) \mathrm{d} \boldsymbol{u} \int_{D_{m}} f(\boldsymbol{X}-\boldsymbol{u}) \mathrm{d} \boldsymbol{u}
$$

with the Bayes risk function

$$
\begin{equation*}
r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right)=\frac{1}{m^{k}} \int_{D_{m}} \int\left\{\hat{\theta}_{m}^{\pi}(\boldsymbol{x})-\boldsymbol{a}^{t} \boldsymbol{\mu}\right\}^{2} f(\boldsymbol{x}-\boldsymbol{\mu}) \mathrm{d} \boldsymbol{x} \mathrm{~d} \boldsymbol{\mu} \tag{2.1}
\end{equation*}
$$

Since $r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right) \leq r_{m}\left(\pi_{m}, \hat{\theta}^{U}\right)=R_{0}$, it is sufficient to show that $\liminf _{m \rightarrow \infty} r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right) \geq$ $R_{0}$. Making the transformations $\boldsymbol{z}=\boldsymbol{x}-\boldsymbol{\mu}$ and $\boldsymbol{t}=\boldsymbol{u}-\boldsymbol{\mu}$ with $\mathrm{d} \boldsymbol{z}=\mathrm{d} \boldsymbol{x}$ and $\mathrm{d} \boldsymbol{t}=\mathrm{d} \boldsymbol{u}$ gives that

$$
\begin{align*}
\hat{\theta}_{m}^{\pi}(\boldsymbol{x})-\boldsymbol{a}^{t} \boldsymbol{\mu} & =\hat{\theta}_{m}^{\pi}(\boldsymbol{z}+\boldsymbol{\mu})-\boldsymbol{a}^{t} \boldsymbol{\mu} \\
& =\int_{D_{m}} \boldsymbol{a}^{t}(\boldsymbol{u}-\boldsymbol{\mu}) f(\boldsymbol{z}+\boldsymbol{\mu}-\boldsymbol{u}) \mathrm{d} \boldsymbol{u} \int_{D_{m}} f(\boldsymbol{z}+\boldsymbol{\mu}-\boldsymbol{u}) \mathrm{d} \boldsymbol{u} \\
& =\int_{\boldsymbol{t}+\boldsymbol{\mu} \in D_{m}} \boldsymbol{a}^{t} \boldsymbol{t} f(\boldsymbol{z}-\boldsymbol{t}) \mathrm{d} \boldsymbol{t} \int_{\boldsymbol{t}+\boldsymbol{\mu} \in D_{m}} f(\boldsymbol{z}-\boldsymbol{t}) \mathrm{d} \boldsymbol{t} \tag{2.2}
\end{align*}
$$

Making the transformation $\xi_{i}=(2 / m)\left(\mu_{i}-m / 2\right)$ with $\mathrm{d} \boldsymbol{\xi}=(2 / m)^{k} \mathrm{~d} \boldsymbol{\mu}$ for $\boldsymbol{\xi}=\left(\xi_{1}, \ldots, \xi_{k}\right)^{t}$, we can rewrites the condition $0<\mu_{i}<m$ as $\left|\xi_{i}\right|<1$. Also the condition that $0<t_{i}+\mu_{i}<$ $m$ for $\boldsymbol{t}=\left(t_{1}, \ldots, t_{k}\right)^{t}$ is expressed by the inequality $-(m / 2)\left(\xi_{i}+1\right)<t_{i}<(m / 2)\left(1-\xi_{i}\right)$. Let $D_{m}^{*}=\left\{\boldsymbol{t} \mid-(m / 2)\left(\xi_{i}+1\right)<t_{i}<(m / 2)\left(1-\xi_{i}\right)\right\}$. Then the transformations are used in (2.2) and (2.1) to obtain that

$$
\begin{equation*}
\hat{\theta}_{m}^{\pi}(\boldsymbol{x})-\boldsymbol{a}^{t} \boldsymbol{\mu}=\int_{D_{m}^{*}} \boldsymbol{a}^{t} \boldsymbol{t} f(\boldsymbol{z}-\boldsymbol{t}) \mathrm{d} \boldsymbol{t} \int_{D_{m}^{*}} f(\boldsymbol{z}-\boldsymbol{t}) \mathrm{d} \boldsymbol{t} \equiv \hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi}) \tag{2.3}
\end{equation*}
$$

and

$$
r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right)=\frac{1}{2^{k}} \int_{\left|\xi_{i}\right|<1, i=1, \ldots, k} \int\left\{\hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})\right\}^{2} f(\boldsymbol{z}) \mathrm{d} \boldsymbol{z} \mathrm{~d} \boldsymbol{\xi}
$$

For a small $\varepsilon>0$, it is observed that

$$
r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right) \geq \frac{1}{2^{k}} \int_{\left|\xi_{i}\right|<1-\varepsilon, i=1, \ldots, k} \int\left\{\hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})\right\}^{2} f(\boldsymbol{z}) \mathrm{d} \boldsymbol{z} \mathrm{~d} \boldsymbol{\xi}
$$

The range of $\boldsymbol{t}$ in the integrals in $\hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})$ given by (2.3) is $D_{m}^{*}=\left\{\boldsymbol{t} \mid-(m / 2)\left(\xi_{i}+1\right)<\right.$ $\left.t_{i}<(m / 2)\left(1-\xi_{i}\right)\right\}$. Since $\left|\xi_{i}\right|<1-\varepsilon$, it is noted that $1-\xi_{i}>1-(1-\varepsilon)=\varepsilon>0$ and $1+\xi_{i}>1+(-1+\varepsilon)=\varepsilon>0$, which imply that the end points $(m / 2)\left(1-\xi_{i}\right)$ and $-(m / 2)\left(1+\xi_{i}\right)$ tend to infinity and minus infinity as $m \rightarrow \infty$ and then $\hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})$ converges $\hat{\theta}^{U}(\boldsymbol{z})$. Using the Fatou lemma, we obtain that

$$
\begin{aligned}
\liminf _{m \rightarrow \infty} r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right) & \geq \liminf _{m \rightarrow \infty} \frac{1}{2^{k}} \int_{\left|\xi_{i}\right|<1-\varepsilon, i=1, \ldots, k} \int\left\{\hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})\right\}^{2} f(\boldsymbol{z}) \mathrm{d} \boldsymbol{z} \mathrm{~d} \boldsymbol{\xi} \\
& \geq \frac{1}{2^{k}} \int_{\left|\xi_{i}\right|<1-\varepsilon, i=1, \ldots, k} \int\left\{\liminf _{m \rightarrow \infty} \hat{\theta}_{m}^{*}(\boldsymbol{z} \mid \boldsymbol{\xi})\right\}^{2} f(\boldsymbol{z}) \mathrm{d} \boldsymbol{z} \mathrm{~d} \boldsymbol{\xi} \\
& =\frac{1}{2^{k}} \int_{\left|\xi_{i}\right|<1-\varepsilon, i=1, \ldots, k} \mathrm{~d} \boldsymbol{\xi} \int\left\{\hat{\theta}^{U}(\boldsymbol{z})\right\}^{2} f(\boldsymbol{z}) \mathrm{d} \boldsymbol{z} \\
& =(1-\varepsilon)^{k} R\left(\mu, \hat{\theta}^{U}\right)=(1-\varepsilon)^{k} R_{0}
\end{aligned}
$$

From the arbitrariness of $\varepsilon>0$, it follows that $\liminf _{m \rightarrow \infty} r_{m}\left(\pi_{m}, \hat{\theta}_{m}^{\pi}\right) \geq R_{0}$, completing the proof of Proposition 2.1.

Proposition 2.1 is an extension of the results of Marchand and Strawderman (2005) and Kubokawa (2004) who treated the case of $k=1$.

Since the unbiased estimator $\widehat{\mu}_{i}^{U}=X_{i}-c_{i}$ of positve parameter $\mu_{i}$ takes a negative value with a positive probability for $i=1, \ldots, k$, it is plausible that $\hat{\theta}^{U}=\sum_{i=1}^{k} a_{i} \widehat{\mu}_{i}^{U}$ can be improved on by a truncated procedure. Let $\Lambda_{+}$and $\Lambda_{-}$be subsets of $\{1, \ldots, k\}$ such that

$$
\begin{equation*}
a_{i}>0 \quad \text { if } \quad i \in \Lambda_{+}, \quad \text { and } \quad a_{j}<0 \quad \text { if } \quad j \in \Lambda_{-} . \tag{2.4}
\end{equation*}
$$

Then $\theta$ and $\hat{\theta}^{U}$ are decomposed as

$$
\begin{gather*}
\theta=\theta_{+}-\theta_{-} \quad \text { for } \quad \theta_{+}=\sum_{i \in \Lambda_{+}} a_{i} \mu_{i} \quad \text { and } \quad \theta_{-}=-\sum_{i \in \Lambda_{-}} a_{i} \mu_{i}, \\
\hat{\theta}^{U}=\hat{\theta}_{+}^{U}-\hat{\theta}_{-}^{U} \quad \text { for } \quad \hat{\theta}_{+}^{U}=\sum_{i \in \Lambda_{+}} a_{i} \widehat{\mu}_{i}^{U} \quad \text { and } \quad \hat{\theta}_{-}^{U}=-\sum_{i \in \Lambda_{-}} a_{i} \widehat{\mu}_{i}^{U} . \tag{2.5}
\end{gather*}
$$

Since $\theta_{+}$and $\theta_{-}$are positive, it is reasonable to truncate $\hat{\theta}_{+}^{U}$ and $\hat{\theta}_{-}^{U}$ at zero, namely, $\hat{\theta}_{+}^{T R}=\max \left\{\hat{\theta}_{+}^{U}, 0\right\}$ and $\hat{\theta}_{-}^{T R}=\max \left\{\hat{\theta}_{-}^{U}, 0\right\}$, which results in the truncated estimator

$$
\hat{\theta}^{T R}=\hat{\theta}_{+}^{T R}-\hat{\theta}_{-}^{T R} .
$$

Proposition 2.2 (inadmissibility of the unbiased estimator) The truncated estimator $\hat{\theta}^{T R}$ dominates the unbiased estimator $\hat{\theta}^{U}$, namely $\hat{\theta}^{T R}$ is minimax.

