# A Weak Approximation with Asymptotic Expansion and Multidimensional Malliavin Weights 

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# A weak approximation with asymptotic expansion and multidimensional Malliavin weights * 

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#### Abstract

This paper develops a new efficient scheme for approximations of expectations of the solutions to stochastic differential equations (SDEs). In particular, we present a method for connecting approximate operators based on an asymptotic expansion with multidimensional Malliavin weights to compute a target expectation value precisely. The mathematical validity is given based on Watanabe and Kusuoka theories in Malliavin calculus. Moreover, numerical experiments for option pricing under local and stochastic volatility models confirm the effectiveness of our scheme. Especially, our weak approximation substantially improve the accuracy at deep Out-of-The-Moneys (OTMs).


Keywords: Asymptotic expansion, Weak approximation, Malliavin calculus, Watanabe theory, Kusuoka Scheme, Option pricing

## 1 Introduction

Developing an approximation method for expectations of diffusion processes is an interesting topic in various research fields. In fact, it seems so useful that a precise approximation for the expectation would lead to substantial reduction of computational burden so that the subsequent analyses could be very easily implemented. Particularly, in finance it has drawn much attention for more than the past two decades since fast and precise computation is so important in terms of competition and risk management in practice such as in trading and investment.

An example among a large number of the related researches is an asymptotic expansion approach, which is mathematically justified by Watanabe theory (Watanabe (1987)) in Malliavin calculus (e.g. Malliavin (1997)). Especially, the asymptotic expansion have been applied to a broad class of problems in finance: for instance, see Takahashi and Yamada (2012a,b, 2013, 2014) and references therein.

Although the asymptotic expansion up to the fifth order is known to be sufficiently accurate for option pricing (e.g. Takahashi et al. (2012)), the main criticism against the method would be that the approximate density function deviates from the true density at its tails that is, some region of the very deep Out-of-The-Money (OTM). However, there exist similar problems, at least implicitly in other well-known approximation methods such as Hagan et al. (2002).

On the other hand, the Monte Carlo simulation method is quite popular mainly due to the ease of its implementation. Nevertheless, in order to achieve accuracy sufficient enough in practice, there exists an unavoidable drawback in computational cost under the standard weak approximation schemes of SDEs such as the Euler-Maruyama scheme.

[^0]To overcome this problem, Kusuoka (2001, 2003b, 2004) developed a high order weak approximation scheme for SDEs based on Malliavin calculus and Lie algebra, which opened the door for the possibility that the computational speed and the accuracy in the Monte Carlo simulation satisfies stringent requirements in financial business. Independently, Lyons and Victoir (2004) developed a cubature method on the Wiener space. Since then, there have been a large number of researches for weak approximations and its applications to the computational finance inspired by those pioneering works. For instance see Crisan et al. (2013) for the Kusuoka's method and its related works (e.g. Bayer et al. (2013)).

This paper develops a new weak approximation scheme for expectations of functions of the solutions to SDEs. In particular, the scheme connects approximate operators constructed based on the asymptotic expansion. More concretely, a diffusion semigroup is defined as the expectation of an appropriate function of the solution to a certain SDE: for example, $P_{t}^{\varepsilon} f(x)=E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ with the solution $X_{t}^{x, \varepsilon}$ of a SDE with perturbation parameter $\varepsilon$ and a function $f$. Then, we approximate $P_{t}^{\varepsilon}$ by an operator $Q_{t}^{\varepsilon, m}$ which is constructed based on the asymptotic expansion up to a certain order $m$. Thus, given a partition of $[0, T], \pi=\left\{\left(t_{0}, t_{1}, \cdots, t_{n}\right): 0=t_{0}<t_{1}<\cdots<t_{n}=T\right\}$, we are able to approximate $P_{T}^{\varepsilon} f(x)$ by connecting the expansion-based approximations sequentially: that is, with $s_{k}=t_{k}-t_{k-1}, k=1, \cdots, n$,

$$
P_{T}^{\varepsilon} f(x) \simeq Q_{s_{n}}^{\varepsilon, m} Q_{s_{n-1}}^{\varepsilon, m} \cdots Q_{s_{1}}^{\varepsilon, m} f(x)
$$

This paper justifies this idea by applying Malliavin calculus, particularly, theories developed by Watanabe (1987), Kusuoka (2003a) and Kusuoka (2001, 2004).

Moreover, we show through numerical examples for option pricing that very few partitions such as $n=2$ is mostly enough to substantially improve the errors at deep OTMs of expansions with order $m=1,2$. For a related but different approach with similar motivation see Section 5 in Fujii (2013).

The organization of the paper is as follows. The next section introduces the setup and the basic results necessary for the subsequent analysis. Section 3 shows our main result for a new weak approximation of the expectation of diffusion processes. After Section 4 briefly describes an example for the implementation method of our scheme, Section 5 provides numerical experiments for option pricing under local and stochastic volatility models. Section 6 makes concluding remarks. Appendix gives the proofs of the theorems 1,2 and 3 as well as the lemma 2 and its proof.

## 2 Preparation

Let $(\mathcal{W}, H, \mathbb{P})$ be the $d$-dimensional Wiener space, i.e. $\mathcal{W}=\left\{w \in C\left([0, T] \rightarrow \mathbf{R}^{d}\right) ; w(0)=0\right\}$ which is a real Banach space under the supremum norm, $H=\{h \in \mathcal{W} ; t \mapsto h(t)$ is absolutely continuous and $\left.\|h\|_{H}^{2}=\int_{0}^{T}\left|\frac{d}{d t} h(t)\right|^{2} d t<\infty\right\}$ is a real Hilbert space under $\|\cdot\|_{H}$ called the Carmeron-Martin subspace and $\mathbb{P}$ is the $d$-dimensional Wiener measure. Let $B_{t}=\left(B_{t}^{1}, \cdots, B_{t}^{d}\right)^{\top}$ be a $d$-dimensional Brownian motion. In this paper, we consider the following general perturbed $N$-dimensional stochastic differential equation with $\varepsilon \in(0,1]$ :

$$
\begin{equation*}
X_{t}^{x, \varepsilon}=x+\int_{0}^{t} V_{0}\left(\varepsilon, X_{s}^{x, \varepsilon}\right) d s+\varepsilon \sum_{j=1}^{d} \int_{0}^{t} V_{j}\left(X_{s}^{x, \varepsilon}\right) d B_{s}^{j} \tag{2.1}
\end{equation*}
$$

where $V_{0} \in C_{b}^{\infty}\left((0,1] \times \mathbf{R}^{N} ; \mathbf{R}^{N}\right)$ and $V_{j} \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}^{N}\right), j=1, \cdots, d$ are bounded. Hereafter, we will use the notation $V f(x)=\sum_{i=1}^{N} V^{i}(x)\left(\partial f / \partial x_{i}\right)(x)$ for $V \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}^{N}\right)$ and $f$ a differentiable function $\mathbf{R}^{N}$ into $\mathbf{R}$. $X_{t}^{x, \varepsilon}$ can be written in the Stratonovich form:

$$
\begin{equation*}
X_{t}^{x, \varepsilon}=x+\int_{0}^{t} \tilde{V}_{0}\left(\varepsilon, X_{s}^{x, \varepsilon}\right) d s+\varepsilon \sum_{j=1}^{d} \int_{0}^{t} \tilde{V}_{j}\left(X_{s}^{x, \varepsilon}\right) \circ d B_{s}^{j} \tag{2.2}
\end{equation*}
$$

where

$$
\begin{align*}
\tilde{V}_{0}^{i}(\varepsilon, x) & =V_{0}^{i}(\varepsilon, x)-\frac{\varepsilon^{2}}{2} \sum_{j=1}^{d} V_{j} V_{j}^{i}(x),  \tag{2.3}\\
\varepsilon \tilde{V}_{j}^{i}(x) & =\varepsilon V_{j}^{i}(x), \quad j=1, \cdots, d . \tag{2.4}
\end{align*}
$$

Here, we consider the case $V_{0}^{i}(\varepsilon, x)=\varepsilon^{k} \hat{V}_{0}^{i}(x), \hat{V}_{0} \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}^{N}\right), k=0,1,2$, for $i=1, \cdots, N$, which is useful in applications (See Takahashi and Toda (2013) for the details). Moreover, we assume the following condition $[\mathbf{H}]$ on the vector fields, which ensures both the integration by parts on the Wiener space and the asymptotic expansion in the next section.
$[\mathbf{H}]$ The matrix $A(x)=\left(A^{i, i^{\prime}}(x)\right)_{i, i^{\prime}}$ defined by

$$
\begin{equation*}
A^{i, i^{\prime}}(x)=\sum_{j=1}^{d} V_{j}^{i}(x) V_{j}^{i^{\prime}}(x), \text { for all } x \in \mathbf{R}^{N}, 1 \leq i, i^{\prime} \leq N \tag{2.5}
\end{equation*}
$$

is non-degenerate, i.e. $\operatorname{det}(A(x))>0$.

### 2.1 The space $\mathcal{K}_{r}$

Let $\mathbf{D}^{k, p}(E), k \geq 1, p \in[1, \infty)$ be the space of $k$-times Malliavin differentiable Wiener functionals $F \in L^{p}(\mathcal{W}, E)$, where $E$ is a separable Hilbert space. See Watanabe (1987), Ikeda and Watanabe (1989), Malliavin (1997), Malliavin and Thalmaier (2006) and Nualart (2006) for more details of the notations. This subsection introduces the space of Wiener functionals $\mathcal{K}_{r}$ developed by Kusuoka (2003a) and its properties. The element of $\mathcal{K}_{r}$ is called the Kusuoka-Stroock function. See Nee $(2010,2011)$ and Crisan et al. (2013) for more details of the notations and the proofs.
Definition 1. Given $r \in \mathbf{R}$ and $n \in \mathbf{N}$, we denote by $\mathcal{K}_{r}(E, n)$ the set of functions $G:(0,1] \times$ $\mathbf{R}^{N} \rightarrow \mathbf{D}^{n, \infty}(E)$ satisfying the following:

1. $G(t, \cdot)$ is $n$-times continuously differentiable and $\left[\partial^{\alpha} G / \partial x^{\alpha}\right]$ is continuous in $(t, x) \in(0,1] \times$ $\mathbf{R}^{N}$ a.s. for any multi-index $\alpha=\alpha^{(l)} \in\{1, \cdots, d\}^{l}$ with length $|\alpha|=l \leq n$. Here, $\left[\partial^{\alpha} G / \partial x^{\alpha}\right]$ is the partial derivative of $G(t, x)$ given by $\frac{\partial^{l}}{\partial x_{\alpha_{1}} \cdots \partial x_{\alpha_{l}}} G(t, x)$.
2. For all $k \leq n-|\alpha|, p \in[1, \infty)$,

$$
\begin{equation*}
\sup _{t \in(0,1], x \in \mathbf{R}^{N}} t^{-r / 2}\left\|\frac{\partial^{\alpha} G}{\partial x^{\alpha}}(t, x)\right\|_{\mathbf{D}^{k, p}}<\infty . \tag{2.6}
\end{equation*}
$$

We write $\mathcal{K}_{r}$ for $\mathcal{K}_{r}(\mathbf{R}, \infty)$.
Next, we show the basic properties of the Kusuoka-Stroock functions.
Lemma 1. [Properties of Kusuoka-Stroock functions]

1. The function $(t, x) \in(0,1] \times \mathbf{R}^{N} \mapsto X_{t}^{x, \varepsilon}$ belongs to $\mathcal{K}_{0}$.
2. Suppose $G \in \mathcal{K}_{r}(n)$ where $r \geq 0$. Then, for $i=1, \cdots, d$,

$$
\begin{equation*}
\text { (a) } \int_{0} G(s, x) d B_{s}^{i} \in \mathcal{K}_{r+1}(n), \text { and (b) } \int_{0} G(s, x) d s \in \mathcal{K}_{r+2}(n) \text {. } \tag{2.7}
\end{equation*}
$$

3. If $G_{i} \in \mathcal{K}_{r_{i}}\left(n_{i}\right), i=1, \cdots, l$, then

$$
\begin{equation*}
\text { (a) } \prod_{i}^{l} G_{i} \in \mathcal{K}_{r_{1}+\cdots+r_{l}}\left(\min _{i} n_{i}\right) \text {, and (b) } \sum_{i=1}^{l} G_{i} \in \mathcal{K}_{\min _{i} r_{i}}\left(\min _{i} n_{i}\right) \text {. } \tag{2.8}
\end{equation*}
$$

Then, we summarize the Malliavin's integration by parts formula using Kusuoka-Stroock functions. Hereafter, for any multi-index $\alpha=\alpha^{(k)}:=\left(\alpha_{1}, \cdots, \alpha_{k}\right) \in\{1, \cdots, N\}^{k}, k \geq 1$ with the length $\left|\alpha^{(k)}\right|=k$, we denote by $\partial_{\alpha^{(k)}}$ the partial derivative $\frac{\partial^{\alpha}}{\partial x^{\alpha}}=\frac{\partial^{k}}{\partial x_{\alpha_{1}} \cdots \partial x_{\alpha_{k}}}$.
Proposition 1. Suppose that the condition $[\mathbf{H}]$ holds. Let $G:(0,1] \times \mathbf{R}^{N} \rightarrow \mathbf{D}^{\infty}=\mathbf{D}^{\infty, \infty}(\mathbf{R})$ be an element of $\mathcal{K}_{r}$ and let $f$ be a function that belongs to the space $C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$. Then for any multi-index $\alpha^{(k)} \in\{1, \cdots, N\}^{k}, k \geq 1$, there exists $H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right) \in \mathcal{K}_{r-k}$ such that

$$
\begin{equation*}
E\left[\partial_{\alpha^{(k)}} f\left(X_{t}^{x, \varepsilon}\right) G(t, x)\right]=E\left[f\left(X_{t}^{x, \varepsilon}\right) H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right)\right], t \in(0,1] \tag{2.9}
\end{equation*}
$$

with

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left\|H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right)\right\|_{L^{p}} \leq t^{(r-k) / 2} C \tag{2.10}
\end{equation*}
$$

where $H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right)$ is recursively given by

$$
\begin{align*}
H_{(i)}\left(X_{t}^{x, \varepsilon}, G(t, x)\right) & =\delta\left(\sum_{j=1}^{N} G(t, x) \gamma_{i j}^{X_{t}^{x, \varepsilon}} D X_{t}^{x, \varepsilon, j}\right)  \tag{2.11}\\
H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right) & =H_{\left(\alpha_{k}\right)}\left(X_{t}^{x, \varepsilon}, H_{\alpha^{(k-1)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right)\right) \tag{2.12}
\end{align*}
$$

and a positive constant $C$. Here, $\delta$ is the Skorohod integral and $D X_{t}^{x, \varepsilon}$ is the Malliavin derivative of $X_{t}^{x, \varepsilon}$,

$$
\begin{equation*}
\left\langle D X_{t}^{x, \varepsilon}, h\right\rangle_{H}=\sum_{k=1}^{d} \int_{0}^{t} D_{s, k} X_{t}^{x, \varepsilon} \frac{d}{d s} h_{k}(s) d s=\lim _{\lambda \rightarrow 0} \frac{X_{t}^{x, \varepsilon}(w+\lambda h)-X_{t}^{x, \varepsilon}(w)}{\lambda}, \quad h \in H \tag{2.13}
\end{equation*}
$$

and $\gamma^{X_{t}^{x, \varepsilon}}=\left(\gamma_{i j}^{X_{i}^{x, \varepsilon}}\right)_{1 \leq i, j \leq N}$ is the inverse matrix of the Malliavin covariance of $X_{t}^{x, \varepsilon}$.
Proof. By $1,2,3$ of Lemma 1, we can see that the Malliavin covariance of $X_{t}^{x, \varepsilon}$ is given by

$$
\begin{equation*}
\sigma_{i, j}^{X_{t}^{x, \varepsilon}}=\sum_{k=1}^{d} \int_{0}^{t} D_{s, k} X_{t}^{x, \varepsilon, i} D_{s, k} X_{t}^{x, \varepsilon, j} d s \in \mathcal{K}_{2} \tag{2.14}
\end{equation*}
$$

since $D_{s, k} X_{t}^{x, \varepsilon, i} \in \mathcal{K}_{0}, s \leq t, k=1, \cdots, d, i=1, \cdots, N$. Under $[\mathbf{H}]$, it can be shown that the nondegenerate condition of the Malliavin covariance matrix is satisfied when $\varepsilon>0$ (but not satisfied when $\varepsilon=0$, that is, the Malliavin covariance matrix $\sigma^{X_{t}^{x, \varepsilon}}$ is not uniformly non-degenerate in $\varepsilon$ ) and then (2.9) holds (See the proofs of Proposition 5.8, Theorem 5.9 and Theorem 6.7 of Shigekawa (2004)). Also, we have $\gamma^{X_{t}^{x, \varepsilon}} \in \mathcal{K}_{-2}$ since $\gamma^{X_{t}^{x, \varepsilon}}=\left(\sigma^{X_{t}^{x, \varepsilon}}\right)^{-1}=\frac{\operatorname{adj} \sigma^{X_{t}^{x, \varepsilon}}}{\operatorname{det} \sigma^{X_{t}^{x, \varepsilon}}}$. Here, $\operatorname{adj} A$ is the adjugate matrix of $A$. By the property of the Skorohod integral (Proposition 1.3.3 of Nualart (2006) and Lemma 5.2 of Malliavin (1997) or (4.15) of Proof of Lemma 4.10 of Malliavin and Thalmaier (2006)), we have

$$
\begin{gather*}
H_{(i)}\left(X_{t}^{x, \varepsilon}, G(t, x)\right)=\delta\left(\sum_{j=1}^{N} G(t, x) \gamma_{i j}^{X_{t}^{\varepsilon}} D X_{t}^{x, \varepsilon, j}\right) \\
=\left[G(t, x) \sum_{j=1}^{N} \sum_{k=1}^{d} \int_{0}^{t} \gamma_{i j}^{X_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} \varepsilon V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k}\right. \\
\left.\quad-\sum_{j=1}^{N} \sum_{k=1}^{d} \int_{0}^{t}\left[D_{s, k} G(t, x)\right] \gamma_{i j}^{X_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} \varepsilon V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d s\right] . \tag{2.15}
\end{gather*}
$$

Again, by Lemma 1, the first and the second terms in the second equality is characterized by

$$
\begin{align*}
& G(t, x) \sum_{j=1}^{N} \sum_{k=1}^{d} \int_{0}^{t} \gamma_{i j}^{X_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} \varepsilon V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k} \in \mathcal{K}_{r-1},  \tag{2.16}\\
& \int_{0}^{t}\left[D_{s, k} G(t, x)\right] \gamma_{i j}^{X_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} \varepsilon V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d s \in \mathcal{K}_{r}, \tag{2.17}
\end{align*}
$$

since $J_{t}^{x, \varepsilon},\left(J_{t}^{x, \varepsilon}\right)^{-1} \in \mathcal{K}_{0}, \gamma_{i j}^{X_{t}^{\varepsilon}} \in \mathcal{K}_{-2}$ and

$$
\begin{equation*}
\int_{0}^{t} \gamma_{i j}^{X_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} \varepsilon V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k} \in \mathcal{K}_{-2+1}=\mathcal{K}_{-1} . \tag{2.18}
\end{equation*}
$$

Then, $H_{(i)}\left(X_{t}^{x, \varepsilon}, G(t, x)\right) \in \mathcal{K}_{r-1}$ and $H_{\alpha^{(k)}}\left(X_{t}^{x, \varepsilon}, G(t, x)\right) \in \mathcal{K}_{r-k}$. Therefore, we have the assertion.

## 3 Weak Approximation with Asymptotic Expansion Method

In the remainder of the paper, we use the following norms and semi-norms:

$$
\begin{align*}
& \|f\|_{\infty}=\sup _{x \in \mathbf{R}^{N}}|f(x)|, \quad\|\nabla f\|_{\infty}=\max _{i \in\{1, \cdots, N\}}\left\|\frac{\partial f}{\partial x_{i}}\right\|_{\infty}  \tag{3.1}\\
& \left\|\nabla^{i} f\right\|_{\infty}=\max _{j_{1}, \cdots, j_{i} \in\{1, \cdots, N\}}\left\|\frac{\partial^{i} f}{\partial x_{j_{1}} \cdots \partial x_{j_{i}}}\right\|_{\infty}, \quad f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right) . \tag{3.2}
\end{align*}
$$

In the first step, we give approximation results of an asymptotic expansion with Malliavin weights for $E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ where

$$
\begin{equation*}
X_{t}^{x, \varepsilon}=x+\int_{0}^{t} V_{0}\left(\varepsilon, X_{s}^{x, \varepsilon}\right) d s+\varepsilon \sum_{j=1}^{d} \int_{0}^{t} V_{j}\left(X_{s}^{x, \varepsilon}\right) d B_{s}^{j} \tag{3.3}
\end{equation*}
$$

Under the smoothness of the vector fields $V_{j}, j=0,1, \cdots, d, X_{t}^{x, \varepsilon}$ is expanded as

$$
\begin{equation*}
X_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\left.\varepsilon \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}+\left.\varepsilon^{2} \frac{1}{2!} \frac{\partial^{2}}{\partial \varepsilon^{2}} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}+\cdots, \text { in } \mathbf{D}^{\infty} \tag{3.4}
\end{equation*}
$$

Here, the above expansion in the space $\mathbf{D}^{\infty}$ is given in the sense that for all $m \in \mathbf{N}$,

$$
\underset{\varepsilon \downarrow 0}{\limsup } \frac{1}{\varepsilon^{m+1}}\left\|X_{t}^{x, \varepsilon}-\left\{X_{t}^{x, 0}+\left.\sum_{i=1}^{m} \varepsilon^{i} \frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}\right\}\right\|_{\mathbf{D}^{k, p}}<\infty
$$

For instance, see Watanabe (1987) and Kunitomo and Takahashi (2003) for the details.
Let us define $\bar{X}_{t}^{x, \varepsilon}$ as the sum of the first two terms in the expansion (3.4) as follows:

$$
\begin{equation*}
\bar{X}_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\left.\varepsilon \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0} \tag{3.6}
\end{equation*}
$$

We remark that $X_{t}^{x, 0}$ is the solution to the following ODE

$$
\begin{equation*}
X_{t}^{x, 0}=x+\int_{0}^{t} V_{0}\left(0, X_{s}^{x, 0}\right) d s \tag{3.7}
\end{equation*}
$$

and $\left.\frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon}\right|_{\varepsilon=0}$ satisfies the following linear SDE:

$$
\begin{align*}
\left.\frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon, l}\right|_{\varepsilon=0}= & \left.\int_{0}^{t} \frac{\partial}{\partial \varepsilon} V_{0}^{l}\left(\varepsilon, X_{s}^{x, 0}\right)\right|_{\varepsilon=0} d s+\sum_{j=1}^{d} \int_{0}^{t} V_{j}^{l}\left(X_{s}^{x, 0}\right) d B_{s}^{j}  \tag{3.8}\\
& +\left.\left.\sum_{k=1}^{N} \int_{0}^{t} \partial_{k} V_{0}^{l}\left(0, X_{s}^{x, \varepsilon}\right)\right|_{\varepsilon=0} \frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon, k}\right|_{\varepsilon=0} d s \\
\left.\frac{\partial}{\partial \varepsilon} X_{0}^{x, \varepsilon, l}\right|_{\varepsilon=0}= & 0, \quad l=1, \cdots, N . \tag{3.9}
\end{align*}
$$

The solution of $\left.\frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon}\right|_{\varepsilon=0}$ is given by

$$
\begin{equation*}
\sum_{j=1}^{d} \int_{0}^{t} J_{t}^{x, 0}\left(J_{u}^{x, 0}\right)^{-1} V_{j}\left(X_{u}^{x, 0}\right) d B_{u}^{j}+\left.\int_{0}^{t} J_{t}^{x, 0}\left(J_{u}^{x, 0}\right)^{-1} \frac{\partial}{\partial \varepsilon} V_{0}\left(\varepsilon, X_{u}^{x, 0}\right)\right|_{\varepsilon=0} d u \tag{3.10}
\end{equation*}
$$

where $J_{t}^{x, 0}=\nabla_{x} X_{t}^{x, 0}$ (See (6.6) in P. 354 of Karatzas and Shreve (1991) for example). Note that $\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}$ is a Gaussian random variable with a mean $\mu(t)$ and a covariance matrix $\Sigma(t)=$ $\left(\Sigma_{i, j}(t)\right)_{1 \leq i, j \leq N}$

$$
\begin{align*}
& \mu(t)=\left.\int_{0}^{t} J_{t}^{x, 0}\left(J_{u}^{x, 0}\right)^{-1} \frac{\partial}{\partial \varepsilon} V_{0}\left(\varepsilon, X_{u}^{x, 0}\right)\right|_{\varepsilon=0} d u  \tag{3.11}\\
& \Sigma_{i, j}(t)=\sum_{k=1}^{d} \int_{0}^{t}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{i}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{j} d s \tag{3.12}
\end{align*}
$$

Here, we note that $t \mapsto \mu(t)$ and $t \mapsto \Sigma_{i, j}(t), 1 \leq i, j \leq N$, are deterministic functions. Therefore $\bar{X}_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\left.\varepsilon \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}$ is a Gaussian random variable with a mean $X_{t}^{x, 0}+\varepsilon \mu(t)$ and a covariance matrix $\varepsilon^{2} \Sigma(t)=\left(\varepsilon^{2} \Sigma_{i, j}(t)\right)_{1 \leq i, j \leq N}$.

## Remark 1.

1. When $V_{0}(\varepsilon, x)=\varepsilon V_{0}(x), \bar{X}_{t}^{x, \varepsilon}$ is given by

$$
\begin{equation*}
\bar{X}_{t}^{x, \varepsilon}=x+\varepsilon \sum_{i=0}^{d} V_{i}(x) \int_{0}^{t} d B_{s}^{i} \tag{3.13}
\end{equation*}
$$

where $B_{t}^{0}=t$.
2. When $V_{0}(\varepsilon, x)=V_{0}(x), \bar{X}_{t}^{x, \varepsilon}$ is given by

$$
\begin{equation*}
\bar{X}_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\varepsilon \sum_{j=1}^{d} \int_{0}^{t} J_{t}^{x, 0}\left(J_{u}^{x, 0}\right)^{-1} V_{j}\left(X_{u}^{x, 0}\right) d B_{u}^{j} \tag{3.14}
\end{equation*}
$$

The next theorem shows the local approximation errors for $E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ using Malliavin weights. Theorem 1. Under the condition $[\mathbf{H}]$, we have the followings;

1. For any $t \in(0,1]$ and $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, there exists $C>0$ such that

$$
\begin{align*}
& \sup _{x \in \mathbf{R}^{N}}\left|E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]-\left\{E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]+\sum_{j=1}^{m} \varepsilon^{j} E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right]\right\}\right| \\
& \leq \varepsilon^{m+1} C\left(\sum_{k=1}^{m+1} t^{(m+1+k) / 2}\left\|\nabla^{k} f\right\|_{\infty}\right), \tag{3.15}
\end{align*}
$$

where $\Phi_{t}^{j}, j \geq 1$, is the Malliavin weights defined by

$$
\begin{align*}
\Phi_{t}^{j}= & \sum_{k=1}^{j} \sum_{\beta_{1}+\cdots+\beta_{k}=j+k, \beta_{l} \geq 2} \sum_{\alpha^{(k)} \in\{1, \cdots, N\}^{k}} \frac{1}{k!} \\
& H_{\alpha^{(k)}}\left(\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0}\right) . \tag{3.16}
\end{align*}
$$

2. For any $t \in(0,1]$ and Lipschitz continuous function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left|E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]-\left\{E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]+\sum_{j=1}^{m} \varepsilon^{j} E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right]\right\}\right| \leq \varepsilon^{m+1} C t^{(m+2) / 2} \tag{3.17}
\end{equation*}
$$

with same weights in (3.16).
3. For any $t \in(0,1]$ and bounded Borel function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left|E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]-\left\{E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]+\sum_{j=1}^{m} \varepsilon^{j} E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right]\right\}\right| \leq \varepsilon^{m+1} C t^{(m+1) / 2} \tag{3.18}
\end{equation*}
$$

with same weights in (3.16).

## Proof.

See Appendix A.