Proof. Noting that $\hat{\theta}_{+}^{U}$ and $\hat{\theta}_{-}^{U}$ are mutually independent, we can write the risk difference $\Delta_{k}=E\left[\left(\hat{\theta}^{U}-\theta\right)^{2}\right]-E\left[\left(\hat{\theta}^{T R}-\theta\right)^{2}\right]$ as

$$
\begin{aligned}
\Delta_{k}= & E\left[\left(\hat{\theta}_{+}^{U}-\theta_{+}\right)^{2}-\left(\hat{\theta}_{+}^{T R}-\theta_{+}\right)^{2}\right]+E\left[\left(\hat{\theta}_{-}^{U}-\theta_{-}\right)^{2}-\left(\hat{\theta}_{-}^{T R}-\theta_{-}\right)^{2}\right] \\
& +2 E\left[\hat{\theta}_{+}^{T R}-\theta_{+}\right] E\left[\hat{\theta}_{-}^{T R}-\theta_{-}\right] .
\end{aligned}
$$

It can be seen that $\left(\hat{\theta}_{+}^{U}-\theta_{+}\right)^{2}-\left(\hat{\theta}_{+}^{T R}-\theta_{+}\right)^{2}=\hat{\theta}_{+}^{U}\left(\hat{\theta}_{+}^{U}-2 \theta_{+}\right) I\left(\hat{\theta}_{+}^{U}<0\right)>0$ where $I(A)$ is the indicator function such that $I(A)=1$ if $A$ is true, otherwise $I(A)=0$. Also, $E\left[\hat{\theta}_{+}^{T R}-\theta_{+}\right]=E\left[\max \left\{\hat{\theta}_{+}^{U}, 0\right\}-\theta_{+}\right]=E\left[\hat{\theta}_{+}^{U}-\theta_{+}+\max \left\{0,-\hat{\theta}_{+}^{U}\right\}\right]=E\left[\max \left\{0,-\hat{\theta}_{+}^{U}\right\}\right] \geq 0$. These observations show that $\Delta_{k}>0$ for any $\boldsymbol{\mu} \in D$.

## 3 Is the Uniform Prior Bayes Estimator Minimax ?

We now investigate whether the generalized Bayes estimator $\hat{\theta}^{G B}$ against the uniform prior over $D$ is minimax or not. As shown below, the minimaxity depends on the dimension $k$ of the location vector $\boldsymbol{\mu}$.

### 3.1 Minimaxity in the case of $k=1$

Let $X$ be a random variable whose density function is given by $f(x-\mu)$ where $\mu$ is a location parameter restricted on the space $\{\mu \in \boldsymbol{R} \mid \mu>0\}$. The unbiased estimator of $\mu$
is $\widehat{\mu}^{U}=X-c_{0}$ for $c_{0}=E[X-\mu]=\int u f(u) \mathrm{d} u$, which is minimax. We first consider a class of estimators of the form

$$
\widehat{\mu}(\phi)=X-\phi(X)
$$

for an absolutely continuous function $\phi(\cdot)$, and derive sufficient conditions on $\phi(\cdot)$ for the minimaxity. From the arguments as in Kubokawa (1994a, 1999, 2004), we can see that the risk difference of two estimators $\widehat{\mu}^{U}$ and $\widehat{\mu}(\phi)$ can be expressed based on an integral.

Lemma 3.1 Assume that $\phi(\cdot)$ is an absolutely continuous function such that $\lim _{w \rightarrow \infty} \phi(w)=$ $c_{0}$. Then, the difference of the risk functions of $\widehat{\mu}^{U}$ and $\widehat{\mu}(\phi)$ is written as

$$
\begin{align*}
\Delta & \equiv R\left(\mu, \widehat{\mu}^{U}\right)-R(\mu, \widehat{\mu}(\phi)) \\
& =-2 \int\left\{\int_{-\infty}^{w} u f(u) \mathrm{d} u-\phi(w+\mu) \int_{-\infty}^{w} f(u) \mathrm{d} u\right\} \phi^{\prime}(w+\mu) \mathrm{d} w . \tag{3.1}
\end{align*}
$$

Proof. Since $\lim _{w \rightarrow \infty} \phi(w)=c_{0}$, it can be seen that

$$
\Delta=E\left[\left[(X-\phi(X+t)-\mu)^{2}\right]_{t=0}^{\infty}\right]=E\left[\int_{0}^{\infty} \frac{\mathrm{d}}{\mathrm{~d} t}(X-\phi(X+t)-\mu)^{2} \mathrm{~d} t\right]
$$

which is rewritten as

$$
\Delta=-2 \iint_{0}^{\infty}\{x-\phi(x+t)-\mu\} \phi^{\prime}(x+t) \mathrm{d} t f(x-\mu) \mathrm{d} x .
$$

Making the transformations $w=x+t-\mu$ and $u=w-t$ with $\mathrm{d} w=\mathrm{d} x$ and $\mathrm{d} u=-\mathrm{d} t$ in turn gives

$$
\begin{aligned}
\Delta & =-2 \iint_{0}^{\infty}\{w-t-\phi(w+\mu)\} \phi^{\prime}(w+\mu) f(w-t) \mathrm{d} t \mathrm{~d} w \\
& =-2 \iint_{-\infty}^{w}\{u-\phi(w+\mu)\} \phi^{\prime}(w+\mu) f(u) \mathrm{d} u \mathrm{~d} w,
\end{aligned}
$$

which yields (3.1).
Lemma 3.1 provides a class of estimators improving on $\widehat{\mu}^{U}$.
Proposition 3.1 Assume that $\phi(\cdot)$ is an absolutely continuous function which satisfies that $(a) \phi(w)$ is nondecreasing in $w$ and $\lim _{w \rightarrow \infty} \phi(w)=c_{0}$, and $(b) \phi(w) \geq \phi^{G B}(w)$, where

$$
\phi^{G B}(w)=\int_{-\infty}^{w} u f(u) \mathrm{d} u / \int_{-\infty}^{w} f(u) \mathrm{d} u .
$$

Then, the estimator $\widehat{\mu}(\phi)$ dominates $\widehat{\mu}^{U}$, namely $\widehat{\mu}(\phi)$ is minimax.
It is easy to see that the function $\phi^{G B}(w)$ is nondecreasing and $\lim _{w \rightarrow \infty} \phi^{G B}(w)=c_{0}$. Since $\phi^{G B}(w) \leq w$, it is also seen that $\phi^{G B}(w) \leq \phi^{T R}(w)=\min \left\{w, c_{0}\right\}$. Thus, $\phi^{G B}(w)$ and $\phi^{T R}(w)$ satisfy the conditions in Proposition 3.1, and we get the improved estimators

$$
\begin{aligned}
& \widehat{\mu}^{G B}=X-\phi^{G B}(X)=\int_{0}^{\infty} \mu f(X-\mu) \mathrm{d} \mu / \int_{0}^{\infty} f(X-\mu) \mathrm{d} \mu, \\
& \widehat{\mu}^{T R}=X-\phi^{T R}(X)=\max \{X, 0\} .
\end{aligned}
$$

It is noted that $\widehat{\mu}^{G B}$ is the generalized Bayes estimator of $\mu$ against the uniform prior $\mathrm{d} \mu$ over the space of $\mu>0$, and that $\widehat{\mu}^{T R}$ is the maximum likelihood estimator of $\mu$.

It can be easily seen that $\lim _{\mu \rightarrow \infty} R\left(\mu, \widehat{\mu}^{G B}\right)=R_{0}=R\left(\mu, \widehat{\mu}^{U}\right)$. Also from Lemma 3.1, we get the following risk property for the generalized Bayes estimator $\widehat{\mu}^{G B}$.

Proposition 3.2 Both estimators $\widehat{\mu}^{G B}$ and $\widehat{\mu}^{U}$ have the same risk at $\mu=0$, namely, $R_{0}=R\left(0, \widehat{\mu}^{U}\right)=R\left(0, \widehat{\mu}^{G B}\right)$. Also, $R\left(\mu, \widehat{\mu}^{G B}\right)$ converges to $R_{0}$ as $\mu \rightarrow \infty$.

### 3.2 Minimaxity and non-minimaxity in the case of $k=2$

Let $X_{1}$ and $X_{2}$ be two mutually independent random variables whose densities are $f_{1}\left(x_{1}-\right.$ $\left.\mu_{1}\right)$ and $f_{2}\left(x_{2}-\mu_{2}\right)$, respectively, where $\mu_{1}$ and $\mu_{2}$ are unknown location parameters restricted to $\mu_{1}>0$ and $\mu_{2}>0$. Let us consider the problem of estimating the linear combination of $\mu_{1}$ and $\mu_{2}$, namely,

$$
\theta=\theta_{a_{1}, a_{2}}=a_{1} \mu_{1}+a_{2} \mu_{2}
$$

where $a_{1}$ and $a_{2}$ are real and known constants. From the results in the previous subsection, it can be guessed that the generalized Bayes estimator $\hat{\theta}^{G B}$ of $\theta$ against the uniform prior $\mathrm{d} \mu_{1} \mathrm{~d} \mu_{2}$ over the space of $\mu_{1}>0$ and $\mu_{2}>0$ improves on the unbiased estimator $\hat{\theta}^{U}=a_{1} \widehat{\mu}_{i}^{U}+a_{2} \widehat{\mu}_{2}^{U}$ in terms of the mean squares error $R\left(\mu_{1}, \mu_{2}, \hat{\theta}^{U}\right)=E\left[\left(\hat{\theta}^{U}-\theta\right)^{2}\right]$, where $\widehat{\mu}_{i}^{U}=X_{i}-c_{i}$ and $c_{i}=E\left[X_{i}-\mu_{i}\right]$ for $i=1,2$. However, this conjecture is not true. As shown below, the condition for the minimaxity of $\hat{\theta}^{G B}$ depends on signs of $a_{1}$ and $a_{2}$.