Remark 2. When $\tilde{V}_{0}(\varepsilon, x)=\varepsilon \tilde{V}_{0}(x), X_{t}^{x, \varepsilon}$ has the following expansion:

$$
\begin{aligned}
X_{t}^{x, \varepsilon}= & x+\varepsilon \sum_{j=0}^{d} \tilde{V}_{j}(x) \int_{0}^{t} \circ d B_{s}^{j} \\
& +\sum_{k=2}^{m} \varepsilon^{k} \sum_{\left(i_{1}, \cdots, i_{k}\right) \in\{0,1, \cdots, d\}^{k}} \\
& \quad\left(\tilde{V}_{i_{1}} \cdots \tilde{V}_{i_{k}}\right)(x) \int_{0<t_{1}<\cdots<t_{k}<t} \circ d B_{t_{1}}^{i_{1}} \circ \cdots \circ d B_{t_{k}}^{i_{k}} \\
& +\varepsilon^{m+1} \tilde{R}_{m}(t, x, \varepsilon)
\end{aligned}
$$

where $\tilde{R}_{m}(t, x, \varepsilon)$ is the residual. Here, we used the notation $B_{t}^{0}=t$. Then,

$$
\begin{aligned}
\left.\frac{1}{k!} \frac{\partial^{k}}{\partial \varepsilon^{k}} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}= & \sum_{\left(i_{1}, \cdots, i_{k}\right) \in\{0,1, \cdots, d\}^{k}} \\
& \left(\tilde{V}_{i_{1}} \cdots \tilde{V}_{i_{k}}\right)(x) \int_{0<t_{1}<\cdots<t_{k}<t} \circ d B_{t_{1}}^{i_{1}} \circ \cdots \circ d B_{t_{k}}^{i_{k}}
\end{aligned}
$$

Remark 3. $\Phi_{t}^{j}$ is obtained by multiple Skorohod integral and each Malliavin weight is concretely
calculated as follows; for $G(t, x) \in \mathcal{K}_{r}$ and $i=1, \cdots, N$,

$$
\begin{align*}
& H_{(i)}\left(\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}, G(t, x)\right) \\
= & G(t, x) \sum_{j=1}^{N} \sum_{k=1}^{d}\left[\Sigma(t)^{-1}\right]_{i, j} \int_{0}^{t}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{j} d B_{s}^{k} \\
& -\sum_{j=1}^{N} \sum_{k=1}^{d}\left[\Sigma(t)^{-1}\right]_{i, j} \int_{0}^{t} D_{s, k} G(t, x)\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{j} d s \tag{3.19}
\end{align*}
$$

with the deterministic covariance matrix $\left(\Sigma_{i, j}(t)\right)_{1 \leq i, j \leq N}$ corresponds to (3.12), i.e.

$$
\begin{align*}
\Sigma_{i, j}(t) & =\left.\left.\sum_{k=1}^{d} \int_{0}^{t} D_{s, k} \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon, i}\right|_{\varepsilon=0} D_{s, k} \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon, j}\right|_{\varepsilon=0} d s \\
& =\sum_{k=1}^{d} \int_{0}^{t}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{i}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{j} d s \tag{3.20}
\end{align*}
$$

Let $\left(P_{t}\right)_{t}$ be linear operators on $f \in C_{b}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$ defined by

$$
\begin{equation*}
P_{t} f(x)=E\left[f\left(X_{t}^{x, \varepsilon}\right)\right] . \tag{3.21}
\end{equation*}
$$

We remark that $\left(P_{t}\right)_{t}$ is a semigroup. Also let $\left(\bar{P}_{t}\right)_{t}$ be linear operators on $f \in C_{b}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$ defined by

$$
\begin{equation*}
\bar{P}_{t} f(x)=E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right] \tag{3.22}
\end{equation*}
$$

Next, as an approximation of $P_{s}$ we introduce a linear operator $Q_{(s)}^{m}$ below. Firstly, for $j \geq 1$ and $t \in(0,1]$, let $\bar{P}_{\Phi^{j}}(t)$ be a linear operator defined by the following expectation with Malliavin weight $\Phi_{t}^{j}$

$$
\begin{equation*}
\bar{P}_{\Phi^{j}}(t) f(x)=E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right] \tag{3.23}
\end{equation*}
$$

Then, $\left(Q_{(s)}^{m}\right)_{s \in(0,1]}$ is defined as linear operators:

$$
\begin{equation*}
Q_{(s)}^{m} f(x)=\bar{P}_{s} f(x)+\sum_{j=1}^{m} \varepsilon^{j} \bar{P}_{\Phi^{j}}(s) f(x) \tag{3.24}
\end{equation*}
$$

We remark that

$$
\begin{align*}
\bar{P}_{\Phi^{j}}(t) f(x) & =\int_{\mathbf{R}^{N}} f(y) E\left[\Phi_{t}^{j} \mid \bar{X}_{t}^{x, \varepsilon}=y\right] p^{\bar{X}^{\varepsilon}}(t, x, y) d y  \tag{3.25}\\
& =E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \mathcal{M}_{(j)}\left(t, x, \bar{X}_{t}^{x, \varepsilon}\right)\right] \tag{3.26}
\end{align*}
$$

where $\mathcal{M}_{(j)}(t, x, y)=E\left[\Phi_{t}^{j} \mid \bar{X}_{t}^{x, \varepsilon}=y\right]$ and $y \mapsto p^{\bar{X}^{\varepsilon}}(t, x, y)$ is the density of $\bar{X}_{t}^{x, \varepsilon}$.
Then, $Q_{(s)}^{m}$ can be written as follows;

$$
\begin{equation*}
Q_{(s)}^{m} f(x)=E\left[f\left(\bar{X}_{s}^{x, \varepsilon}\right) \mathcal{M}^{m}\left(s, x, \bar{X}_{s}^{x, \varepsilon}\right)\right] \tag{3.27}
\end{equation*}
$$

where $\mathcal{M}^{m}(s, x, y)=1+\sum_{j=1}^{m} \varepsilon^{j} \mathcal{M}_{(j)}(s, x, y)$.
Then, we have the following explicit representation for the Malliavin weight function $\mathcal{M}^{m}$.

Theorem 2. Under the condition $[\mathbf{H}]$, the Malliavin weight function $\mathcal{M}^{m}$ is given by

$$
\begin{align*}
& \mathcal{M}^{m}(t, x, y)  \tag{3.28}\\
= & 1+\sum_{j=1}^{m} \varepsilon^{j} \sum_{k=1}^{j} \sum_{\beta_{1}+\cdots+\beta_{k}=j+k, \beta_{l} \geq 2} \sum_{\alpha^{(k)} \in\{1, \cdots, N\}^{k}} \frac{\varepsilon^{k}}{k!} \\
& \partial_{\alpha_{k}}^{*} \circ \partial_{\alpha_{k-1}}^{*} \circ \cdots \circ \partial_{\alpha_{1}}^{*} E\left[\left.\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0} \right\rvert\, \bar{X}_{t}^{x, \varepsilon}=y\right],
\end{align*}
$$

where $\partial^{*}$ is the divergence operator on the Gaussian space $\left(\mathbf{R}^{N}, \nu\right)$, i.e.

$$
\begin{gather*}
\nu(d y)=p^{\bar{X}^{\varepsilon}}(t, x, y) d y \\
=\frac{1}{(2 \pi \varepsilon)^{N / 2} \operatorname{det}(\Sigma(t))^{1 / 2}} e^{-\frac{\left(y-X_{t}^{x, 0}-\varepsilon \mu(t)\right)^{\top} \Sigma^{-1}(t)\left(y-X_{t}^{x, 0}-\varepsilon \mu(t)\right)}{2 \varepsilon^{2}}} d y \\
\partial_{i}^{*} A(y)=-\left[\frac{\partial}{\partial y_{i}} \log p^{\bar{X}^{\varepsilon}}(t, x, y)\right] A(y)-\frac{\partial}{\partial y_{i}} A(y), \quad A \in \mathcal{S}\left(\mathbf{R}^{N}\right), \quad 1 \leq i \leq N . \tag{3.29}
\end{gather*}
$$

Here, $\mu(t)$ and $\Sigma(t)=\left(\Sigma_{i, j}(t)\right)_{1 \leq i, j \leq N}$ are defined in (3.11) and (3.12), respectively, that is,

$$
\begin{align*}
& \mu(t)=\left.\int_{0}^{t} J_{t}^{x, 0}\left(J_{u}^{x, 0}\right)^{-1} \frac{\partial}{\partial \varepsilon} V_{0}\left(\varepsilon, X_{u}^{x, 0}\right)\right|_{\varepsilon=0} d u  \tag{3.30}\\
& \Sigma_{i, j}(t)=\sum_{k=1}^{d} \int_{0}^{t}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{i}\left(J_{t}^{x, 0}\left(J_{s}^{x, 0}\right)^{-1} V_{k}\left(X_{s}^{x, 0}\right)\right)^{j} d s \tag{3.31}
\end{align*}
$$

and $\mathcal{S}\left(\mathbf{R}^{N}\right)$ is the Schwartz rapidly decreasing functions on $\mathbf{R}^{N}$.

## Proof.

See Appendix B
Remark 4. The term $\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0}$ in each conditional expectation in (3.28) of Theorem 2 is generally expressed as a finite sum of iterated multiple Wiener-Itô integrals. Hence, we are able to explicitly compute each conditional expectation, conditioned on $\bar{X}_{t}^{x, \varepsilon}$ that is given by the first order Wiener-Itô integral.

For instance, let $q_{k}=\left(q_{k, 1}, \cdots, q_{k, d}\right)^{\top}, q_{k, i} \in L^{2}([0, t]), k=1,2,3,4, i=1, \cdots, d$ and $h_{l}(\xi ; v)$ be the (one dimensional) Hermite polynomial of degree $l$ with parameter $v=\int_{0}^{t} q_{1}^{\top}(s) q_{1}(s) d s$. Then, the conditional expectations of the second and the third order iterated multiple Wiener-Itô integrals are evaluated as the following formulas:

$$
\begin{gather*}
\mathrm{E}\left[\int_{0}^{t} \int_{0}^{s} q_{2}^{\top}(u) d B_{u} q_{3}^{\top}(s) d B_{s} \mid \int_{0}^{t} q_{1}^{\top}(s) d B_{s}=\xi\right]  \tag{3.32}\\
=\left(\int_{0}^{t} \int_{0}^{s} q_{2}^{\top}(u) q_{1}(u) d u q_{3}^{\top}(s) q_{1}(s) d s\right) \frac{h_{2}(\xi ; v)}{v^{2}}, \\
\mathrm{E}\left[\int_{0}^{t} \int_{0}^{s} \int_{0}^{u} q_{2}^{\top}(r) d B_{r} q_{3}^{\top}(u) d B_{u} q_{4}^{\top}(s) d B_{s} \mid \int_{0}^{t} q_{1}^{\top}(s) d B_{s}=\xi\right]  \tag{3.33}\\
=\left(\int_{0}^{t} q_{4}^{\top}(s) q_{1}(s) \int_{0}^{s} q_{3}^{\top}(u) q_{1}(u) \int_{0}^{u} q_{2}^{\top}(r) q_{1}(r) d r d u d s\right) \frac{h_{3}(\xi ; v)}{v^{3}}
\end{gather*}
$$

where $h_{2}(\xi ; v)=\xi^{2}-v$ and $h_{3}(\xi ; v)=\xi^{3}-3 v \xi$.
The conditional expectations of higher order iterated multiple Wiener-Itô integrals can be evaluated in the similar manner. For the details see Takahashi (1999) and Takahashi et al. (2009). In fact, we obtain the Malliavin weights appearing in the numerical examples in Section 5 as closed forms by applying the formulas.

Therefore, Theorem 1 is summarized as follows.
Corollary 1. Assume that the condition $[\mathbf{H}]$ holds.

1. There exists $C>0$ such that

$$
\begin{equation*}
\left\|P_{s} f-Q_{(s)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} C\left(\sum_{k=1}^{m+1} s^{(m+1+k) / 2}\left\|\nabla^{k} f\right\|_{\infty}\right) \tag{3.34}
\end{equation*}
$$

for any $s \in(0,1]$ and $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$.
2. There exists $C>0$ such that

$$
\begin{equation*}
\left\|P_{s} f-Q_{(s)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} C s^{(m+2) / 2} \tag{3.35}
\end{equation*}
$$

for any $s \in(0,1]$ and Lipschitz continuous function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$.
3. There exists $C>0$ such that

$$
\begin{equation*}
\left\|P_{s} f-Q_{(s)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} C s^{(m+1) / 2} \tag{3.36}
\end{equation*}
$$

for any $s \in(0,1]$ and bounded Borel function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$.
Remark 5. The above results are obtained based on the integration by parts argument for $G(s, x) \in$ $\mathcal{K}_{r}$ with time $s \in(0,1]$. However, we are able to show that the same results hold for $s \in(0, T]$, $T>0$, using the properties of the elements in the space $\mathcal{K}_{r}^{T}$ defined as in Crisan et al. (2013).

Next, for $T>0, \gamma>0$, define a partition $\pi=\left\{\left(t_{0}, t_{1}, \cdots, t_{n}\right): 0=t_{0}<t_{1}<\cdots<t_{n}=\right.$ $\left.T, t_{k}=k^{\gamma} T / n^{\gamma}, n \in \mathbf{N}\right\}$ and $s_{k}=t_{k}-t_{k-1}, k=1, \cdots, n$. Using the asymptotic expansion operator $Q^{m}$ of $P$, we can guess the following semigroup approximation.

$$
E\left[f\left(X_{T}^{x, \varepsilon}\right)\right]=P_{T} f(x)=P_{s_{n}} P_{s_{n-1}} \cdots P_{s_{1}} f(x) \simeq Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f(x)
$$

The next theorem shows our main result on the approximation error for this scheme.

Theorem 3. Assume that the condition $[\mathbf{H}]$ holds. Let $T>0, \gamma>0$ and $n \in \mathbf{N}$.

1. For any $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, there exists $C>0$ such that

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{\gamma(m+2) / 2}}, \quad 0<\gamma<m /(m+2),  \tag{3.37}\\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}(1+\log n), \quad \gamma=m /(m+2), \\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}, \quad \gamma>m /(m+2) . \tag{3.38}
\end{align*}
$$

2. For any Lipschitz continuous function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{\gamma(m+2) / 2}}, \quad 0<\gamma<m /(m+2) \\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}(1+\log n), \quad \gamma=m /(m+2),  \tag{3.40}\\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}, \quad \gamma>m /(m+2) \tag{3.41}
\end{align*}
$$

3. For any bounded Borel function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{\gamma(m+1) / 2}}, \quad 0<\gamma<(m-1) /(m+1), \\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{(m-1) / 2}}(1+\log n), \quad \gamma=(m-1) /(m+1),  \tag{3.43}\\
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{(m-1) / 2}}, \quad \gamma>(m-1) /(m+1) . \tag{3.44}
\end{align*}
$$

## Proof.

See Appendix C.
Remark 6. Due to the theorem above, the higher order asymptotic expansion provides the higher order weak approximation. In fact, we can mostly attain enough accuracy even when the expansion order $m$ is low such as $m=1,2$. In Section 5 we confirm this fact through numerical examples.
Remark 7. When $\gamma=1$, i.e. $s_{k}=T / n$ for all $k=1, \cdots, n$, we have

1. For any $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, there exists $C>0$ such that

$$
\left\|P_{T} f-\left(Q_{(T / n)}^{m}\right)^{n} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}
$$

2. For any Lipschitz continuous function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\left\|P_{T} f-\left(Q_{(T / n)}^{m}\right)^{n} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{m / 2}}
$$

3. For any bounded Borel function $f: \mathbf{R}^{N} \rightarrow \mathbf{R}$, there exists $C>0$ such that

$$
\left\|P_{T} f-\left(Q_{(T / n)}^{m}\right)^{n} f\right\|_{\infty} \leq \varepsilon^{m+1} \frac{C}{n^{(m-1) / 2}}
$$

## 4 Computation with Malliavin Weights

This section illustrates computational scheme for implementation of our method.

### 4.1 Backward Discrete-time Approximation

For preparation we describe a backward discrete time approximation of our method.
For $s \in(0,1]$ and $x, y \in \mathbf{R}^{N}$, define $p^{m}(s, x, y)$ as

$$
\begin{equation*}
Q_{(s)}^{m} f(x)=\int_{\mathbf{R}^{N}} f(y) p^{m}(s, x, y) d y \tag{4.1}
\end{equation*}
$$

Then, $p^{m}(s, x, y)$ is given by using the Malliavin weight function $\mathcal{M}^{m}$ as follows;

$$
\begin{equation*}
p^{m}(s, x, y)=\mathcal{M}^{m}(s, x, y) p^{\bar{X}^{\varepsilon}}(s, x, y) \tag{4.2}
\end{equation*}
$$

with

$$
\begin{equation*}
p^{\bar{X}^{\varepsilon}}(s, x, y)=\frac{1}{\left(2 \pi \varepsilon^{2}\right)^{N / 2} \operatorname{det}(\Sigma(s))^{1 / 2}} e^{-\frac{\left(y-\varepsilon \mu(s)-X_{s}^{x, 0}\right)^{\top} \Sigma^{-1}(s)\left(y-\varepsilon \mu(s)-X_{s}^{x, 0}\right)}{2 \varepsilon^{2}}}, \tag{4.3}
\end{equation*}
$$

where $\mu(s)$ and $\Sigma(s)=\left(\Sigma_{i, j}(s)\right)_{1 \leq i, j \leq N}$ are defined in (3.11) and (3.12), respectively.
Then, we are able to calculate $\left(Q_{(T / n)}^{m}\right)^{n} f(x)$ as follows:

$$
\begin{align*}
& \left(Q_{(T / n)}^{m}\right)^{n} f(x)  \tag{4.4}\\
= & \int_{\left(\mathbf{R}^{N}\right)^{n}} f\left(y_{n}\right) \prod_{i=0}^{n-1} p^{m}\left(s_{i}, y_{i}, y_{i+1}\right) d y_{n} \cdots d y_{1}  \tag{4.5}\\
= & \int_{\left(\mathbf{R}^{N}\right)^{n-1}} q_{n-1}\left(y_{n-1}\right) \prod_{i=0}^{n-2} p^{m}\left(s_{i}, y_{i}, y_{i+1}\right) d y_{n-1} \cdots d y_{1}  \tag{4.6}\\
= & \int_{\left(\mathbf{R}^{N}\right)^{n-2}} q_{n-2}\left(y_{n-2}\right) \prod_{i=0}^{n-3} p^{m}\left(s_{i}, y_{i}, y_{i+1}\right) d y_{n-2} \cdots d y_{1}  \tag{4.7}\\
= & \int_{\mathbf{R}^{N}} q_{1}\left(y_{1}\right) p^{m}\left(s_{1}, y_{0}, y_{1}\right) d y_{1}, \tag{4.8}
\end{align*}
$$

with $y_{0}=x$.

### 4.2 Example of Computational Scheme

We are able to compute the expectation in the various ways such as numerical integration and Monte Carlo simulation. As an illustrative purpose and an example, this subsection briefly describes a scheme based on Monte Carlo simulation.

In computation of $\left(Q_{(T / n)}^{m}\right)^{n} f(x)$ with simulation (for the case of $\gamma=1$ ), we store $\bar{X}_{T / n}^{x,(j)} \equiv$ $\bar{X}_{T / n}^{x, \varepsilon,(j)}$, which stands for the $j$-th $(1 \leq j \leq M)$ independent outcome of $\bar{X}^{x, \varepsilon}$ at $T / n$ (that is, at $\left.t_{i}+T / n\right)$ starting from $x$ at each grid $t_{i}=(i T) / n(0 \leq i \leq n-1)$.

Then, we calculate an approximate semigroup at each time grid. That is, $q_{n-1}(x), q_{n-2}(x)$ are calculated as follows:

$$
\begin{align*}
q_{n-1}(x) & =\int_{\mathbf{R}^{N}} f(y) p^{m}(T / n, x, y) d y  \tag{4.9}\\
& =\int_{\mathbf{R}^{N}} f(y) \mathcal{M}^{m}(T / n, x, y) p^{\bar{X}^{\varepsilon}}(T / n, x, y) d y  \tag{4.10}\\
& \simeq \frac{1}{M} \sum_{j=1}^{M} f\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right),  \tag{4.11}\\
q_{n-2}(x) & =\int_{\mathbf{R}^{N}} q_{n-1}(y) p^{m}(T / n, x, y) d y  \tag{4.12}\\
& =\int_{\mathbf{R}^{N}} q_{n-1}(y) \mathcal{M}^{m}(T / n, x, y) p^{\bar{X}^{\varepsilon}}(T / n, x, y) d y  \tag{4.13}\\
& \simeq \frac{1}{M} \sum_{j=1}^{M} q_{n-1}\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right) \tag{4.14}
\end{align*}
$$

Therefore, in general,

$$
\begin{align*}
q_{i-1}(x) & =\int_{\mathbf{R}^{N}} q_{i}(y) p^{m}(T / n, x, y) d y  \tag{4.15}\\
& =\int_{\mathbf{R}^{N}} q_{i}(y) \mathcal{M}^{m}(T / n, x, y) p^{\bar{X}^{\varepsilon}}(T / n, x, y) d y  \tag{4.16}\\
& \simeq \frac{1}{M} \sum_{j=1}^{M} q_{i}\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right) . \tag{4.17}
\end{align*}
$$

Finally, we obtain an approximation:

$$
\begin{align*}
\left(Q_{(T / n)}^{m}\right)^{n} f(x) & =\int_{\mathbf{R}^{N}} q_{1}(y) p^{m}(T / n, x, y) d y  \tag{4.18}\\
& =\int_{\mathbf{R}^{N}} q_{1}(y) \mathcal{M}^{m}(T / n, x, y) p^{\bar{X}^{\varepsilon}}(T / n, x, y) d y  \tag{4.19}\\
& \simeq \frac{1}{M} \sum_{j=1}^{M} q_{1}\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right) \tag{4.20}
\end{align*}
$$

We also remark that if the numerical integration method is applied, the scheme is based on the equations (4.16) and (4.19).

### 4.3 Comparison with Kusuoka-Lyons-Victoir (KLV) Cubature Method

In this subsection, we compare our method to a related work, Kusuoka-Lyons-Victoir (KLV) cubature method on Wiener space (Kusuoka (2001, 2004), Lyons and Victoir (2004)).

As mentioned above, we defined the operator $Q_{(s)}^{m}$ by using the asymptotic expansion with Malliavin weights, while Kusuoka (2001, 2004) and Lyons and Victoir (2004) developed a construction method of a local approximation operator $\hat{Q}_{(s)}^{m}$ for $P_{s}$ based on finite variation paths $\omega_{1}, \cdots, \omega_{l}$ for some $l \in \mathbf{N}$ with weights $\lambda_{1}, \cdots, \lambda_{l}$.

In the following, we summarize our weak approximation method and the KLV cubature scheme.
[Weak approximation with asympotic expansion and Malliavin weights]
Let $X_{t}^{x, \varepsilon}$ be a solution to the following SDE:

$$
\begin{equation*}
d X_{t}^{x, \varepsilon}=V_{0}\left(\varepsilon, X_{t}^{x, \varepsilon}\right) d t+\varepsilon \sum_{i=1}^{d} V_{i}\left(X_{t}^{x, \varepsilon}\right) d B_{s}^{i}, \quad X_{t}^{x, \varepsilon}=x . \tag{4.21}
\end{equation*}
$$

For a Lipschitz continuous function $f, P_{t} f(x)=E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ is approximated by $Q_{(s)}^{m} f(x)=$ $E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]+\sum_{j=1}^{m} \varepsilon^{j} E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right]=E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \mathcal{M}^{m}\left(t, x, \bar{X}_{t}^{x, \varepsilon}\right)\right]$ as follows:

$$
\begin{equation*}
\left\|P_{t} f-Q_{(t)}^{m} f\right\|_{\infty}=O\left(\varepsilon^{m+1} t^{(m+2) / 2}\right), \quad t \in(0,1] . \tag{4.22}
\end{equation*}
$$

Then, we have the global approximation;

$$
\begin{equation*}
\left\|P_{T} f-\left(Q_{(T / n)}^{m}\right)^{n} f\right\|_{\infty}=O\left(\varepsilon^{m+1} n^{-m / 2}\right) . \tag{4.23}
\end{equation*}
$$

It is emphasized that we are able to evaluate Malliavin weights $\mathcal{M}^{m}\left(t, x, \bar{X}_{t}^{x, \varepsilon}\right)$ mostly as closed forms by applying computational schemes such as conditional expectation formulas in Takahashi (1999) and Takahashi et al. (2009). In fact, this is the case for the numerical examples in Section 5 of this paper.

## [KLV cubature scheme on Wiener space]

Let $X_{t}^{x}$ be a solution to the following SDE:

$$
\begin{equation*}
d X_{t}^{x}=V_{0}\left(X_{t}^{x}\right) d t+\sum_{i=1}^{d} V_{i}\left(X_{t}^{x}\right) \circ d B_{s}^{i}, \quad X_{t}^{x}=x \tag{4.24}
\end{equation*}
$$

A set of finite variation paths $\omega=\left(\omega_{1}, \cdots, \omega_{l}\right)$ with $\lambda=\left(\lambda_{1}, \cdots, \lambda_{l}\right)$ forms cubature formula on Wiener Space of degree $m$ if for any $\alpha \in \mathcal{A}_{m}$,

$$
\begin{equation*}
E\left[\int_{0<t_{1}<\cdots<t_{r}<t} \circ d B_{t_{1}}^{\alpha_{1}} \circ \cdots \circ d B_{t_{r}}^{\alpha_{r}}\right]=\sum_{j=1}^{l} \lambda_{j} \int_{0<t_{1}<\cdots<t_{r}<t} d \omega_{j, t_{1}}^{\alpha_{1}} \cdots d \omega_{j, t_{r}}^{\alpha_{r}} . \tag{4.25}
\end{equation*}
$$

$\omega=\left(\omega_{1}, \cdots, \omega_{l}\right)$ and $\lambda=\left(\lambda_{1}, \cdots, \lambda_{l}\right)$ are called the cubature paths and weights, respectively. Here, $\mathcal{A}_{m}$ is a set defined by $\mathcal{A}_{m}=\left\{\left(\alpha_{1}, \cdots, \alpha_{r}\right) \in\{0,1, \cdots, d\}^{r} ; r+\#\left\{j \mid \alpha_{j}=0\right\} \leq m, r \in \mathbf{N}\right\}$. For cubature paths $\omega=\left(\omega_{1}, \cdots, \omega_{l}\right)$ and weights $\lambda=\left(\lambda_{1}, \cdots, \lambda_{l}\right)$, consider the following ODEs:

$$
\begin{align*}
d \hat{X}_{t}^{x}\left(\omega_{j}\right) & =V_{0}\left(\hat{X}_{t}^{x}\left(\omega_{j}\right)\right) d t+\sum_{i=1}^{d} V_{i}\left(\hat{X}_{t}^{x}\left(\omega_{j}\right)\right) d \omega_{j, s}^{i},  \tag{4.26}\\
\hat{X}_{t}^{x}\left(\omega_{j}\right) & =x, \quad j=1, \cdots, l .
\end{align*}
$$

Then, for a Lipschitz continuous function $f, P_{t} f(x)=E\left[f\left(X_{t}^{x}\right)\right]$ can be approximated by $\hat{Q}_{(s)}^{m} f(x)=$ $\sum_{j=1}^{l} \lambda_{j} f\left(\hat{X}_{t}^{x}\left(\omega_{j}\right)\right)$ as follows:

$$
\begin{equation*}
\left\|P_{t} f-\hat{Q}_{(t)}^{m} f\right\|_{\infty}=O\left(t^{(m+1) / 2}\right), \quad t \in(0,1] . \tag{4.27}
\end{equation*}
$$

Then, it can be shown that

$$
\begin{equation*}
\left\|P_{T} f-\left(\hat{Q}_{(T / n)}^{m}\right)^{n} f\right\|_{\infty}=O\left(n^{-(m-1) / 2}\right) . \tag{4.28}
\end{equation*}
$$

See Kusuoka (2001, 2004) and Lyons and Victoir (2004) for the proofs. Here, we note that the Kusuoka-Lyons-Victoir's approximation is generally discussed in the case of non-uniform time grids.

In order to obtain a local approximation, we use Malliavin's integration by parts formula on Wiener space for a Gaussian random variable $\bar{X}_{t}^{x, \varepsilon}=X_{t}^{0, x}+\left.\varepsilon \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}$. Then, the local approximation $Q_{(t)}^{m} f(x)$ is given by multiplying the Malliavin weight function $\mathcal{M}^{m}\left(t, x, \bar{X}_{t}^{x, \varepsilon}\right)$ and $f\left(\bar{X}_{t}^{x, \varepsilon}\right)$. As mentioned above, we can mostly evaluate Malliavin weights $\mathcal{M}^{m}\left(t, x, \bar{X}_{t}^{x, \varepsilon}\right)$ as closed forms.

On the other hand, the Kusuoka-Lyons-Victoir's approximation based on the cubature formula on Wiener space requires to solve the ODEs (4.26) with cubature paths and weights, and then the local approximation $\hat{Q}_{(s)}^{m} f(x)$ is given by the weighted sum of $f\left(\hat{X}_{t}^{x}\left(\omega_{j}\right)\right)$ with the cubature weights $\lambda_{j}, j=1, \cdots, l$.