In general, let us consider a class of estimators of the form $\hat{\theta}\left(\phi_{1}, \phi_{2}\right)=a_{1} \widehat{\mu}_{1}\left(\phi_{1}\right)+$ $a_{2} \widehat{\mu}_{2}\left(\phi_{2}\right)$, where $\widehat{\mu}_{i}\left(\phi_{i}\right)=X_{i}-\phi_{i}\left(X_{i}\right)$ for $i=1,2$ and $\phi_{i}(\cdot)$ is an absolutely continuous function.

Lemma 3.2 The risk difference of the estimators $\hat{\theta}^{U}$ and $\hat{\theta}\left(\phi_{1}, \phi_{2}\right)$ is written as

$$
\begin{aligned}
& R\left(\mu_{1}, \mu_{2}, \hat{\theta}^{U}\right)-R\left(\mu_{1}, \mu_{2}, \hat{\theta}\left(\phi_{1}, \phi_{2}\right)\right) \\
& \quad=a_{1}^{2}\left\{R\left(\mu_{1}, \widehat{\mu}_{1}^{U}\right)-R\left(\mu_{1}, \widehat{\mu}_{1}\left(\phi_{1}\right)\right)\right\}+a_{2}^{2}\left\{R\left(\mu_{2}, \widehat{\mu}_{2}^{U}\right)-R\left(\mu_{2}, \widehat{\mu}_{2}\left(\phi_{2}\right)\right)\right\} \\
& \quad-2 a_{1} a_{2} E\left[\widehat{\mu}_{1}\left(\phi_{1}\right)-\mu_{1}\right] E\left[\widehat{\mu}_{2}\left(\phi_{2}\right)-\mu_{2}\right] .
\end{aligned}
$$

It is noted that $E\left[\widehat{\mu}_{i}\left(\phi_{i}\right)-\mu_{i}\right]=E\left[X_{i}-\mu_{i}-\phi_{i}\left(X_{i}\right)\right]=c_{i}-E\left[\phi_{i}\left(X_{i}\right)\right]$. If $\phi_{i}(w)$ is a nondecreasing function with $\lim _{w \rightarrow \infty} \phi_{i}(w)=c_{i}$, then it can be seen that $E\left[\widehat{\mu}_{i}\left(\phi_{i}\right)-\mu_{i}\right] \geq$ 0 . Hence from Proposition 3.1 and Lemma 3.2, we get the following proposition.

Proposition 3.3 For $i=1,2$, assume that $\phi_{i}(\cdot)$ is an absolutely continuous function which satisfies that $(a) \phi_{i}(w)$ is nondecreasing in $w$ and $\lim _{w \rightarrow \infty} \phi_{i}(w)=c_{0}$, and (b) $\phi_{i}(w) \geq \phi_{i}^{G B}(w)$, where

$$
\phi_{i}^{G B}(w)=\int_{-\infty}^{w} u f_{i}(u) \mathrm{d} u / \int_{-\infty}^{w} f_{i}(u) \mathrm{d} u
$$

If $a_{1} a_{2} \leq 0$, then the estimator $\hat{\theta}\left(\phi_{1}, \phi_{2}\right)$ is minimax.

It is interesting to note that the condition $a_{1} a_{2} \leq 0$ is necessary and sufficient for the minimaxity of the generalized Bayes estimator against the uniform prior over the restricted space, which is expressed as $\hat{\theta}^{G B}=a_{1} \widehat{\mu}_{1}^{G B}+a_{2} \widehat{\mu}_{2}^{G B}$ for $\widehat{\mu}_{i}^{G B}=X_{i}-\phi_{i}^{G B}\left(X_{i}\right)$.

Proposition 3.4 The generalized Bayes estimator $\hat{\theta}^{G B}=a_{1} \widehat{\mu}_{1}^{G B}+a_{2} \widehat{\mu}_{2}^{G B}$ against the uniform prior $\mathrm{d} \mu_{1} \mathrm{~d} \mu_{2}$ on $\mu_{1}>0$ and $\mu_{2}>0$ is minimax relative to the squared error loss if and only if $a_{1} a_{2} \leq 0$.

Proof. Since $\phi_{i}^{G B}$ satisfies condition (a) of Proposition 3.3, it is observed that $E\left[\widehat{\mu}_{i}\left(\phi_{i}^{G B}\right)-\mu_{i}\right]=c_{i}-E\left[\phi_{i}^{G B}\left(X_{i}\right)\right]>0$. If $a_{1} a_{2} \leq 0$, it is seen that $-2 a_{1} a_{2} E\left[\widehat{\mu}_{1}\left(\phi_{i}\right) \widehat{\mu}_{2}\left(\phi_{2}\right)\right] \geq$ 0 . From Proposition 3.1, it follows that $R\left(\mu_{i}, \widehat{\mu}_{i}^{U}\right)-R\left(\mu_{i}, \widehat{\mu}_{i}^{G B}\right) \geq 0$ for $i=1,2$. Thus, the dominance of $\hat{\theta}^{G B}$ over $\hat{\theta}^{U}$ is proved.

Reversely, suppose that $\hat{\theta}^{G B}$ dominates $\hat{\theta}^{U}$. We show that supposing the inequality $a_{1} a_{2}>0$ yields a contradiction. From Lemma 3.2, it is seen that at $\left(\mu_{1}, \mu_{2}\right)=(0,0)$,

$$
\begin{aligned}
& R\left(0,0, \hat{\theta}^{U}\right)-R\left(0,0, \hat{\theta}^{G B}\right) \\
& \quad=a_{1}^{2}\left\{R\left(0, \widehat{\mu}_{1}^{U}\right)-R\left(0, \widehat{\mu}_{1}^{G B}\right)\right\}+a_{2}^{2}\left\{R\left(0, \widehat{\mu}_{2}^{U}\right)-R\left(0, \widehat{\mu}_{2}^{G B}\right)\right\} \\
& \quad-2 a_{1} a_{2} E_{0}\left[\widehat{\mu}_{1}^{G B}\right] E_{0}\left[\widehat{\mu}_{2}^{G B}\right],
\end{aligned}
$$

which is equal to $-2 a_{1} a_{2} E_{0}\left[\widehat{\mu}_{1}^{G B}\right] E_{0}\left[\widehat{\mu}_{2}^{G B}\right]$ from Proposition 3.2. Under the supposition that $a_{1} a_{2}>0$, it is clear that $-2 a_{1} a_{2} E_{0}\left[\widehat{\mu}_{1}^{G B}\right] E_{0}\left[\widehat{\mu}_{2}^{G B}\right]<0$ at $\left(\mu_{1}, \mu_{2}\right)=(0,0)$. This contradicts that $\hat{\theta}^{G B}$ dominates $\hat{\theta}^{U}$. Hence, if $\hat{\theta}^{G B}$ dominates $\hat{\theta}^{U}$, then $a_{1} a_{2} \leq 0$.

### 3.3 Non-minimaxity for $k \geq 3$

We here treat the case of $k \geq 3$ where the setup of the random variables $X_{1}, \ldots, X_{k}$ is given around (1.1). Although it may be guessed that the generalized Bayes estimator against the uniform prior over the parameter $D$ is minimax, the following proposition shows that this conjecture is not correct.

Proposition 3.5 The generalized Bayes estimator $\hat{\theta}^{G B}$, given in (1.4), against the uniform prior over $D$ is not minimax if $k \geq 3$.

Proof. Corresponding to the decompositions given in (2.5), we can write $\hat{\theta}^{G B}$ as $\hat{\theta}^{G B}=\hat{\theta}_{+}^{G B}-\hat{\theta}_{-}^{G B}$ for $\hat{\theta}_{+}^{G B}=\sum_{i \in \Lambda_{+}} a_{i} \widehat{\mu}_{i}^{G B}$ and $\hat{\theta}_{-}^{G B}=-\sum_{i \in \Lambda_{-}} a_{i} \widehat{\mu}_{i}^{G B}$. Since $k \geq 3$, either $\Lambda_{+}$or $\Lambda_{-}$includes more than two elements. We here suppose that $\Lambda_{+}$has more than two elements without any loss of generality. The risk difference of the two estimators $\hat{\theta}^{U}$ and $\hat{\theta}^{G B}$ is expressed as

$$
\begin{aligned}
\Delta(\boldsymbol{\mu})= & R\left(\boldsymbol{\mu}, \hat{\theta}^{U}\right)-R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right) \\
= & E\left[\left(\hat{\theta}_{+}^{U}-\theta_{+}\right)^{2}-\left(\hat{\theta}_{+}^{G B}-\theta_{+}\right)^{2}\right]+E\left[\left(\hat{\theta}_{-}^{U}-\theta_{-}\right)^{2}-\left(\hat{\theta}_{-}^{G B}-\theta_{-}\right)^{2}\right] \\
& +2 E\left[\hat{\theta}_{+}^{G B}-\theta_{+}\right] E\left[\hat{\theta}_{-}^{G B}-\theta_{-}\right] \\
= & \Delta_{+}(\boldsymbol{\mu})+\Delta_{-}(\boldsymbol{\mu})+2 B_{+}(\boldsymbol{\mu}) B_{-}(\boldsymbol{\mu}), \quad \text { (say) }
\end{aligned}
$$

for $B_{+}(\boldsymbol{\mu})=E\left[\hat{\theta}_{+}^{G B}-\theta_{+}\right]$and $B_{-}(\boldsymbol{\mu})=E\left[\hat{\theta}_{-}^{G B}-\theta_{-}\right]$. Note that $B_{-}(\boldsymbol{\mu})=-\sum_{i \in \Lambda_{-}} a_{i} B_{i}\left(\mu_{i}\right)$ for $B_{i}\left(\mu_{i}\right)=E_{\mu_{i}}\left[X_{i}-\mu_{i}-\phi_{i}^{G B}\left(X_{i}\right)\right]$ and that $B_{i}\left(\mu_{i}\right)=c_{i}-E_{0}\left[\phi_{i}^{G B}\left(X_{i}+\mu_{i}\right)\right]$. Since $B_{i}\left(\mu_{i}\right) \rightarrow 0$ as $\mu_{i} \rightarrow \infty$, it is seen that $B_{-}(\boldsymbol{\mu}) \rightarrow 0$ as $\mu_{i} \rightarrow \infty$ for all $i \in \Lambda_{-}$. Since

$$
\Delta_{-}(\boldsymbol{\mu})=\sum_{i \in \Lambda_{-}} a_{i}^{2}\left\{E\left[\left(\widehat{\mu}_{i}^{U}-\mu_{i}\right)^{2}\right]-E\left[\left(\widehat{\mu}_{i}^{G B}-\mu_{i}\right)^{2}\right]\right\}-2 \sum_{i \in \Lambda_{-}} \sum_{j \neq i, j \in \Lambda_{-}} a_{i} a_{j} B_{i}\left(\mu_{i}\right) B_{j}\left(\mu_{j}\right),
$$

from Proposition 3.2, it can be seen that $\Delta_{-}(\boldsymbol{\mu}) \rightarrow 0$ as $\mu_{i} \rightarrow \infty$ for all $i \in \Lambda_{-}$. Thus,

$$
\lim _{\mu_{i} \rightarrow \infty, i \in \Lambda_{-}} \Delta(\boldsymbol{\mu})=\Delta_{+}(\boldsymbol{\mu}) .
$$

Similarly, $\Delta_{+}(\boldsymbol{\mu})$ is written as

$$
\Delta_{+}(\boldsymbol{\mu})=\sum_{i \in \Lambda_{+}} a_{i}^{2}\left\{E\left[\left(\widehat{\mu}_{i}^{U}-\mu_{i}\right)^{2}\right]-E\left[\left(\widehat{\mu}_{i}^{G B}-\mu_{i}\right)^{2}\right]\right\}-2 \sum_{i \in \Lambda_{+}} \sum_{j \neq i, j \in \Lambda_{+}} a_{i} a_{j} B_{i}\left(\mu_{i}\right) B_{j}\left(\mu_{j}\right),
$$

and from Proposition 3.1, it follows that the first term in the r.h.s. is equal to zero when $\mu_{i}=0$ for all $i \in \Lambda_{+}$. Since $B_{i}(0)=c_{i}-E_{0}\left[\phi_{i}^{G B}\left(X_{i}\right)\right]>0$ and $a_{i} a_{j}>0$ for any $i, j \in \Lambda_{+}$, it is concluded that

$$
\lim _{\mu_{i} \rightarrow 0, i \in \Lambda_{+}} \lim _{\mu_{i} \rightarrow \infty, i \in \Lambda_{-}} \Delta(\boldsymbol{\mu})=\lim _{\mu_{i} \rightarrow 0, i \in \Lambda_{+}} \Delta_{+}(\boldsymbol{\mu})=-2 \sum_{i \in \Lambda_{+}} \sum_{j \neq i, j \in \Lambda_{+}} a_{i} a_{j} B_{i}(0) B_{j}(0),
$$

which is negative. That is, $R\left(\boldsymbol{\mu}, \hat{\theta}^{U}\right)<R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right)$ for a $\boldsymbol{\mu} \in D$, which means that $\hat{\theta}^{G B}$ is not minimax.

## 4 Admissible and Minimax Estimation in Normal Distributions

The generalized Bayes estimator against the uniform prior over $D$ is not necessarily minimax as shown in the previous section. An interesting query is what is a prior distribution which results in the Bayes estimator satisfying the minimaxity. Although it may be hard to answer this query in the general location family, we can find an affirmative solution in a setup where the underlying distributions are normal.

Let $X_{1}, \ldots, X_{k}$ be mutually independent random variables where $X_{i}$ has a normal distribution with mean $\mu_{i}$ and unit variance, $\mathcal{N}\left(\mu_{i}, 1\right)$ for $\mu_{i}>0$. We use the same notations $D, \boldsymbol{\mu}, \theta, \boldsymbol{a}$ as defined around (1.1). A prior distribution considered here, denoted by $\pi^{*}(\boldsymbol{\mu})$, is that with probability one,

$$
\mu_{i}=\alpha_{i} \xi_{+} \quad \text { for } \quad i \in \Lambda_{+}, \quad \text { and } \quad \mu_{j}=\beta_{j} \xi_{-} \quad \text { for } \quad j \in \Lambda_{-},
$$

where $\alpha_{i}=a_{i} \sum_{j \in \Lambda_{+}} a_{j} / \sum_{j \in \Lambda_{+}} a_{j}^{2}, \beta_{j}=a_{j} \sum_{i \in \Lambda_{-}} a_{i} / \sum_{i \in \Lambda_{-}} a_{i}^{2}$, and $\xi_{+}$and $\xi_{-}$are distributed uniformly over the set $\left\{\left(\xi_{+}, \xi_{-}\right) \mid \xi_{+}>0, \xi_{-}>0\right\}$. For notational simplicity, let $A_{1}=\sum_{i \in \Lambda_{+}} a_{i}, A_{2}=\sum_{i \in \Lambda_{+}} \alpha_{i}^{2}, B_{1}=-\sum_{i \in \Lambda_{-}} a_{i}$ and $B_{2}=\sum_{i \in \Lambda_{-}} a_{i}^{2}$. Then it is noted
that $\sum_{i \in \Lambda_{+}} \alpha_{i}^{2}=A_{1}^{2} / A_{2}, \sum_{i \in \Lambda_{+}} \alpha_{i} x_{i} / \sum_{i \in \Lambda_{+}} \alpha_{i}^{2}=\hat{\theta}_{+}^{U} / A_{1}, \sum_{i \in \Lambda_{+}} a_{i} \alpha_{i}=A_{1}$, and similar equalities are satisfied for $\beta_{j}$. The joint density function of $(\boldsymbol{X}, \boldsymbol{\mu})$ is

$$
\begin{align*}
& (2 \pi)^{-k / 2} \exp \left\{-\frac{1}{2} \sum_{i \in \Lambda_{+}}\left(x_{i}-\alpha_{i} \xi_{+}\right)^{2}-\frac{1}{2} \sum_{j \in \Lambda_{+}}\left(x_{j}-\beta_{j} \xi_{-}\right)^{2}\right\} \mathrm{d} \boldsymbol{x} \mathrm{~d} \xi_{+} \mathrm{d} \xi_{-} \\
& \quad=\exp \left\{-\frac{A_{1}^{2}}{2 A_{2}}\left(\xi_{+}-\frac{\hat{\theta}_{+}^{U}}{A_{1}}\right)^{2}-\frac{B_{1}^{2}}{2 B_{2}}\left(\xi_{-}-\frac{\hat{\theta}_{-}^{U}}{B_{1}}\right)^{2}\right\} p\left(S_{1}, S_{2}\right) \mathrm{d} \boldsymbol{x} \mathrm{~d} \xi_{+} \mathrm{d} \xi_{-} \tag{4.1}
\end{align*}
$$

where $p\left(S_{1}, S_{2}\right)=(2 \pi)^{-k / 2} \exp \left\{-\left(S_{+}+S_{-}\right) / 2\right\}$ for $S_{+}=\sum_{i \in \Lambda_{+}} x_{i}^{2}-\left(\sum_{i \in \Lambda_{+}} \alpha_{i} x_{i}\right)^{2} / \sum_{i \in \Lambda_{+}} \alpha_{i}^{2}$ and $S_{-}=\sum_{j \in \Lambda_{-}} x_{j}^{2}-\left(\sum_{j \in \Lambda_{-}} \beta_{j} x_{j}\right)^{2} / \sum_{j \in \Lambda_{-}} \beta_{i}^{2}$. To simplify the notations more, let

$$
\theta_{1}=\theta_{+} / \sqrt{A_{2}}, \quad \theta_{2}=\theta_{-} / \sqrt{B_{2}}, \quad z_{1}=\hat{\theta}_{+}^{U} / \sqrt{A_{2}}, \quad z_{2}=\hat{\theta}_{-}^{U} / \sqrt{B_{2}} .
$$

Then, $z_{1}$ and $z_{2}$ are mutually independently distributed as $\mathcal{N}\left(\theta_{1}, 1\right)$ and $\mathcal{N}\left(\theta_{2}, 1\right)$, respectively, and

$$
\begin{equation*}
\theta=\sqrt{A_{2}} \theta_{1}-\sqrt{B_{2}} \theta_{2} . \tag{4.2}
\end{equation*}
$$

Making the transformations $\xi_{1}=A_{1} A_{2}^{-1 / 2} \xi_{+}$and $\xi_{2}=B_{1} B_{2}^{-1 / 2} \xi_{-}$, we can rewrite the joint density function of ( $\boldsymbol{X}, \boldsymbol{\mu}$ ) given in (4.1) as

$$
\begin{equation*}
\exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\} \frac{\sqrt{A_{2} B_{2}}}{A_{1} B_{1}} p\left(S_{1}, S_{2}\right) \mathrm{d} \boldsymbol{x} \mathrm{~d} \boldsymbol{\xi} \tag{4.3}
\end{equation*}
$$

where $\boldsymbol{\xi}=\left(\xi_{1}, \xi_{2}\right)^{t}$ and $\boldsymbol{z}=\left(z_{1}, z_{2}\right)^{t}$. Since $\sum_{i \in \Lambda_{+}} a_{i} \alpha_{i} \xi_{+}+\sum_{j \in \Lambda_{-}} a_{j} \beta_{j} \xi_{-}=\sqrt{A_{2}} \xi_{1}-$ $\sqrt{B_{2}} \xi_{2}$, the generalized Bayes estimator of $\theta$ against the prior $\pi^{*}$ can be written as

$$
\begin{align*}
\hat{\theta}^{G B *} & =\frac{\int_{D}\left(\sqrt{A_{2}} \xi_{1}-\sqrt{B_{2}} \xi_{2}\right) \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}{\int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}  \tag{4.4}\\
& =\sqrt{A_{2}}\left\{z_{1}-\phi^{G B *}\left(z_{1}\right)\right\}-\sqrt{B_{2}}\left\{z_{2}-\phi^{G B *}\left(z_{2}\right)\right\},
\end{align*}
$$

where $\boldsymbol{a}^{\boldsymbol{t}} \boldsymbol{X}=\hat{\theta}_{+}^{U}-\hat{\theta}_{-}^{U}=\sqrt{A_{2}} z_{1}-\sqrt{B_{2}} z_{2}$ and

$$
\phi^{G B *}(w)=\int_{-\infty}^{w} u \exp \left\{-u^{2} / 2\right\} \mathrm{d} u / \int_{-\infty}^{w} \exp \left\{-u^{2} / 2\right\} \mathrm{d} u
$$

The minimaxity and admissiblity of $\hat{\theta}^{G B *}$ can be established in the following proposition.
Proposition 4.1 The generalized Bayes estimator $\hat{\theta}^{G B *}$ of $\theta$ against the prior $\pi^{*}$ is admissible and minimax.