Finally, we summarize the algorithms of our weak approximation method and the KLV cubature scheme on Wiener space as Algorithm 1 and Algorithm 2, respectively.

```
Algorithm 1 Weak approximation with asympotic expansion and Malliavin weights
    Define the Malliavin weight \(\mathcal{M}^{m}(t, x, y)\).
    for \(i=1\) to \(n\) do
        Simulate Gaussian random variable \(\bar{X}_{T / n}^{x,(j)}, j=1, \cdots, M\).
        if \(i=1\) then
            \(q_{n-i}(x)=\frac{1}{M} \sum_{j=1}^{M} f\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right)\)
        else
            \(q_{n-i}(x)=\frac{1}{M} \sum_{j=1}^{M} q_{n-i+1}\left(\bar{X}_{T / n}^{x,(j)}\right) \mathcal{M}^{m}\left(T / n, x, \bar{X}_{T / n}^{x,(j)}\right)\)
        end if
    end for
    \(P_{T} f(x) \simeq q_{0}(x)\)
```

```
Algorithm 2 Weak approximation: KLV cubature on Wiener space
    Define the cubature paths \(\omega=\left(\omega_{1}, \cdots, \omega_{l}\right)\) and weights \(\lambda=\left(\lambda_{1}, \cdots, \lambda_{l}\right)\).
    for \(i=1\) to \(n\) do
        Solve ODE for \(\hat{X}_{T / n}^{x}\left(\omega_{j}\right), j=1, \cdots, l\).
        if \(i=1\) then
            \(\hat{q}_{n-i}(x)=\sum_{j=1}^{l} \lambda_{j} f\left(\hat{X}_{T / n}^{x}\left(\omega_{j}\right)\right)\)
        else
            \(\hat{q}_{n-i}(x)=\sum_{j=1}^{l} \lambda_{j} \hat{q}_{n-i+1}\left(\hat{X}_{T / n}^{x}\left(\omega_{j}\right)\right)\)
        end if
    end for
    \(P_{T} f(x) \simeq \hat{q}_{0}(x)\)
```


## 5 Numerical Example

This section demonstrates the effectiveness of our method through the numerical examples for option pricing under local and stochastic volatility models.

### 5.1 Local volatility model

The first example takes the following local volatility model:

$$
\begin{align*}
d S_{t}^{x, \varepsilon} & =\varepsilon \sigma\left(S_{t}^{x, \varepsilon}\right) d B_{t}  \tag{5.1}\\
S_{0}^{x, \varepsilon} & =S_{0}=x
\end{align*}
$$

Then, let $\left(\bar{S}_{t}^{x, \varepsilon}\right)_{t \geq 0}$ be the solution to the following SDE;

$$
\begin{align*}
d \bar{S}_{t}^{x, \varepsilon} & =\varepsilon \sigma(x) d B_{t}  \tag{5.2}\\
\bar{S}_{0}^{x, \varepsilon} & =x .
\end{align*}
$$

In this numerical example, for the payoff function $f(x)=\max \{x-K, 0\}$ or $f(x)=\max \{K-x, 0\}$ where $K$ is a positive constant, we apply the first order asymptotic expansion operator, that is $m=1$;

$$
\begin{equation*}
Q_{(t)}^{1} f(x)=E\left[f\left(\bar{S}_{t}^{x, \varepsilon}\right) \mathcal{M}^{1}\left(t, x, \bar{S}_{t}^{x, \varepsilon}\right)\right] \tag{5.3}
\end{equation*}
$$

and the second order asymptotic expansion operator that is, $m=2$;

$$
\begin{equation*}
Q_{(t)}^{2} f(x)=E\left[f\left(\bar{S}_{t}^{x, \varepsilon}\right) \mathcal{M}^{2}\left(t, x, \bar{S}_{t}^{x, \varepsilon}\right)\right] . \tag{5.4}
\end{equation*}
$$

The Malliavin weights $\mathcal{M}^{1}(t, x, y)$ and $\mathcal{M}^{2}(t, x, y)$ are given by

$$
\mathcal{M}^{1}(t, x, y)=1+\varepsilon E\left[\left.H_{(1)}\left(\left.\frac{\partial}{\partial \varepsilon} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0},\left.\frac{1}{2} \frac{\partial^{2}}{\partial \varepsilon^{2}} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0}\right) \right\rvert\, \bar{S}_{t}^{x, \varepsilon}=y\right],
$$

and

$$
\begin{aligned}
\mathcal{M}^{2}(t, x, y)= & \mathcal{M}^{1}(t, x, y)+\varepsilon^{2} E\left[\left.H_{(1)}\left(\left.\frac{\partial}{\partial \varepsilon} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0},\left.\frac{1}{6} \frac{\partial^{3}}{\partial \varepsilon^{3}} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0}\right) \right\rvert\, \bar{S}_{t}^{x}=y\right] \\
& +\frac{1}{2} \varepsilon^{2} E\left[\left.H_{(1,1)}\left(\left.\frac{\partial}{\partial \varepsilon} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0},\left(\left.\frac{1}{2} \frac{\partial^{2}}{\partial \varepsilon^{2}} S_{t}^{x, \varepsilon}\right|_{\varepsilon=0}\right)^{2}\right) \right\rvert\, \bar{S}_{t}^{x, \varepsilon}=y\right]
\end{aligned}
$$

Moreover, we remark that those Malliavin weights are obtained as closed forms.
Also, we specify the local volatility function as a log-normal scaled volatility $\varepsilon \sigma(S)=\varepsilon S_{0}^{1-\beta} S^{\beta}$ with $\beta=0.5$. The parameters are set to be $S_{0}=100$ and $\varepsilon=0.4$. The benchmark values are computed by Monte Carlo simulations (BenchmarkMC) with $10^{7}$ trials and 1000 time steps for the 1 year maturity case or 2000 time steps for the 10 year maturity case.

Figure 1 and Figure 2 show the results. The vertical axis in the figures is the error rate defined by

$$
\text { Error Rate }=(\text { WeakApprox }- \text { BenchmarkMC }) / \text { BenchmarkMC }(\%) .
$$

Here, WeakApprox is our weak approximation based on the asymptotic expansion with Malliavin weights given in previous sections. We observe that the increase in the number of the time steps improves the approximation. (See Error Rate AE 1order and Error Rate AE 1order WeakApprox $n=2,3$ in Figure 1.) We also note that our scheme with the second order expansion and two time steps (Error Rate AE 2order WeakApprox $n=2$ ) improves the base (analytical only) second order expansion (Error Rate AE 2order), and is able to provide an accurate approximation across all the strikes even for the long maturity case such as the 10 year maturity case in Figure 2.


Figure 1: $T=1$ : Local volatility model, Error rates of the 1st and 2nd order asymptotic expansions and their weak approximations


Figure 2: $T=10$ : Local volatility model, Error rates of the 1st and 2nd order asymptotic expansions and the weak approximations

### 5.2 Stochastic volatility model

The second example considers the following stochastic volatility model, which is also known as the log-normal SABR model.

$$
\begin{align*}
d S_{t}^{(z, \sigma)} & =\sigma_{t}^{\sigma} S_{t}^{(z, \sigma)} d B_{t}^{1}, S_{0}^{(z, \sigma)}=z  \tag{5.5}\\
d \sigma_{t}^{\sigma} & =\nu \sigma_{t}^{\sigma}\left(\rho d B_{t}^{1}+\sqrt{1-\rho^{2}} d B_{t}^{2}\right), \sigma_{0}^{\sigma}=\sigma \tag{5.6}
\end{align*}
$$

Next, let us introduce the following perturbed logarithmic SABR model:

$$
\begin{align*}
d X_{1, t}^{(x, \sigma), \varepsilon} & =\varepsilon\left[-\eta \frac{\left(\sigma_{t}^{\sigma, \varepsilon}\right)^{2}}{2} d t+\eta \sigma_{t}^{\sigma, \varepsilon} d B_{t}^{1}\right], X_{1,0}^{(x, \sigma), \varepsilon}=x,  \tag{5.7}\\
d \sigma_{t}^{\sigma, \varepsilon} & =\varepsilon\left[\sigma_{t}^{\sigma, \varepsilon}\left(\rho d B_{t}^{1}+\sqrt{1-\rho^{2}} d B_{t}^{2}\right)\right], \sigma_{0}^{\sigma, \varepsilon}=\sigma, \tag{5.8}
\end{align*}
$$

with $\varepsilon=\nu$ and $\eta=1 / \nu$. For some fixed $T>0$ and $K>0$, the target expectation is given by

$$
\begin{aligned}
& E\left[f\left(X_{1, T}^{(x, \sigma), \varepsilon}, \sigma_{T}^{\sigma, \varepsilon}\right)\right] \equiv E\left[\hat{f}\left(X_{1, T}^{(x, \sigma), \varepsilon}\right)\right] \\
:= & E\left[\max \left\{e^{X_{1, T}^{(x, \sigma), \varepsilon}}-K, 0\right\}\right] \text { or } E\left[\max \left\{K-e^{X_{1, T}^{(x, \sigma), \varepsilon}}, 0\right\}\right] .
\end{aligned}
$$

Next, let $\left(\bar{X}_{1, t}^{(x, \sigma), \varepsilon}, \bar{\sigma}_{t}^{\sigma, \varepsilon}\right)_{t \geq 0}$ be the solution to the following SDE:

$$
\begin{align*}
d \bar{X}_{1, t}^{(x, \sigma), \varepsilon} & =\varepsilon\left[-\eta \frac{\sigma^{2}}{2} d t+\eta \sigma d B_{t}^{1}\right], \bar{X}_{1,0}^{(x, \sigma), \varepsilon}=x  \tag{5.9}\\
d \bar{\sigma}_{t}^{\sigma, \varepsilon} & =\varepsilon\left[\sigma\left(\rho d B_{t}^{1}+\sqrt{1-\rho^{2}} d B_{t}^{2}\right)\right], \bar{\sigma}_{0}^{\sigma, \varepsilon}=\sigma \tag{5.10}
\end{align*}
$$

The parameters are set to be $z=100, \sigma=0.3, \varepsilon=\nu=0.1, \eta=1 / \nu$ and $\rho=-0.5$. The benchmark values are calculated by Monte Carlo simulations with $10^{7}$ trials and 1000 time steps for the 1 year maturity case or 2000 times steps for the 2 year maturity case.

In this example, we use the first order two dimensional asymptotic expansion operator with two time steps, that is $m=1$ and $n=2$. Then, the calculation procedure corresponding to the one in the previous section is the following: Firstly, set $t_{0}=0, t_{1}=T / 2, t_{2}=T$ and $s=t_{k}-t_{k-1}=T / 2$, ( $k=1,2$ ).

- For $\left(\bar{X}_{1, t_{1}}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}, \bar{\sigma}_{1, t_{1}}^{\sigma_{1}, \varepsilon}\right)=\left(x_{1}, \sigma_{1}\right)$ at $t=t_{1}$,

$$
\begin{equation*}
q_{1}\left(x_{1}, \sigma_{1}\right)=E\left[\hat{f}\left(\bar{X}_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}\right) \mathcal{M}^{1}\left(s,\left(x_{1}, \sigma_{1}\right),\left(\bar{X}_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}, \bar{\sigma}_{s}^{\sigma_{1}, \varepsilon}\right)\right)\right] \tag{5.11}
\end{equation*}
$$

- At $t=t_{0}=0$,

$$
\begin{equation*}
q_{0}(x, \sigma)=E\left[q_{1}\left(\bar{X}_{1, s}^{(x, \sigma), \varepsilon}, \bar{\sigma}_{s}^{\sigma, \varepsilon}\right) \mathcal{M}^{1}\left(s,(x, \sigma),\left(\bar{X}_{1, s}^{(x, \sigma), \varepsilon}, \bar{\sigma}_{s}^{\sigma, \varepsilon}\right)\right)\right] \tag{5.12}
\end{equation*}
$$

Here, $\mathcal{M}^{1}\left(t,(x, \sigma),\left(x^{\prime}, \sigma^{\prime}\right)\right)$ is the two dimensional Malliavin weight given by

$$
\begin{aligned}
& \mathcal{M}^{1}\left(t,(x, \sigma),\left(x^{\prime}, \sigma^{\prime}\right)\right) \\
= & 1+\varepsilon E\left[\left.H_{(1)}\left(\left(\left.\frac{\partial}{\partial \varepsilon} X_{1, t}^{(x, \sigma), \varepsilon}\right|_{\varepsilon=0},\left.\frac{\partial}{\partial \varepsilon} \sigma_{t}^{\sigma, \varepsilon}\right|_{\varepsilon=0}\right),\left.\frac{1}{2} \frac{\partial^{2}}{\partial \varepsilon^{2}} X_{1, t}^{(x, \sigma), \varepsilon}\right|_{\varepsilon=0}\right) \right\rvert\,\left(\bar{X}_{1, t}^{(x, \sigma), \varepsilon}, \bar{\sigma}_{t}^{\sigma, \varepsilon}\right)=\left(x^{\prime}, \sigma^{\prime}\right)\right] \\
& +\varepsilon E\left[\left.H_{(1)}\left(\left(\left.\frac{\partial}{\partial \varepsilon} X_{1, t}^{(x, \sigma), \varepsilon}\right|_{\varepsilon=0},\left.\frac{\partial}{\partial \varepsilon} \sigma_{t}^{\sigma, \varepsilon}\right|_{\varepsilon=0}\right),\left.\frac{1}{2} \frac{\partial^{2}}{\partial \varepsilon^{2}} \sigma_{t}^{\sigma, \varepsilon}\right|_{\varepsilon=0}\right) \right\rvert\,\left(\bar{X}_{1, t}^{(x, \sigma), \varepsilon}, \bar{\sigma}_{t}^{\sigma, \varepsilon}\right)=\left(x^{\prime}, \sigma^{\prime}\right)\right] .
\end{aligned}
$$

Moreover, we remark that those Malliavin weights are obtained as closed forms as in the local volatility case.