Proof. The minimaxity of $\hat{\theta}^{G B *}$ follows from Proposition 3.3. In fact, the arguments given around (4.2) and (4.4) mean that the generalized Bayes estimator of $\theta=\sqrt{A_{2}} \theta_{1}-$ $\sqrt{B_{2}} \theta_{2}$ is based on $\boldsymbol{z}$, which has $\mathcal{N}\left(\boldsymbol{\theta}, \boldsymbol{I}_{2}\right)$ where $\boldsymbol{\theta}=\left(\theta_{1}, \theta_{2}\right)^{t}$ for $\theta_{1}>0$ and $\theta_{2}>0$. Thus, it can be seen that $\phi^{G B *}(w)$ satisfies the conditions (a) and (b) of Proposition 3.3, so that $\hat{\theta}^{G B *}$ is minimax.

We next prove the admissibility of $\hat{\theta}^{G B *}$ using the method of Brown and Hwang (1982). Consider a sequence of the prior distributions $\pi_{n}^{*}(\boldsymbol{\mu})$ such that with probability one,

$$
\mu_{i}=\alpha_{i} \xi_{+} \quad \text { for } \quad i \in \Lambda_{+}, \quad \text { and } \quad \mu_{j}=\beta_{j} \xi_{-} \quad \text { for } \quad j \in \Lambda_{-},
$$

where $\left(\xi_{+}, \xi_{-}\right)$is distributed as $\left\{h_{n}\left(A_{1} A_{2}^{-1 / 2} \xi_{+}+B_{1} B_{2}^{-1 / 2} \xi_{-}\right)\right\}^{2}$ for

$$
h_{n}(t)= \begin{cases}1, & \text { if } 0 \leq t<1 \\ 1-\log t / \log n, & \text { if } 1 \leq t \leq n \\ 0, & \text { if } n<t\end{cases}
$$

Similarly to (4.3), we can write the joint density function of ( $\boldsymbol{X}, \boldsymbol{\mu})$ given in (4.1) as

$$
\begin{equation*}
\exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \frac{\sqrt{A_{2} B_{2}}}{A_{1} B_{1}} p\left(S_{1}, S_{2}\right) \mathrm{d} \boldsymbol{x} \mathrm{~d} \boldsymbol{\xi} \tag{4.5}
\end{equation*}
$$

where $|\boldsymbol{\xi}|$ denotes $|\boldsymbol{\xi}|=\xi_{1}+\xi_{2}$. The generalized Bayes estimator $\delta_{n}$ against the prior $\pi_{n}^{*}(\boldsymbol{\mu})$ can be expressed as

$$
\delta_{n}=\frac{\int_{D}\left(\sqrt{A_{2}} \xi_{1}-\sqrt{B_{2}} \xi_{2}\right)\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}
$$

and the generalized Bayes estimator $\hat{\theta}^{G B *}$ corresponds to the case of $h_{n}(|\boldsymbol{\xi}|)=1$, where $D=\left\{\boldsymbol{\xi} \mid \xi_{1}>0, \xi_{2}>0\right\}$. From (4.3), the difference of the Bayes risk functions of two estimators $\hat{\theta}^{G B *}$ and $\delta_{n}$ is written by

$$
\begin{aligned}
\Delta_{n} & =\int_{D} \int\left\{\left(\hat{\theta}^{G B *}-\theta\right)^{2}-\left(\delta_{n}-\theta\right)^{2}\right\} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \frac{\sqrt{A_{2} B_{2}}}{A_{1} B_{1}} p\left(S_{1}, S_{2}\right) \mathrm{d} \boldsymbol{x} \mathrm{~d} \boldsymbol{\xi} \\
& =\int\left(\hat{\theta}^{G B *}-\delta_{n}\right)^{2} \int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \frac{\sqrt{A_{2} B_{2}}}{A_{1} B_{1}} p\left(S_{1}, S_{2}\right) \mathrm{d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{x}
\end{aligned}
$$

where $\theta=\sqrt{A_{2}} \xi_{1}-\sqrt{B_{2}} \xi_{2}$ in the above bracket. Noting that $z_{1}, z_{2}$ and $\left(S_{+}, S_{-}\right)$are mutually independent, we can evaluate $\Delta_{n}$ as

$$
\begin{align*}
\Delta_{n}= & C \int\left(\hat{\theta}^{G B *}-\delta_{n}\right)^{2} \int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \mathrm{~d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{z} \\
\leq & 2 C A_{2} \int\left\{\int_{D} \xi_{1} f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D} \xi_{1} f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}\right\}^{2} \int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \mathrm{~d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{z} \\
& +2 C B_{2} \int\left\{\int_{D} \xi_{2} f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D} \xi_{2} f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}\right\}^{2} \int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \mathrm{~d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{z} \\
= & \Delta_{+}+\Delta_{-}, \quad \text { (say) } \tag{4.6}
\end{align*}
$$

where $C$ is an appropriate positive constant, and

$$
\begin{aligned}
f_{1}(\boldsymbol{\xi}) & =\frac{\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right)}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}}, \\
f_{2}(\boldsymbol{\xi}) & =\frac{\exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right)}{\int_{D} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}} .
\end{aligned}
$$

We now show that $\Delta_{+} \rightarrow 0$ and $\Delta_{-} \rightarrow 0$ as $n \rightarrow \infty$ by using the same arguments as in Tsukuma and Kubokawa (2008). Let $\boldsymbol{\theta} \vee \boldsymbol{\eta}=\left(\max \left(\theta_{1}, \eta_{1}\right) \text {, max }\left(\theta_{2}, \eta_{2}\right)\right)^{t}$ and $\boldsymbol{\theta} \wedge \boldsymbol{\eta}=\left(\min \left(\theta_{1}, \eta_{1}\right), \min \left(\theta_{2}, \eta_{2}\right)\right)^{t}$ for $\boldsymbol{\theta}=\left(\theta_{1}, \theta_{2}\right)^{t}$ and $\boldsymbol{\eta}=\left(\eta_{1}, \eta_{2}\right)^{t}$. Since $\left\{h_{n}(t)\right\}^{2}$ is nonincreasing in $t$, it is noted that $\left\{h_{n}(|\boldsymbol{\theta} \wedge \boldsymbol{\eta}|)\right\}^{2} \geq\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2}$, which implies that $f_{1}(\boldsymbol{\theta}) f_{2}(\boldsymbol{\eta}) \leq f_{2}(\boldsymbol{\theta} \vee \boldsymbol{\eta}) f_{1}(\boldsymbol{\theta} \wedge \boldsymbol{\eta})$. Hence from Karlin and Rinott (1980), it follows that

$$
\begin{equation*}
\int_{D} \xi_{i} f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi} \leq \int_{D} \xi_{i} f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}, \quad i=1,2 . \tag{4.7}
\end{equation*}
$$

Using the integration by parts, we can see that

$$
\begin{align*}
& \int_{D}\left(\xi_{1}-z_{1}\right)\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi} \\
& = \\
& \quad \exp \left(-z_{1}^{2} / 2\right) \int_{0}^{n}\left\{h_{n}\left(\xi_{2}\right)\right\}^{2} \exp \left(-\left(\xi_{2}-x_{2}\right)^{2} / 2\right) \mathrm{d} \xi_{2}  \tag{4.8}\\
& \quad \\
& \quad-\int_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n} h_{n}(|\boldsymbol{\xi}|)\{1 /(|\boldsymbol{\xi}| \log n)\} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}  \tag{4.9}\\
& \int_{D}\left(\xi_{1}-z_{1}\right) \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi} \\
& \quad=\exp \left(-z_{1}^{2} / 2\right) \int_{0}^{\infty} \exp \left(-\left(\xi_{2}-z_{2}\right)^{2} / 2\right) \mathrm{d} \xi_{2}
\end{align*}
$$

Combining (4.7), (4.8) and (4.9) gives that

$$
\begin{align*}
0 \leq & \int_{D}\left(\xi_{1}-z_{1}\right) f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D}\left(\xi_{1}-z_{1}\right) f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi} \\
= & \frac{\exp \left(-z_{1}^{2} / 2\right)}{\int_{0}^{\infty} \exp \left(-\left(\xi_{1}-z_{1}\right)^{2} / 2\right) \mathrm{d} \xi_{1}} \\
& \quad-\frac{\exp \left(-z_{1}^{2} / 2\right) \int_{0}^{n}\left\{h_{n}\left(\xi_{2}\right)\right\}^{2} \exp \left(-\left(\xi_{2}-z_{2}\right)^{2} / 2\right) \mathrm{d} \xi_{2}}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}} \\
& +\frac{\int_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n}(|\boldsymbol{\xi}| \log n)^{-1} h_{n}(|\boldsymbol{\xi}|) \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}} . \tag{4.10}
\end{align*}
$$

Since $h_{n}(|\boldsymbol{\xi}|) I(\boldsymbol{\xi} \in D, 0 \leq|\boldsymbol{\xi}| \leq n) \leq h_{n}\left(\xi_{2}\right) I\left(0 \leq \xi_{1} \leq n, 0 \leq \xi_{2} \leq n\right)$, we observe that

$$
\begin{aligned}
& \int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi} \\
& \quad \leq \int_{0 \leq \xi_{1} \leq n, 0 \leq \xi_{2} \leq n}\left\{h_{n}\left(\xi_{2}\right)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi} \\
& \quad \leq \int_{0}^{\infty} \exp \left(-\left(\xi_{1}-z_{1}\right)^{2} / 2\right) \mathrm{d} \xi_{1} \int_{0}^{n}\left\{h_{n}\left(\xi_{2}\right)\right\}^{2} \exp \left(-\left(\xi_{2}-z_{2}\right)^{2} / 2\right) \mathrm{d} \xi_{2},
\end{aligned}
$$

which is used to evaluate the second term in the r.h.s. of the equation (4.10). Hence from
(4.10),

$$
\begin{aligned}
0 & \leq \int_{D}\left(\xi_{1}-z_{1}\right) f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D}\left(\xi_{1}-z_{1}\right) f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi} \\
& \leq \frac{\int_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n}(|\boldsymbol{\xi}| \log n)^{-1} h_{n}(|\boldsymbol{\xi}|) \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}} .
\end{aligned}
$$