Actually, at $t_{1}$ we need not implement (5.11), but just compute the first order analytical asymptotic expansion for pricing options with the time-to-maturity $T / 2$ and the initial value $\left(\bar{X}_{1, t_{1}}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}, \bar{\sigma}_{t_{1}}^{\sigma_{1}, 0}\right)=\left(x_{1}, \sigma_{1}\right)$. That is,

$$
\begin{equation*}
\hat{q}_{1}\left(x_{1}, \sigma_{1}\right)=E\left[\hat{f}\left(\bar{X}_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}\right) \hat{\mathcal{M}}^{1}\left(s,\left(x_{1}, \sigma_{1}\right), \bar{X}_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}\right)\right], \tag{5.13}
\end{equation*}
$$

where $\hat{\mathcal{M}}^{1}\left(s,\left(x_{1}, \sigma_{1}\right), y\right)=1+\varepsilon \hat{\mathcal{M}}_{(1)}\left(s,\left(x_{1}, \sigma_{1}\right), y\right)$, and $\hat{\mathcal{M}}_{(1)}\left(s,\left(x_{1}, \sigma_{1}\right), y\right)$ stands for the first order one dimensional Malliavin weight:

$$
\begin{equation*}
\hat{\mathcal{M}}_{(1)}\left(s,\left(x_{1}, \sigma_{1}\right), y\right)=E\left[\left.H_{(1)}\left(\left.\frac{\partial}{\partial \varepsilon} X_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}\right|_{\varepsilon=0},\left.\frac{1}{2} \frac{\partial^{2}}{\partial \varepsilon^{2}} X_{1, s}^{\left(x_{1}, \sigma_{1}\right), \varepsilon}\right|_{\varepsilon=0}\right) \right\rvert\, \bar{X}_{1, s}^{\left(x_{1}, \sigma_{1}, \varepsilon\right)}=y\right] . \tag{5.14}
\end{equation*}
$$

On the other hand, we apply a conditional expectation formula for multidimensional asymptotic expansions in Takahashi (1999) in order to evaluate the Malliavin weight $\mathcal{M}^{1}$ in (5.12).

Figure 3 and Figure 4 show the results (the vertical axis in the figures is Error Rate). Again, our scheme with (5.13) and (5.12) (Error rate AE 1st order Weak Approx $n=2$ ) improves the base first order expansion (Error rate AE 1st order) especially for the deep OTM calls and puts.


Figure 3: $T=1$ : Stochastic volatility model, Error rate of the 1st order 2 dimensional asymptotic expansion and the weak approximation


Figure 4: $T=2$ : Stochastic volatility model, Error rate of the 1st order 2 dimensional asymptotic expansion and the weak approximation

### 5.3 Error Analysis

In this section, we investigate the validity of our approximation by comparing the theoretical and the numerical errors.

In particular, we use the same example of our weak approximation in the local volatility model with the maturity $T=1$ in Section 5.1. Here, we remark that this example can be regarded as the Lipschitz continuous case in Theorem 3.

Based on the results of Theorem 3, for a fixed expansion order $m$ and a time grid parameter $\gamma=$ 1 , the error of the weak approximation by the $m$-th order asymptotic expansion with discretization $n$ approximately satisfies the following relation:

$$
\begin{align*}
& \text { Error Weak Approx with Asymp Expansion }(m, n+1) \\
\simeq & \{\text { Error Weak Approx with Asymp Expansion }(m, n)\} \times(n /(n+1))^{m / 2} \tag{5.15}
\end{align*}
$$

Here, "Error Weak Approx with Asymp Expansion $(m, n)$ " stands for the deviation of "Weak Approximation" from "Benchmark Monte Carlo", that is the value of (WeakApprox)-(BenchmarkMC).

Figure 5 checks the above relation in the case that $m=1$ and $n=2$. In the figure "Theoretical Error: AE 1 order Weak Approx $n=3$ " is calculated by the equation (5.15). It is observed that
the order of the theoretical error is rather similar to that of the numerical error "Error: AE 1 order Weak Approx $n=3$ " across all the strike prices.


Figure 5: Error with respect to $n$ of the weak approximation for fixed $m$
Next, let us check the validity of our method from another viewpoint. For a fixed partition number $n$ and a time grid parameter $\gamma=1$, the error of the weak approximation based on $(m+1)$ th order asymptotic expansion with discretization $n$ labeled by "Error Weak Approx with Asymp Expansion $(m+1, n)$ ", approximately satisfies the relation

$$
\begin{align*}
& \text { Error Weak Approx with Asymp Expansion }(m+1, n) \\
& \simeq \quad\{\text { Error Weak Approx with Asymp Expansion }(m, n)\} \times \varepsilon / \sqrt{n} \tag{5.16}
\end{align*}
$$

Figure 6 examines the above relation in the case $m=1$ and $n=2$ with $\varepsilon=0.4$.
"Theoretical Error: AE 2 order Weak Approx n=2" in Figure 6 is calculated by the equation (5.16). We observe that the order of the theoretical error is very close to that of the numerical error "Error: AE 2 order Weak Approx $n=2$ " for all the strike prices.


Figure 6: Error with respect to $m$ of the weak approximation for fixed $n$
Finally, we test the numerical errors by changing the parameter $\gamma$. Again, we fix the parameter $m=1$. Based on the result of the Lipschitz continuous case in our main theorem (Theorem 3), the errors depend on the range of $\gamma$, i.e. $\gamma<1 / 3=m /(m+2), \gamma=1 / 3=m /(m+2)$, $\gamma>1 / 3=m /(m+2)$.

In order to see the differences of the errors with the different values of $\gamma$, Figure 7 and Figure 8 plot the errors for $\gamma=0.1, \gamma=0.33, \gamma=0.5, \gamma=1.0, \gamma=1.5$ and $\gamma=2.0$ with $n=2$ and $n=3$, respectively.


Figure 7: Error of the weak approximation $n=2$ with respect to time grid parameter $\gamma$


Figure 8: Error of the weak approximation $n=3$ with respect to time grid parameter $\gamma$

We are able to find that the errors are determined by the levels of $\gamma$ and the behavior of the errors is consistent with the theoretical results in Theorem 3.

In addition, we examine which time grid parameter $\gamma$ is optimal. In order to show this, we execute a simple test for the case $m=1$ and $n=2$. Particularly, we solve the following minimization problem:

$$
\begin{align*}
\hat{\gamma}=\operatorname{argmin}\{ & \sum_{K \in\{50,60, \cdots, 190,200\}} \\
& \left.(\text { Error Weak Approx with Asymp Expansion }(m, n ; \gamma, K))^{2}\right\} . \tag{5.17}
\end{align*}
$$

We obtained a parameter $\hat{\gamma}=1.015657$. That is, the value close to $\gamma=1$ (the uniform time grid case) is optimal in our weak approximation with asymptotic expansion.

Therefore, we can conclude that the results of the numerical experiments of our weak approximation are consistent with the theoretical part of this paper, and confirmed the validity of our method.

## 6 Concluding Remarks

In this paper, we have shown a new approximation method for the expectations of the functions of the solutions to SDEs by applying an asymptotic expansion with Malliavin calculus. In particular, based on Kusuoka (2001, 2003a,b, 2004) we have obtained error estimates for our new weak approximation.

Moreover, we have confirmed the validity of our method through the numerical examples for option pricing under local and stochastic volatility models. The scheme is simple and we can
attain enough accuracy even when the expansion order $m$ is low such as $m=1,2$ with a few time steps $n=2,3$ as demonstrated in the previous section.

In order to obtain more accurate numerical approximation, it is natural to use many partitions $n$ in the time scale. However, the computational cost becomes exponentially larger as the number of partitions becomes larger.

To overcome this problem, some efficient tree based (discretization) techniques can be applied. Another possible solution is to use the higher order expansion developed in Takahashi et al. (2012) or Violante (2012). We are convinced that the higher order expansion will improve the accuracy since the higher order $m$-th expansion improves the error orders to $O\left(\varepsilon^{m+1} / n^{m}\right)$ for a Lipschitz continuous $f$ and $O\left(\varepsilon^{m+1} / n^{m-1}\right)$ for a bounded Borel $f$.

Further, applying our method to the higher dimensional problems is one of the important issues. When the dimension $N$ of the state variables becomes higher, the computational cost becomes larger. However, the multidimensional higher order expansion such as in Takahashi (1999) or Takahashi et al. (2012) is a tractable approach to the extension. These topics will be the main themes in our next research.

## A Proof of Theorem 1

Firstly, for the preparation for the proof of the theorem, we characterize the differentiations of the solution to the general perturbed SDEs $X_{t}^{x, \varepsilon}$ with respect to $\varepsilon$ as elements in the space $\mathcal{K}_{r}$. The following lemma plays an important rule for estimating the order of the local approximation for $E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ in Theorem 1 .

## Lemma 2.

$$
\frac{1}{j!} \frac{\partial^{j}}{\partial \varepsilon^{j}} X_{t}^{x, \varepsilon} \in \mathcal{K}_{j}, \quad j \geq 1
$$

Proof. We prove the assertion by induction. First, the differentiation of $X_{t}^{x, \varepsilon}$ with respect to $\varepsilon$ is given by

$$
\begin{align*}
\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon, l}= & \int_{0}^{t} \frac{\partial}{\partial \varepsilon} V_{0}^{l}\left(\varepsilon, X_{s}^{x, \varepsilon}\right) d s+\sum_{j=1}^{d} \int_{0}^{t} V_{j}^{l}\left(X_{s}^{x, \varepsilon}\right) d B_{s}^{j} \\
& +\sum_{k=1}^{N} \int_{0}^{t} \partial_{k} V_{0}^{l}\left(\varepsilon, X_{s}^{x, \varepsilon}\right) \frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon, k} d s \\
& +\varepsilon \sum_{k=1}^{N} \sum_{j=1}^{d} \int_{0}^{t} \partial_{k} V_{j}^{l}\left(X_{s}^{x, \varepsilon}\right) \frac{\partial}{\partial \varepsilon} X_{s}^{x, \varepsilon, k} d B_{s}^{j}, \quad l=1, \cdots, N \tag{A.1}
\end{align*}
$$

The above SDE is linear and the order of the Kusuoka-Stroock function $\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}$ is determined by the following term

$$
\begin{equation*}
\sum_{j=1}^{d} \int_{0}^{t} J_{t}^{x, \varepsilon}\left(J_{u}^{x, \varepsilon}\right)^{-1} V_{j}\left(X_{u}^{x, \varepsilon}\right) d B_{u}^{j} \in \mathcal{K}_{1} \tag{A.2}
\end{equation*}
$$

where $J_{t}^{x, \varepsilon}=\nabla_{x} X_{t}^{x, \varepsilon}$. Since this term gives the minimum order in the terms that consist of (A.1). Here, we use the properties $J_{s}^{x, \varepsilon},\left(J_{s}^{x, \varepsilon}\right)^{-1} \in \mathcal{K}_{0}, s \in(0,1]$ and the boundness of $V_{j}, j=1, \cdots, d$. We have $\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon} \in \mathcal{K}_{1}$ by using the properties 2 and 3 in Lemma 1.

For $i \geq 2, \frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon}=\left(\frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon, 1}, \cdots, \frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon, N}\right)$ is recursively determined by the
following:

$$
\begin{align*}
& \frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon, n}=\frac{1}{i!} \int_{0}^{t} \frac{\partial^{i}}{\partial \varepsilon^{i}} V_{0}^{n}\left(\varepsilon, X_{u}^{x, \varepsilon}\right) d u \\
& +\sum_{m=1}^{i} \sum_{i^{(k)}, \alpha^{(k)}}^{(m)} \frac{1}{(i-m)!} \int_{0}^{t}\left(\prod_{l=1}^{k} \frac{1}{i_{l}!} \frac{\partial^{i_{l}}}{\partial \varepsilon^{i_{l}}} X_{u}^{x, \varepsilon, \alpha_{l}}\right) \partial_{\alpha^{(k)}} \frac{\partial^{i-m}}{\partial \varepsilon^{i-m}} V_{0}^{n}\left(\varepsilon, X_{u}^{x, \varepsilon}\right) d u \\
& +\sum_{i^{(k)}, \alpha^{(k)}}^{(i-1)} \int_{0}^{t}\left(\prod_{l=1}^{k} \frac{1}{i_{l}!} \frac{\partial^{i_{l}}}{\partial \varepsilon^{i_{l}}} X_{u}^{x, \varepsilon, \alpha_{l}}\right) \sum_{j=1}^{d} \partial_{\alpha^{(k)}} V_{j}^{n}\left(X_{u}^{x, \varepsilon}\right) d B_{u}^{j} \\
& +\varepsilon \sum_{i^{(\beta), \alpha^{(k)}}}^{(i)} \int_{0}^{t}\left(\prod_{l=1}^{k} \frac{1}{i_{l}!} \frac{\partial^{i_{l}}}{\partial \varepsilon^{i_{l}}} X_{u}^{x, \varepsilon, \alpha_{l}}\right) \sum_{j=1}^{d} \partial_{\alpha^{(k)}} V_{j}^{n}\left(X_{u}^{x, \varepsilon}\right) d B_{u}^{j}, n=1, \cdots, N, \tag{A.3}
\end{align*}
$$

where

$$
\begin{equation*}
\sum_{i^{(k)}, \alpha^{(k)}}^{(i)}:=\sum_{k=1}^{i} \sum_{i_{1}+\cdots+i_{k}=i, i_{l} \geq 1} \sum_{\alpha^{(k)} \in\{1, \cdots, N\}^{k}} \frac{1}{k!} . \tag{A.4}
\end{equation*}
$$

The above SDE is linear and the order of the Kusuoka-Stroock function $\frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon}$ is determined inductively by the term

$$
\begin{equation*}
\sum_{i^{(k)}, \alpha^{(k)}}^{(i-1)} \int_{0}^{t} J_{t}^{x, \varepsilon}\left(J_{u}^{x, \varepsilon}\right)^{-1}\left(\prod_{l=1}^{k} \frac{1}{i_{l}!} \frac{\partial^{i_{l}}}{\partial \varepsilon^{i_{l}}} X_{u}^{x, \varepsilon, \alpha_{l}}\right) \sum_{j=1}^{d} \partial_{\alpha^{(k)}} V_{j}\left(X_{u}^{x, \varepsilon}\right) d B_{s}^{j} \in \mathcal{K}_{i} \tag{A.5}
\end{equation*}
$$

Since this term gives the minimum order in the terms that consist of (A.3). Then, $\frac{1}{i!} \frac{\partial^{i}}{\partial \varepsilon^{i}} X_{t}^{x, \varepsilon} \in \mathcal{K}_{i}$ by using the properties 2 and 3 in Lemma 1 .

Hereafter, we give the expansion for $E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]$ around $E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]$. We remark that $X_{t}^{x, \varepsilon}$ is not uniformly non-degenerate Wiener functional in Watanabe sense because $X_{t}^{x, 0}$ is completely degenerate as Wiener functional, i.e. $X_{t}^{x, 0}$ is the solution to ODE. Then, in order to give the expansion, we define a Wiener functional $Y_{t}^{\varepsilon}$ given by $Y_{t}^{\varepsilon}=\varphi\left(X_{t}^{x, \varepsilon}\right)=\frac{X_{t}^{x, \varepsilon}-X_{t}^{x, 0}}{\varepsilon}$, i.e. $\left(Y_{t}^{\varepsilon, 1}, \cdots, Y_{t}^{\varepsilon, N}\right)=\left(\varphi_{1}\left(X_{t}^{x, \varepsilon, 1}\right), \cdots, \varphi_{N}\left(X_{t}^{x, \varepsilon, N}\right)\right), \varphi_{i}(\xi)=\frac{\xi-X_{t}^{x, 0, i}}{\varepsilon}, i=1, \cdots, N$. The expansion of $Y_{t}^{\varepsilon}$ is given in the space $\mathbf{D}^{\infty}$, that is, for all $m \in \mathbf{N}$,

$$
\underset{\varepsilon \downarrow 0}{\limsup } \frac{1}{\varepsilon^{m+1}}\left\|Y_{t}^{\varepsilon}-\left\{\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}+\left.\sum_{i=1}^{m} \varepsilon^{i} \frac{1}{(i+1)!} \frac{\partial^{i+1}}{\partial \varepsilon^{i+1}} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}\right\}\right\|_{\mathbf{D}^{k, p}}<\infty,
$$

We note that $Y_{t}^{0}=\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}$ and $Y_{0}^{0}=0$. Let $\sigma^{Y_{t}^{\varepsilon}}$ be the Malliavin covariance matrix of $Y_{t}^{\varepsilon}$ and set

$$
\begin{equation*}
\tau=\inf \left\{s ;\left(J_{s}^{x, \varepsilon}\right)^{-1} A\left(X_{s}^{x, \varepsilon}\right)\left(\left(J_{s}^{x, \varepsilon}\right)^{-1}\right)^{\top} \leq A(x) / 2\right\} . \tag{A.7}
\end{equation*}
$$

Then, we can see

$$
\begin{align*}
\operatorname{det}\left(\sigma^{Y_{t}^{\varepsilon}}\right) \geq & \operatorname{det}\left(J_{t}^{x, \varepsilon}\right)^{2} \operatorname{det} \int_{0}^{\min \{t, \tau\}}\left(J_{s}^{x, \varepsilon}\right)^{-1} A\left(X_{s}^{x, \varepsilon}\right)\left(\left(J_{s}^{x, \varepsilon}\right)^{-1}\right)^{\top} d s \\
\geq & \left(1 / 2^{N}\right) \operatorname{det}\left(J_{t}^{x, \varepsilon}\right)^{2} \operatorname{det}(A(x)) \min \{t, \tau\}^{N},  \tag{A.8}\\
& \sup _{\varepsilon \in(0,1]}\left\|\operatorname{det}\left(J_{t}^{x, \varepsilon}\right)^{-1}\right\|_{L^{p}}<\infty \tag{A.9}
\end{align*}
$$

and

$$
\begin{equation*}
P(\tau<1 / n) \leq c_{1} \exp \left(-c_{2} n^{c_{3}}\right), n \in \mathbf{N} \tag{A.10}
\end{equation*}
$$

where $c_{i}, i=1,2,3$ are positive constants (See the proofs of Theorem 3.4 of Watanabe (1987) or Theorem 10.5 of Ikeda and Watanabe (1989) for (A.8), (A.9) and (A.10)).

Therefore, under the condition $[\mathbf{H}]$, we can see the non-degeneracy of the Malliavin covariance matrix of $Y_{t}^{\varepsilon}$

$$
\begin{equation*}
\sup _{\varepsilon \in(0,1]}\left\|\operatorname{det}\left(\sigma^{Y_{t}^{\varepsilon}}\right)^{-1}\right\|_{L^{p}}<\infty, \quad p<\infty \tag{A.11}
\end{equation*}
$$

Then, the density $\xi \mapsto p_{t}^{Y^{\varepsilon}}(\xi)$ of $Y_{t}^{\varepsilon}$ starting from 0 is smooth. Moreover, the Malliavin covariance matrix $\sigma^{Y_{t}^{\varepsilon}}$ is non-degenerate uniformly in $\varepsilon$;

$$
\begin{equation*}
\underset{\varepsilon \downarrow 0}{\limsup }\left\|\operatorname{det}\left(\sigma^{Y_{t}^{\varepsilon}}\right)^{-1}\right\|_{L^{p}}=\left\|\operatorname{det}\left(\sigma^{Y_{t}^{0}}\right)^{-1}\right\|_{L^{p}}<\infty, \quad p<\infty \tag{A.12}
\end{equation*}
$$

Then, we are able to give the following Taylor formulas for $\xi \mapsto p_{t}^{Y^{\varepsilon}}(\xi)$ and $E\left[f\left(Y_{t}^{\varepsilon}\right)\right]$ using the Malliavin weights:

$$
\begin{align*}
& p_{t}^{Y^{\varepsilon}}(\xi)=p_{t}^{Y^{0}}(\xi)+\sum_{j=1}^{m} \varepsilon^{j} E\left[\Phi_{t}^{j} \mid Y_{t}^{0}=\xi\right] p_{t}^{Y^{0}}(\xi) \\
& \quad+\varepsilon^{m+1} \int_{0}^{1}(1-u)^{m}(m+1) \\
& \quad \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[\left.H_{\alpha^{(k)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right) \right\rvert\, Y_{t}^{\varepsilon u}=\xi\right] p_{t}^{Y^{\varepsilon u}}(\xi) d u,  \tag{A.13}\\
& E\left[f\left(Y_{t}^{\varepsilon}\right)\right]=\int_{\mathbf{R}^{N}} f(\xi) p_{t}^{Y^{\varepsilon}}(\xi) d \xi \\
& \left.=\int_{\mathbf{R}^{N}} f(\xi)\right)_{t}^{Y^{0}}(\xi) d \xi+\sum_{j=1}^{m} \varepsilon^{j} \int_{\mathbf{R}^{N}} f(\xi) E\left[\Phi_{t}^{j} \mid Y_{t}^{0}=\xi\right] p_{t}^{Y^{0}}(\xi) d \xi \\
& +\varepsilon^{m+1} \int_{0}^{1}(1-u)^{m}(m+1) \\
& \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} \int_{\mathbf{R}^{N}} f(\xi) E\left[\left.H_{\alpha \alpha^{(k)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha l}\right|_{\eta=\varepsilon u}\right) \right\rvert\, Y_{t}^{\varepsilon u}=\xi\right] p_{t}^{Y_{t}^{\varepsilon u}}(\xi) d \xi d u \\
& =E\left[f\left(Y_{t}^{0}\right)\right]+\sum_{j=1}^{m} \varepsilon^{j} E\left[f\left(Y_{t}^{0}\right) \Phi_{t}^{j}\right]+\varepsilon^{m+1} r_{m}(t, x, \varepsilon) . \tag{A.14}
\end{align*}
$$

Here, $\Phi_{t}^{j}$ is the Malliavin weight given by

$$
\begin{equation*}
\Phi_{t}^{j}=\sum_{\alpha^{(k)}, \beta^{(k)}}^{j} H_{\alpha^{(k)}}\left(Y_{t}^{0},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0}\right) \tag{A.15}
\end{equation*}
$$

with

$$
\begin{equation*}
\sum_{\alpha^{(k)}, \beta^{(k)}}^{j}=\sum_{k=1}^{j} \sum_{\sum_{l=1}^{k} \beta_{l}=j+k, \beta_{l} \geq 2} \sum_{\alpha^{(k)}=\left(\alpha_{1}, \cdots, \alpha_{k}\right) \in\{1, \cdots, N\}^{k}} \frac{1}{k!} \tag{A.16}
\end{equation*}
$$

and $r_{m}(t, x, \varepsilon)$ is the residual
1.

$$
\begin{align*}
& r_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[\left.\partial_{\alpha^{(k)}} f\left(Y_{t}^{\varepsilon u}\right) \prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right] d u \tag{A.17}
\end{align*}
$$

for $f \in C_{b}^{\infty}\left(\mathbf{R}^{N}\right)$,
2.

$$
\begin{align*}
& r_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \\
& \quad \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[\partial_{\alpha^{(1)}} f\left(Y_{t}^{\varepsilon u}\right) H_{\alpha^{(k-1)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right)\right] d u \tag{A.18}
\end{align*}
$$

for $f \in C_{b}^{1}\left(\mathbf{R}^{N}\right)$,
3.

$$
\begin{align*}
& r_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \\
& \quad \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[f\left(Y_{t}^{\varepsilon u}\right) H_{\alpha^{(k)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right)\right] d u \tag{A.19}
\end{align*}
$$

for an arbitrary bounded continuous function $f$.
Then, by the transformation $X_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\varepsilon Y_{t}^{\varepsilon}$, the density $y \mapsto p^{X^{\varepsilon}}(t, x, y)$ of $X_{t}^{x, \varepsilon}$ is given by

$$
\begin{align*}
p^{X^{\varepsilon}}(t, x, y) & =p_{t}^{Y^{\varepsilon}}(\varphi(y)) \operatorname{det}\left|\frac{\partial\left(\varphi_{1}, \cdots, \varphi_{N}\right)}{\partial\left(y_{1}, \cdots, y_{N}\right)}\right|  \tag{A.20}\\
& =p_{t}^{Y^{\varepsilon}}\left(\left(y-X_{t}^{x, 0}\right) / \varepsilon\right) \frac{1}{\varepsilon^{N}} \tag{A.21}
\end{align*}
$$

Here, we note that

$$
\begin{align*}
& \int_{\mathbf{R}^{N}} f(y) p_{t}^{Y^{0}}\left(\left(y-X_{t}^{x, 0}\right) / \varepsilon\right) \frac{1}{\varepsilon^{N}} d y  \tag{A.22}\\
= & \int_{\mathbf{R}^{N}} f(y) \frac{1}{\left(2 \pi \varepsilon^{2}\right)^{N / 2} \operatorname{det}(\Sigma(t))^{1 / 2}} e^{-\frac{\left(y-\varepsilon \mu(t)-X_{t}^{x, 0}\right)^{\top} \Sigma^{-1}(t)\left(y-\varepsilon \mu(t)-X_{t}^{x, 0}\right)}{2 \varepsilon^{2}}} d y \\
= & \int_{\mathbf{R}^{N}} f(y) p^{\bar{X}^{\varepsilon}}(t, x, y) d y=E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]
\end{align*}
$$

where $\mu(t)$ and $\Sigma(t)$ are the mean and the covariance matrix of $Y_{t}^{0}$ and $y \mapsto p^{\bar{X}^{\varepsilon}}(t, x, y)$ is the density of $\bar{X}_{t}^{x, \varepsilon}$. Also, for $G(t, x) \in \mathcal{K}_{r}$, we have

$$
\begin{align*}
& \int_{\mathbf{R}^{N}} f(y) E\left[H_{(i)}\left(Y_{t}^{0}, G(t, x)\right) \mid Y_{t}^{0}=\left(y-X_{t}^{x, 0}\right) / \varepsilon\right] p_{t}^{Y^{0}}\left(\left(y-X_{t}^{x, 0}\right) / \varepsilon\right) \frac{1}{\varepsilon^{N}} d y \\
= & \int_{\mathbf{R}^{N}} f(y) E\left[H_{(i)}\left(Y_{t}^{0}, G(t, x)\right) \mid \bar{X}_{t}^{x, \varepsilon}=y\right] p^{\bar{X}^{\varepsilon}}(t, x, y) d y \\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) H_{(i)}\left(Y_{t}^{0}, G(t, x)\right)\right], \tag{A.23}
\end{align*}
$$

and

$$
\begin{align*}
& \int_{\mathbf{R}^{N}} f(y) E\left[H_{(i)}\left(Y_{t}^{\varepsilon u}, G(t, x)\right) \mid Y_{t}^{\varepsilon u}=\left(y-X_{t}^{x, 0}\right) / \varepsilon\right] p_{t}^{Y^{\varepsilon u}}\left(\left(y-X_{t}^{x, 0}\right) / \varepsilon\right) \frac{1}{\varepsilon^{N}} d y \\
= & E\left[f\left(\tilde{X}_{t}^{x, \varepsilon u}\right) H_{(i)}\left(Y_{t}^{\varepsilon u}, G(t, x)\right)\right], \tag{A.24}
\end{align*}
$$

with $\tilde{X}_{t}^{x, \varepsilon u}=X_{t}^{x, 0}+\varepsilon Y_{t}^{\varepsilon u}, u \in[0,1]$.
Therefore, (A.14) with (A.17), (A.18) and (A.19) can be transformed into

$$
E\left[f\left(X_{t}^{x, \varepsilon}\right)\right]=E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right)\right]+\sum_{i=1}^{m} \varepsilon^{i} E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \Phi_{t}^{j}\right]+\varepsilon^{m+1} R_{m}(t, x, \varepsilon)
$$

where
1.

$$
\begin{align*}
& R_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[\left.\partial_{\alpha^{(k)}} f\left(\tilde{X}_{t}^{x, \varepsilon u}\right) \prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right] d u \tag{A.25}
\end{align*}
$$

for $f \in C_{b}^{\infty}\left(\mathbf{R}^{N}\right)$,
2.

$$
\begin{align*}
& R_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \\
& \quad \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[\partial_{\alpha^{(1)}} f\left(\tilde{X}_{t}^{x, \varepsilon u}\right) H_{\alpha^{(k-1)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right)\right] d u \tag{A.26}
\end{align*}
$$

for $f \in C_{b}^{1}\left(\mathbf{R}^{N}\right)$,
3.

$$
\begin{align*}
& R_{m}(t, x, \varepsilon) \\
= & \int_{0}^{1}(1-u)^{m}(m+1) \\
& \sum_{\alpha^{(k)}, \beta^{(k)}}^{m+1} E\left[f\left(\tilde{X}_{t}^{x, \varepsilon u}\right) H_{\alpha^{(k)}}\left(Y_{t}^{\varepsilon u},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \eta^{\beta_{l}}} X_{t}^{x, \eta, \alpha_{l}}\right|_{\eta=\varepsilon u}\right)\right] d u \tag{A.27}
\end{align*}
$$

for an arbitrary bounded continuous function $f$.