Using the Cauchy-Schwarz inequality, we can see that

$$
\begin{aligned}
& \left\{\int_{D} \xi_{1} f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D} \xi_{1} f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}\right\}^{2} \\
& \quad \leq \frac{\left\{\int_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n}(|\boldsymbol{\xi}| \log n)^{-1} h_{n}(|\boldsymbol{\xi}|) \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}\right\}^{2}}{\left\{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}\right\}^{2}} \\
& \quad \leq \frac{\int_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n}(|\boldsymbol{\xi}| \log n)^{-2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}}{\int_{D}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi}},
\end{aligned}
$$

which implies that

$$
\begin{aligned}
\Delta_{+} & =2 C A_{2} \int\left\{\int_{D} \xi_{1} f_{2}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}-\int_{D} \xi_{1} f_{1}(\boldsymbol{\xi}) \mathrm{d} \boldsymbol{\xi}\right\}^{2} \int_{D} \exp \left\{-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right\}\left\{h_{n}(|\boldsymbol{\xi}|)\right\}^{2} \mathrm{~d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{z} \\
& \leq 2 C A_{2} \iint_{\boldsymbol{\xi} \in D, 1 \leq|\boldsymbol{\xi}| \leq n}(|\boldsymbol{\xi}| \log n)^{-2} \exp \left(-\|\boldsymbol{\xi}-\boldsymbol{z}\|^{2} / 2\right) \mathrm{d} \boldsymbol{\xi} \mathrm{~d} \boldsymbol{z} \\
& =2 C A_{2}(2 \pi) \int_{\boldsymbol{\xi} \in D, 1 \leq \xi_{1}+\xi_{2} \leq n}\left(\xi_{1}+\xi_{2}\right)^{-2} \mathrm{~d} \boldsymbol{\xi}(\log n)^{-2} .
\end{aligned}
$$

Making the transformations $u=\xi_{1}+\xi_{2}$ and $w=\xi_{1} /\left(\xi_{1}+\xi_{2}\right)$, we can see that

$$
\int_{\boldsymbol{\xi} \in D, 1 \leq \xi_{1}+\xi_{2} \leq n}\left(\xi_{1}+\xi_{2}\right)^{-2} \mathrm{~d} \boldsymbol{\xi}=\int_{0}^{1} \mathrm{~d} w \int_{1}^{n} u^{-1} \mathrm{~d} u=\log n
$$

so that $\Delta_{+}$is evaluated as

$$
\Delta_{+} \leq 2 C A_{2}(2 \pi)(\log n)^{-1}
$$

which goes to zero as $n \rightarrow \infty$. Similarly, we have $\Delta_{-} \leq 2 C B_{2}(2 \pi)(\log n)^{-1}$. Therefore, the admissibility of $\hat{\theta}^{G B *}$ is established.

Finally, we give an expression of the risk function of $\hat{\theta}^{G B *}$. As seen from (4.3) and (4.4), the estimator $\hat{\theta}^{G B *}$ corresponds to the case of $k=2$ in the generalized Bayes estimator $\hat{\theta}^{G B}$ against the uniform prior over $D$ given in (1.3). Thus, we begin with handling the estimator $\hat{\theta}^{G B}$. First, the generalized Bayes estimator of the mean vector $\boldsymbol{\mu}$ against the uniform prior is given by $\widehat{\boldsymbol{\mu}}^{G B}=\boldsymbol{X}-\boldsymbol{\phi}^{G B}(\boldsymbol{X})$, where

$$
\phi^{G B}(\boldsymbol{X})=\frac{\int_{D}(\boldsymbol{X}-\boldsymbol{\xi}) \exp \left\{-\|\boldsymbol{X}-\boldsymbol{\xi}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}{\int_{D} \exp \left\{-\|\boldsymbol{X}-\boldsymbol{\xi}\|^{2} / 2\right\} \mathrm{d} \boldsymbol{\xi}}
$$

for $\boldsymbol{\xi}=\left(\xi_{1}, \ldots, \xi_{k}\right)^{t}$. It can be seen that $\phi^{G B}(\boldsymbol{X})=\left(\phi_{1}^{G B}\left(X_{1}\right), \ldots, \phi_{k}^{G B}\left(X_{k}\right)\right)^{t}$ where $\phi_{i}^{G B}\left(X_{i}\right)=\int_{0}^{\infty}\left(X_{i}-\xi_{i}\right) \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i} / \int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}$. The function $\phi_{i}^{G B}\left(X_{i}\right)$ can be further rewritten as

$$
\begin{equation*}
\phi_{i}^{G B}\left(X_{i}\right)=\phi_{i}^{G B}=\frac{\int_{-\infty}^{X_{i}} u \exp \left\{-u^{2} / 2\right\} \mathrm{d} u}{\int_{-\infty}^{X_{i}} \exp \left\{-u^{2} / 2\right\} \mathrm{d} u}=-\frac{\exp \left\{-X_{i}^{2} / 2\right\}}{\int_{-\infty}^{X_{i}} \exp \left\{-u^{2} / 2\right\} \mathrm{d} u} \tag{4.11}
\end{equation*}
$$

which is negative. In the context of the simultaneous estimation of $\boldsymbol{\mu}$, Hartigan (2004) derived an expression of the risk function of $\widehat{\boldsymbol{\mu}}^{G B}$, which is given by

$$
R\left(\boldsymbol{\mu}, \widehat{\boldsymbol{\mu}}^{G B}\right)=E\left[\left\|\widehat{\boldsymbol{\mu}}^{G B}-\boldsymbol{\mu}\right\|^{2}\right]=k+E_{\boldsymbol{\mu}}\left[\sum_{i=1}^{k} \mu_{i} \phi_{i}^{G B}\left(X_{i}\right)\right] .
$$

This demonstrates that $\widehat{\boldsymbol{\mu}}^{G B}$ dominates $\boldsymbol{X}$, namely, $\widehat{\boldsymbol{\mu}}^{G B}$ is minimax for any dimension $k$. To the contrast, the dominance results obtained in Section 3 mean that the generalized Bayes estimator $\hat{\theta}^{G B}$ is not necessarily minimax. Using the same arguments as in Hartigan (2004), we can get a similar expression of the risk function. Using the same notation as in (4.11), we can express the generalized Bayes estimator $\hat{\theta}^{G B}$ of $\theta=\boldsymbol{a}^{t} \boldsymbol{\mu}$ as

$$
\hat{\theta}^{G B}=\boldsymbol{a}^{t} \widehat{\boldsymbol{\mu}}^{G B}=\boldsymbol{a}^{t} \boldsymbol{X}-\boldsymbol{a}^{t} \boldsymbol{\phi}^{G B}(\boldsymbol{X}),
$$

whose risk function is given in the following proposition.
Proposition 4.2 The risk function $R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right)=E\left[\left(\hat{\theta}^{G B}-\theta\right)^{2}\right]$ is expressed as

$$
\begin{equation*}
R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right)=\boldsymbol{a}^{t} \boldsymbol{a}+E_{\boldsymbol{\mu}}\left[\sum_{i=1}^{k} a_{i}^{2} \mu_{i} \phi_{i}^{G B}\left(X_{i}\right)+2 \sum_{i=1}^{k} \sum_{j>i} a_{i} a_{j} \phi_{i}^{G B}\left(X_{i}\right) \phi_{j}^{G B}\left(X_{j}\right)\right] . \tag{4.12}
\end{equation*}
$$

Proof. For notational simplicity, let $\phi_{i}=\phi_{i}^{G B}\left(X_{i}\right)$ and $\boldsymbol{\phi}=\left(\phi_{1}, \ldots, \phi_{k}\right)^{t}$. Let $\Delta=R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right)-R\left(\boldsymbol{\mu}, \boldsymbol{a}^{t} \boldsymbol{X}\right)$. Since $R\left(\boldsymbol{\mu}, \boldsymbol{a}^{t} \boldsymbol{X}\right)=\boldsymbol{a}^{t} \boldsymbol{a}$, it is easy to see that

$$
\Delta=\boldsymbol{a}^{t} E\left[-(\boldsymbol{X}-\boldsymbol{\mu}) \phi^{t}-\boldsymbol{\phi}(\boldsymbol{X}-\boldsymbol{\mu})^{t}+\boldsymbol{\phi} \phi^{t}\right] \boldsymbol{a}
$$

Applying the Stein identity to one of the cross product terms gives that

$$
\begin{aligned}
E\left[(\boldsymbol{X}-\boldsymbol{\mu}) \phi^{t}\right] & =E\left[\operatorname{diag}_{i}\left(\left(X_{i}-\mu_{i}\right) \phi_{i}\right)\right] \\
& =E\left[\operatorname{diag}_{i}\left(1-\frac{\int_{0}^{\infty}\left(X_{i}-\xi_{i}\right)^{2} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}{\int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}+\phi_{i}^{2}\right)\right]
\end{aligned}
$$

where $\operatorname{diag}_{i}\left(d_{i}\right)$ denotes diag $\left(d_{1}, \ldots, d_{k}\right)$. Since $\left(X_{i}-\mu_{i}\right)\left(X_{i}-\xi_{i}\right)=\left(X_{i}-\xi_{i}\right)^{2}+\left(\xi_{i}-\right.$ $\left.\mu_{i}\right)\left(X_{i}-\xi_{i}\right)$, the other cross product term is written as

$$
\begin{aligned}
E\left[\boldsymbol{\phi}(\boldsymbol{X}-\boldsymbol{\mu})^{t}\right]= & E\left[\operatorname{diag}_{i}\left(\frac{\int_{0}^{\infty}\left(X_{i}-\xi_{i}\right)^{2} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}{\int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}\right)\right. \\
& \left.+\operatorname{diag}_{i}\left(\frac{\int_{0}^{\infty}\left(\xi_{i}-\mu_{i}\right)\left(X_{i}-\xi_{i}\right) \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}{\int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}\right)\right]
\end{aligned}
$$

By integration by parts, it is observed that

$$
\begin{aligned}
\int_{0}^{\infty} & \left(\xi_{i}-\mu_{i}\right)\left(X_{i}-\xi_{i}\right) \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i} \\
\quad & =\mu_{i} \exp \left\{-X_{i}^{2} / 2\right\}-\int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}
\end{aligned}
$$

From (4.11), it follows that

$$
\frac{\int_{0}^{\infty}\left(\xi_{i}-\mu_{i}\right)\left(X_{i}-\xi_{i}\right) \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}{\int_{0}^{\infty} \exp \left\{-\left(X_{i}-\xi_{i}\right)^{2} / 2\right\} \mathrm{d} \xi_{i}}=-\mu_{i} \phi_{i}-1
$$

Combining the above observations gives that

$$
\Delta=\boldsymbol{a}^{t} E\left[-\operatorname{diag}_{i}\left(\left\{\phi_{i}\right\}^{2}-\mu_{i} \phi_{i}\right)+\boldsymbol{\phi} \boldsymbol{\phi}^{t}\right] \boldsymbol{a}
$$

which yields expression (4.12).
When $\mu_{i}$ is zero, it is seen that $E_{0}\left[\phi_{i}\left(X_{i}\right)\right]=E_{0}\left[\phi_{1}\left(X_{1}\right)\right]$ for $i=2, \ldots, k$. Then from Proposition 4.2, it is seen that $R\left(\mathbf{0}, \hat{\theta}^{G B}\right)=\boldsymbol{a}^{t} \boldsymbol{a}+2 \sum_{i=1}^{k} \sum_{j>i} a_{i} a_{j}\left\{E_{0}\left[\phi_{1}^{G B}\left(X_{1}\right)\right]\right\}^{2}$, which implies that a necessary condition for the minimaxity of $\hat{\theta}^{G B}$ is that $\sum_{i=1}^{k} \sum_{j>i} a_{i} a_{j} \leq 0$ or $k=1$. As seen from Propositions 3.1 and 3.3, this is a sufficient condition as well. From Proposition 3.5, however, it is not sufficient in the case of $k \geq 3$.

As the case of $k=2$ in Proposition 4.2, we can provide an expression of the risk of the generalized Bayes estimator $\hat{\theta}^{G B *}$ given in (4.4). It is expressed as

$$
\begin{aligned}
R\left(\boldsymbol{\mu}, \hat{\theta}^{G B}\right)= & A_{2}^{2}+B_{2}^{2}+E_{\boldsymbol{\mu}}\left[A_{2} \theta_{1} \phi^{G B s}\left(z_{1}\right)+B_{2} \theta_{2} \phi^{G B s}\left(z_{2}\right)\right] \\
& -2 E_{\boldsymbol{\mu}}\left[\sqrt{A_{2} B_{2}} \phi^{G B *}\left(z_{1}\right) \phi^{G B *}\left(z_{2}\right)\right] .
\end{aligned}
$$

## 5 A relation to the Stein problem in variance estimation

In this section, we explain that the estimation of the restricted mean in a normal distribution is related to the Stein problem in the estimation of variance. This fact was established by Rukhin (1992) in a canonical form of a normal distributional model. We here use the same arguments to clarify the conditions on the parameters under which the Stein estimator of variance in a linear regression model converges to the truncated estimator of the restriced normal mean. We also show that the Stein problem in estimation of ratio of variances converges to the estimation of the difference of two restricted normal means.

Let us consider the linear regression model

$$
\begin{equation*}
\boldsymbol{y}=\boldsymbol{X} \boldsymbol{\beta}+\boldsymbol{\epsilon} \tag{5.1}
\end{equation*}
$$

where $\boldsymbol{y}$ and $\boldsymbol{X}$ are $n \times 1$ and $n \times p$ observation matrices, respectively, and $\boldsymbol{\beta}$ is a $p$-vector of the regression parameters and $\boldsymbol{\epsilon}$ is an $n$-vector of errors having a distribution $\mathcal{N}\left(\mathbf{0}, \sigma^{2} \boldsymbol{I}_{n}\right)$.

It is assumed that $\boldsymbol{X}$ is of full rank. Let $\widehat{\boldsymbol{\beta}}=\left(\boldsymbol{X}^{t} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{t} \boldsymbol{y}$ and $S=(\boldsymbol{y}-\boldsymbol{X} \widehat{\boldsymbol{\beta}})^{t}(\boldsymbol{y}-\boldsymbol{X} \widehat{\boldsymbol{\beta}})$, which are distributed as $\mathcal{N}\left(\boldsymbol{\beta}, \sigma^{2} \boldsymbol{I}_{p}\right)$ and $\sigma^{2} \chi_{m}^{2}$ for $m=n-p$. Stein (1964) showed that the best scale estimator based on $S$ is inadmissible and is improved on by using information contained in $\widehat{\boldsymbol{\beta}}$. For instance, the unbiased estimator $\hat{\sigma}^{2 U}=S / m$ is improved on by the truncated estimator

$$
\hat{\sigma}^{2 S}=\left\{S / m,\left(S+\widehat{\boldsymbol{\beta}}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \widehat{\boldsymbol{\beta}}\right) / n\right\}
$$

relative to an entropy loss function. Rukhin (1992) showed that this dominance result can be approximated by the estimation of a positive mean in a normal distribution.

Consider the asymptotic approximation under the following setup which is a slightly different framework from that of Rukin (1992):
(A1) The dimension $p$ behaves as $p=n-d_{n}$ where $d_{n}>0$ and $d_{n}=O\left(n^{\delta}\right)$ for $0 \leq \delta<1$.
(A2) $\boldsymbol{X}^{t} \boldsymbol{X} / n$ converges to a positive definite matrix, and there is a positive constant $\theta$ such that

$$
\lim _{n \rightarrow \infty} \sqrt{m} \boldsymbol{\beta}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \boldsymbol{\beta} /\left(n \sigma^{2}\right)=\sqrt{2} \theta
$$

Under (A1), it is easy to see that $m=O\left(n^{\delta}\right)$ and $m \rightarrow \infty$ as $n \rightarrow \infty$. Let $Z=$ $\left(S-m \sigma^{2}\right) /\left(\sqrt{2 m} \sigma^{2}\right)$ and $\boldsymbol{U}=\left(\boldsymbol{X}^{t} \boldsymbol{X}\right)^{1 / 2}(\widehat{\boldsymbol{\beta}}-\boldsymbol{\beta}) / \sigma$. Then $\boldsymbol{U}$ have $\mathcal{N}_{p}(\mathbf{0}, \boldsymbol{I})$. Since $E[S]=m \sigma^{2}$ and $\operatorname{Var}[S]=2 m \sigma^{4}$, it is seen that $Z$ converges to $\mathcal{N}(0,1)$ as $m \rightarrow \infty$. Thus,

$$
\begin{equation*}
\sqrt{m}\left(\hat{\sigma}^{2 U}-\sigma^{2}\right) / \sigma^{2}=\sqrt{2} Z=-\sqrt{2}(Y-\theta) \tag{5.2}
\end{equation*}
$$

where $Y=-Z+\theta$ and it converges to $\mathcal{N}(\theta, 1)$. Since $\widehat{\boldsymbol{\beta}}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \widehat{\boldsymbol{\beta}}=\sigma^{2} \boldsymbol{U}^{t} \boldsymbol{U}+2 \sigma \boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X}\right)^{1 / 2} \boldsymbol{U}+$ $\boldsymbol{\beta}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \boldsymbol{\beta}$, it can be seen that

$$
\begin{aligned}
& \sqrt{m}\left(\hat{\sigma}^{2 S}-\sigma^{2}\right) / \sigma^{2} \\
& =\sqrt{m}\left(\hat{\sigma}^{2 U}-\sigma^{2}\right) / \sigma^{2}-\sqrt{m} \max \left\{0, \frac{p}{n m} S-\frac{\widehat{\boldsymbol{\beta}}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \widehat{\boldsymbol{\beta}}}{n}\right\} \\
& =\sqrt{2} Z-\max \left\{0, \frac{p}{n}(\sqrt{2} Z+\sqrt{m})-\frac{\sqrt{m}}{n} \boldsymbol{U}^{t} \boldsymbol{U}\right. \\
& \\
& \left.\quad-2 \frac{\sqrt{m}}{\sigma \sqrt{n}} \boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U}-\frac{\sqrt{m} \boldsymbol{\beta}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \boldsymbol{\beta}}{n \sigma^{2}}\right\} \\
& =\sqrt{2} Z-\max \left\{0, \frac{p}{n} \sqrt{2} Z+\frac{\sqrt{m p}}{n} \sqrt{p}\left(\boldsymbol{U}^{t} \boldsymbol{U} / p-1\right)\right. \\
& \\
& \left.\quad-2 \frac{\sqrt{m}}{\sigma \sqrt{n}} \boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U}-\frac{\sqrt{m} \boldsymbol{\beta}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \boldsymbol{\beta}}{n \sigma^{2}}\right\} .
\end{aligned}
$$

From the assumptions, it is observed that $p / n \rightarrow 1, \sqrt{m p} / n=O\left(n^{(\delta-1) / 2}\right) \rightarrow 0$ and $\sqrt{p}\left(\boldsymbol{U}^{t} \boldsymbol{U} / p-1\right)=O_{p}(1)$, so that $(\sqrt{m p} / n) \sqrt{p}\left(\boldsymbol{U}^{t} \boldsymbol{U} / p-1\right) \rightarrow 0$. Note that

$$
\frac{\sqrt{m}}{\sigma \sqrt{n}} \boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U}=\sqrt{\sqrt{m} / n} \sqrt{\sqrt{m} \boldsymbol{\beta}^{t} \boldsymbol{X}^{t} \boldsymbol{X} \boldsymbol{\beta} / n} \frac{\boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U}}{\sqrt{\boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right) \boldsymbol{\beta}}}
$$

Since $\boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U} / \sqrt{\boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right) \boldsymbol{\beta}} \sim \mathcal{N}(0,1)$ and $\sqrt{m} / n=O\left(n^{\delta / 2-1}\right)$, it is seen that $\{\sqrt{m} / \sigma \sqrt{n}\} \boldsymbol{\beta}^{t}\left(\boldsymbol{X}^{t} \boldsymbol{X} / n\right)^{1 / 2} \boldsymbol{U} \rightarrow 0$. Thus,

$$
\begin{align*}
\sqrt{m}\left(\hat{\sigma}^{2 S}-\sigma^{2}\right) / \sigma^{2} & \rightarrow \sqrt{2} Z-\max \{0, \sqrt{2} Z-\sqrt{2} \theta\} \\
& =-\sqrt{2}(\max \{Y, 0\}-\theta) \tag{5.3}
\end{align*}
$$

where $Y=-Z+\theta$ converges to $\mathcal{N}(\theta, 1)$ for $\theta>0$. This shows that Stein's truncated estimator of $\sigma^{2}$ converges to the nonnegative estimator $\max (Y, 0)$ of $\theta$ where $Y \sim \mathcal{N}(\theta, 1)$ for $\theta>0$.

We next consider the estimation of ratio of variances in two linear models, given by $\boldsymbol{y}_{i}=\boldsymbol{X}_{i} \boldsymbol{\beta}_{i}+\boldsymbol{\epsilon}_{i}, i=1,2$, where $\boldsymbol{\epsilon}_{i} \sim \mathcal{N}_{n}\left(\mathbf{0}, \sigma_{i}^{2} \boldsymbol{I}_{n}\right), \boldsymbol{\beta}_{i}$ is a $p \times 1$ vector and the other variables are defined similarly to (5.1). Let $\widehat{\boldsymbol{\beta}}_{i}$ and $S_{i}$ be defined as similar statistics as in model (5.1). Kubokawa (1994b), Kubokawa and Srivastava (1996) and Iliopoulos and Kourouklis (1999) showed that the best multiple by the ratio $S_{1} / S_{1}$ can be improved on by using information on $\widehat{\boldsymbol{\beta}}_{1}$ and $\widehat{\boldsymbol{\beta}}_{2}$ in the estimation of the ratio $\rho=\sigma_{2}^{2} / \sigma_{1}^{2}$. Let $\hat{\sigma}_{i}^{2 U}=S_{i} / m$ and $\hat{\sigma}_{i}^{2 S}=\min \left\{\hat{\sigma}_{i}^{2 U},\left(S_{i}+\widehat{\boldsymbol{\beta}}_{i}^{t} \boldsymbol{X}_{i}^{t} \boldsymbol{X}_{i} \widehat{\boldsymbol{\beta}}_{i}\right) / n\right\}$ for $i=1,2$ and $m=n-p$. For instance, the ratio of the unbiased estimators $\hat{\sigma}_{2}^{2 U} / \hat{\sigma}_{1}^{2 U}$ should be improved on by the ratio of the truncated estimators $\hat{\sigma}_{2}^{2 S} / \hat{\sigma}_{1}^{2 S}$. To derive the asymptotic approximations of these ratio estimators, it is noted that for two estimators $\hat{\sigma}_{1}^{2}$ and $\hat{\sigma}_{2}^{2}$,

$$
\begin{align*}
\sqrt{m}\left(\hat{\sigma}_{2}^{2} / \hat{\sigma}_{1}^{2}-\sigma_{2}^{2} / \sigma_{1}^{2}\right) & =\frac{\sqrt{m}\left(\hat{\sigma}_{2}^{2}-\sigma_{2}^{2}\right) / \sigma_{2}^{2}+\sqrt{m}}{\left(\hat{\sigma}_{1}^{2}-\sigma_{1}^{2}\right) / \sigma_{1}^{2}+1} \frac{\sigma_{2}^{2}}{\sigma_{1}^{2}}-\sqrt{m} \frac{\sigma_{2}^{2}}{\sigma_{1}^{2}} \\
& =\frac{\sigma_{2}^{2}}{\sigma_{1}^{2}}\left(\frac{\sqrt{m}\left(\hat{\sigma}_{2}^{2}-\sigma_{2}^{2}\right) / \sigma_{2}^{2}}{\left(\hat{\sigma}_{1}^{2}-\sigma_{1}^{2}\right) / \sigma_{1}^{2}+1}-\frac{\sqrt{m}\left(\hat{\sigma}_{1}^{2}-\sigma_{1}^{2}\right) / \sigma_{1}^{2}}{\left(\hat{\sigma}_{1}^{2}-\sigma_{1}^{2}\right) / \sigma_{1}^{2}+1}\right) \tag{5.4}
\end{align*}
$$

Assume the condition (A1) and
(A2') For $i=1,2, \boldsymbol{X}_{i}^{t} \boldsymbol{X}_{i} / n$ converges to a positive definite matrix, and there is positive constant $\theta_{i}$ such that

$$
\lim _{n \rightarrow \infty} \sqrt{m} \boldsymbol{\beta}_{i}^{t} \boldsymbol{X}_{i}^{t} \boldsymbol{X}_{i} \boldsymbol{\beta}_{i} /\left(n \sigma_{i}^{2}\right)=\sqrt{2} \theta_{i} .
$$

For $i=1,2$, let $Z_{i}=\left(S_{i}-m \sigma_{i}^{2}\right) /\left(\sqrt{2 m} \sigma_{i}^{2}\right)$ and $Y_{i}=-Z_{i}+\theta_{i}$, which has $\mathcal{N}\left(\theta_{i}, 1\right)$. Hence from (5.2) and (5.4), it is observed that

$$
\sqrt{m}\left(\hat{\sigma}_{2}^{2 U} / \hat{\sigma}_{1}^{2 U}-\sigma_{2}^{2} / \sigma_{1}^{2}\right) \rightarrow\left(\sigma_{2}^{2} / \sigma_{1}^{2}\right)\left\{\left(Y_{1}-Y_{2}\right)-\left(\theta_{1}-\theta_{2}\right)\right\}
$$

Also from (5.3) and (5.4),

$$
\sqrt{m}\left(\hat{\sigma}_{2}^{2 S} / \hat{\sigma}_{1}^{2 S}-\sigma_{2}^{2} / \sigma_{1}^{2}\right) \rightarrow\left(\sigma_{2}^{2} / \sigma_{1}^{2}\right)\left\{\left(\max \left(Y_{1}, 0\right)-\max \left(Y_{2}, 0\right)\right)-\left(\theta_{1}-\theta_{2}\right)\right\}
$$

This shows that the estimation of the ratio of the variances can be approximated by the estimation of the difference of the positive means of normal distributions. Thus, the estimation of the mean difference can be motivated from the estimation of ratio of variances.

## References

[1] Brown, L.D. and Hwang, J.T. (1982). A unified admissibility proof. In Statistical Decision Theory and Related Topics III (S.S. Gupta, J. Berger, eds.), 205-230. Academic Press, New York.
[2] Farrell, R.H. (1964). Estimators of a location parameter in the absolutely continuous case. Ann. Math. Statist., 35, 949-998.
[3] Girshick, M.A. and Savage, L.J. (1951). Bayes and minimax estimates for quadratic loss functions. In Proc. Second Berkeley Symp. Math. Statist. Probab., 1, 53-74. University of California Press, Berkeley.
[4] Hartigan, J. (2004). Uniform priors on convex sets improve risk. Statist. Prob. Letters, 67, 285-288.
[5] Iliopoulos, G. and Kourouklis, S. (1999). Improving on the best affine equivariant estimator of the ratio of the generalized variances. J. Multivariate Analysis, 68, 176-192.
[6] Karlin, S. and Rinott, Y. (1980). Classes of orderings of measures and related correlation inequalities. I. Multivariate totally positive distributions. J. Multivariate Anal., 10, 467-498.
[7] Katz, M. (1961). Admissible and minimax estimates of parameters in truncated spaces. Ann. Math. Statist., 32, 136-142..
[8] Kubokawa, T. (1994a). A unified approach to improving equivariant estimators. Ann. Statist., 22, 290-299.
[9] Kubokawa, T. (1994b). Double shrinkage estimation of ratio of scale parameters. Ann. Inst. Statist. Math., 46, 95-119.
[10] Kubokawa, T. (1999). Shrinkage and modification techniques in estimation of variance and the related problems: A review. Commun. Statist. - Theory and Methods, 28, 613-650.
[11] Kubokawa,T. (2004). Minimaxity in estimation of restricted parameters. J. Japan Statist. Soc., 34, 229-253.
[12] Kubokawa, T. and Saleh, A.K.MD.E. (1998). Estimation of location and scale parameters under order restrictions. J. Statistical Research, 28, 41-51.
[13] Kubokawa, T. and Srivastava, M.S. (1996). Double shrinkage estimators of ratio of variances. Proceedings of the Sixth Lukacs Symposium, 139-154.
[14] Marchand, E. and Strawderman, W. E. (2004). Estimation in restricted parameter spaces: A review. Festschrift for Herman Rubin, IMS Lecture Notes-Monograph Series, 45, 21-44.
[15] Marchand, E. and Strawderman, W.E. (2005). Improving on the minimum risk equivariant estimator of a location parameter which is constrained to an interval or a half-interval. Ann. Inst. Statist. Math., 57, 129-143.
[16] Rukhin, A. (1992). Asymptotic risk behavior of mean vector and variance estimators and the problem of positive normal mean. Ann. Inst. Statist. Math., 44, 299-311.
[17] Stein, C. (1964). Inadmissibility of the usual estimator for the variance of a normal distribution with unknown mean. Ann. Inst. Statist. Math., 16, 155-160.
[18] Tsukuma, H. and Kubokawa, T. (2008). Stein's phenomenon in estimation of means restricted to a polyhedral convex cone. J. Multivariate Analysis, 99, 141-164.


[^0]:    *Faculty of Economics, University of Tokyo, 7-3-1, Hongo, Bunkyo-ku, Tokyo 113-0033, Japan E-Mail: tatsuya@e.u-tokyo.ac.jp