For $k \leq m+1, \sum_{l=1}^{k} \beta_{l}=m+1+k, \beta_{l} \geq 2, \alpha^{(k)}=\left(\alpha_{1}, \cdots, \alpha_{k}\right) \in\{1, \cdots, N\}^{k}$, the product of the higher derivative terms with respect to $\varepsilon$ of $X_{t}^{x, \varepsilon}$ is characterized as

$$
\begin{equation*}
\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}} \in \mathcal{K}_{m+1+k} \tag{A.28}
\end{equation*}
$$

by using Lemma 2 with Lemma 1.
For $i=1, \cdots, N$ and $G(t, x) \in \mathcal{K}_{r}$, we are able to see the following property for Malliavin weight as in Proposition 1

$$
\begin{align*}
& H_{(i)}\left(Y_{t}^{\varepsilon}, G(t, x)\right)=\delta\left(\sum_{j=1}^{N} G(t, x) \gamma_{i j}^{Y_{t}^{\varepsilon}} D Y_{t}^{\varepsilon, j}\right) \\
& = \\
&  \tag{A.29}\\
& \quad\left[G(t, x) \sum_{j=1}^{N} \sum_{k=1}^{d} \int_{0}^{t} \gamma_{i j}^{Y_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k}\right. \\
& \left.\quad-\sum_{k=1}^{N} \int_{0}^{d}\left[D_{s, k} G(t, x)\right] \gamma_{i j}^{Y_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d s\right] \in \mathcal{K}_{r-1} .
\end{align*}
$$

Here, the first and the second terms in the second equality are characterized by

$$
\begin{align*}
& G(t, x) \sum_{j=1}^{N} \sum_{k=1}^{d} \int_{0}^{t} \gamma_{i j}^{Y_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k} \in \mathcal{K}_{r-1}  \tag{A.30}\\
& \int_{0}^{t}\left[D_{s, k} G(t, x)\right] \gamma_{i j}^{Y_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d s \in \mathcal{K}_{r} \tag{A.31}
\end{align*}
$$

since

$$
\begin{equation*}
\int_{0}^{t} \gamma_{i j}^{Y_{t}^{\varepsilon}}\left(J_{t}^{x, \varepsilon}\left(J_{s}^{x, \varepsilon}\right)^{-1} V_{k}\left(X_{s}^{x, \varepsilon}\right)\right)^{j} d B_{s}^{k} \in \mathcal{K}_{-2+1}=\mathcal{K}_{-1} . \tag{A.32}
\end{equation*}
$$

Then, applying (A.29) with (A.28) for (A.25), (A.26) and (A.27), we obtain the following estimates according to the smoothness of $f$ :
1.

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left|R_{m}(t, x, \varepsilon)\right| \leq C\left(\sum_{k=1}^{m+1} t^{(m+1+k) / 2}\left\|\nabla^{k} f\right\|_{\infty}\right) \tag{A.33}
\end{equation*}
$$

for any $f \in C_{b}^{\infty}\left(\mathbf{R}^{N}\right)$,
2.

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left|R_{m}(t, x, \varepsilon)\right| \leq C t^{(m+2) / 2}\|\nabla f\|_{\infty} \tag{A.34}
\end{equation*}
$$

for any $f \in C_{b}^{1}$,
3.

$$
\begin{equation*}
\sup _{x \in \mathbf{R}^{N}}\left|R_{m}(t, x, \varepsilon)\right| \leq C t^{(m+1) / 2}\|f\|_{\infty} \tag{A.35}
\end{equation*}
$$

for an arbitrary bounded continuous function $f$.
Then, we have the assertion.

## B Proof of Theorem 2

For $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, we have

$$
\begin{align*}
& \int_{\mathbf{R}^{N}} f(y) E\left[\left.H_{(i)}\left(\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}, G(t, x)\right) \right\rvert\, \bar{X}_{t}^{x, \varepsilon}=y\right] \nu(d y)  \tag{B.1}\\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) H_{(i)}\left(\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}, G(t, x)\right)\right] \\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \delta\left(\sum_{j=1}^{N} G(t, x) \gamma_{i j}^{Y_{t}^{0}} D Y_{t}^{0, j}\right)\right] \\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \delta\left(\sum_{j=1}^{N} \varepsilon G(t, x) \frac{1}{\varepsilon^{2}} \gamma_{i j}^{Y_{t}^{0}} \varepsilon D Y_{t}^{0, j}\right)\right] \\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) \delta\left(\sum_{j=1}^{N} \varepsilon G(t, x) \gamma_{i j}^{\bar{X}_{t}^{x, \varepsilon}} D \bar{X}_{t}^{x, \varepsilon, j}\right)\right] \\
= & E\left[f\left(\bar{X}_{t}^{x, \varepsilon}\right) H_{(i)}\left(\bar{X}_{t}^{x, \varepsilon}, \varepsilon G(t, x)\right)\right] \\
= & E\left[\partial_{i} f\left(\bar{X}_{t}^{x, \varepsilon}\right) \varepsilon G(t, x)\right] \\
= & \int_{\mathbf{R}^{N}} \partial_{i} f(y) E\left[\varepsilon G(t, x) \mid \bar{X}_{t}^{x, \varepsilon}=y\right] \nu(d y) \\
= & \int_{\mathbf{R}^{N}} f(y) \partial_{i}^{*} E\left[\varepsilon G(t, x) \mid \bar{X}_{t}^{x, \varepsilon}=y\right] \nu(d y), \tag{B.2}
\end{align*}
$$

where $\gamma^{\bar{X}_{t}^{x, \varepsilon}}=\left(\gamma_{i j}^{x, \varepsilon}\right)_{1 \leq i, j \leq N}$ and $\gamma^{Y_{t}^{0}}=\left(\gamma_{i j}^{Y_{t}^{0}}\right)_{1 \leq i, j \leq N}$ are the inverse matrices of the Malliavin covariance matrices of $\bar{X}_{t}^{x, \varepsilon}$ and $Y_{t}^{0}$, respectively. Here, we note that $Y_{t}^{0}=\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}$ and $\bar{X}_{t}^{x, \varepsilon}=X_{t}^{x, 0}+\left.\varepsilon \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0}=X_{t}^{x, 0}+\varepsilon Y_{t}^{0}$. Also, we use the following relations in the above equations; for $k=1, \cdots, d$ and $j=1, \cdots, N$,

$$
\begin{equation*}
D_{s, k} \bar{X}_{t}^{x, \varepsilon, j}=\left.\varepsilon D_{s, k} \frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon, j}\right|_{\varepsilon=0}=\varepsilon D_{s, k} Y_{t}^{0, j}, s \leq t \tag{B.3}
\end{equation*}
$$

and, for $i, j=1, \cdots, N$,

$$
\begin{equation*}
\gamma_{i j}^{\bar{X}_{t}^{x, \varepsilon}}=\frac{1}{\varepsilon^{2}} \gamma_{i j}^{Y_{t}^{0}} . \tag{B.4}
\end{equation*}
$$

The formulas (B.1) and (B.2) hold for any Lipschitz and bounded Borel function $f$ by using mollifier arguments. We remark that in general for any $G \in \mathbf{D}^{\infty}$ and non-degenerate $F \in$ $\mathbf{D}^{\infty}\left(\mathbf{R}^{N}\right)$, the conditional expectation can be regarded as a map $\mathbf{D}^{\infty} \ni G \mapsto E[G \mid F=\cdot] \in \mathcal{S}\left(\mathbf{R}^{N}\right)$ by Malliavin (1997) and Malliavin and Thalmaier (2006). Therefore, for $k=1, \cdots, j \leq m$, $\sum_{l=1}^{k} \beta_{l}=j+k, \beta_{l} \geq 2, \alpha^{(k)}=\left(\alpha_{1}, \cdots, \alpha_{k}\right) \in\{1, \cdots, N\}^{k}$, we have

$$
\begin{align*}
& E\left[\left.H_{\alpha^{(k)}}\left(\left.\frac{\partial}{\partial \varepsilon} X_{t}^{x, \varepsilon}\right|_{\varepsilon=0},\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0}\right) \right\rvert\, \bar{X}_{t}^{x, \varepsilon}=y\right]  \tag{B.5}\\
= & \varepsilon^{k} \partial_{\alpha_{k}}^{*} \circ \partial_{\alpha_{k-1}}^{*} \circ \cdots \circ \partial_{\alpha_{1}}^{*} E\left[\left.\left.\prod_{l=1}^{k} \frac{1}{\beta_{l}!} \frac{\partial^{\beta_{l}}}{\partial \varepsilon^{\beta_{l}}} X_{t}^{x, \varepsilon, \alpha_{l}}\right|_{\varepsilon=0} \right\rvert\, \bar{X}_{t}^{x, \varepsilon}=y\right],
\end{align*}
$$

and obtain the assertion.

## C Proof of Theorem 3

We follow the similar argument as in Kusuoka $(2001,2003 \mathrm{~b}, 2004)$ and Chapter 3 of Crisan et al. (2013).

Note first that we have the following equality:

$$
\begin{aligned}
& P_{T} f(x)-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f(x) \\
= & P_{T-t_{n-1}} P_{t_{n-1}} f(x)-Q_{\left(s_{n}\right)}^{m} P_{t_{n-1}} f(x) \\
& +Q_{\left(s_{n}\right)}^{m} P_{t_{n-1}} f(x)-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} P_{t_{n-2}} f(x) \\
& +\cdots \\
& +Q_{\left(s_{n}\right)}^{m} \cdots Q_{\left(s_{2}\right)}^{m} P_{t_{1}} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f \\
= & P_{T-t_{n-1}} P_{t_{t_{n-1}}} f(x)-Q_{\left(s_{n}\right)}^{m} P_{t_{n-1}} f(x) \\
& +Q_{\left(s_{n}\right)}^{m}\left(P_{s_{n-1}} P_{t_{n-2}} f(x)-Q_{\left(s_{n-1}\right)}^{m} P_{t_{n-2}} f(x)\right) \\
& \cdots \\
& +Q_{\left(s_{n}\right)}^{m} \cdots Q_{\left(s_{2}\right)}^{m}\left(P_{t_{1}} f(x)-Q_{\left(s_{1}\right)}^{m} f(x)\right) .
\end{aligned}
$$

Then, since $Q^{m}$ is a Markov operator, we have

$$
\begin{aligned}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty} \\
\leq & \left(\left\|P_{s_{n}} P_{t_{n-1}} f-Q_{\left(s_{n}\right)}^{m} P_{t_{n-1}} f\right\|_{\infty}\right. \\
& +\left\|P_{s_{n-1}} P_{t_{n-2}} f-Q_{\left(s_{n-1}\right)}^{m} P_{t_{n-2}} f\right\|_{\infty} \\
& \cdots \\
& \left.+\left\|P_{t_{1}} f-Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}\right)(1+O(\varepsilon)) \\
= & \left(\sum_{k=2}^{n}\left\|P_{s_{k}} P_{t_{k-1}} f-Q_{\left(s_{k}\right)}^{m} P_{t_{k-1}} f\right\|_{\infty}\right. \\
& \left.+\left\|P_{t_{1}} f-Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}\right)(1+O(\varepsilon)) .
\end{aligned}
$$

First, note that we can directly apply (3.34), (3.35) or (3.36) in Corollary 1 to obtain an estimate of $\left\|P_{t_{1}} f-Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}$ for $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, a Lipschitz continuous function or a bounded Borel function, respectively. To obtain an estimate of $\sum_{k=2}^{n}\left\|P_{s_{k}} P_{t_{k-1}} f-Q_{\left(s_{k}\right)}^{m} P_{t_{k-1}} f\right\|_{\infty}$, we apply the results in Corollary 1 to $P_{t} f$ (in stead of $f$ ) as follows.

- By (3.34) in Corollary 1, for $s, t \in(0,1]$ and $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, there exists $C$ such that

$$
\begin{align*}
\left\|P_{s} P_{t} f-Q_{(s)}^{m} P_{t} f\right\|_{\infty} & \leq \sum_{l=1}^{m+1} \varepsilon^{m+1} s^{(m+1+l) / 2} C\left\|\nabla^{l} P_{t} f\right\|_{\infty}  \tag{C.1}\\
& \leq \sum_{l=1}^{m+1} \varepsilon^{m+1} s^{(m+1+l) / 2} C\left\|\nabla^{l} f\right\|_{\infty} \tag{C.2}
\end{align*}
$$

Hence,

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}  \tag{C.3}\\
\leq & C \sum_{k=2}^{n} \sum_{l=1}^{m+1} \varepsilon^{m+1} s_{k}^{(m+1+l) / 2}\left\|\nabla^{l} f\right\|_{\infty}  \tag{C.4}\\
& +C \sum_{l=1}^{m+1} \varepsilon^{m+1} s_{1}^{(m+1+l) / 2}\left\|\nabla^{l} f\right\|_{\infty} . \tag{C.5}
\end{align*}
$$

- By (3.35) in Corollary 1, for $s, t \in(0,1]$ and $f \in C_{b}^{1}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, there exists $C$ such that

$$
\begin{align*}
\left\|P_{s} P_{t} f-Q_{(s)}^{m} P_{t} f\right\|_{\infty} & \leq \varepsilon^{m+1} s^{(m+2) / 2} C\left\|\nabla P_{t} f\right\|_{\infty}  \tag{C.6}\\
& \leq \varepsilon^{m+1} s^{(m+2) / 2} C\|\nabla f\|_{\infty} \tag{C.7}
\end{align*}
$$

Hence,

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}  \tag{C.8}\\
\leq & C \sum_{k=2}^{n} \varepsilon^{m+1} s_{k}^{(m+2) / 2}\|\nabla f\|_{\infty}  \tag{C.9}\\
& +C \varepsilon^{m+1} s_{1}^{(m+2) / 2}\|\nabla f\|_{\infty} . \tag{C.10}
\end{align*}
$$

- By (3.36) in Corollary 1, for $s, t \in(0,1]$ and bounded Borel function $f$ on $\mathbf{R}^{N}$, there exists $C$ (including $\varepsilon^{m+1}$ ) such that

$$
\begin{align*}
\left\|P_{s} P_{t} f-Q_{(s)}^{m} P_{t} f\right\|_{\infty} & \leq \varepsilon^{m+1} s^{(m+1) / 2} C\left\|P_{t} f\right\|_{\infty}  \tag{C.11}\\
& \leq \varepsilon^{m+1} s^{(m+1) / 2} C\|f\|_{\infty} \tag{C.12}
\end{align*}
$$

Hence,

$$
\begin{align*}
& \left\|P_{T} f-Q_{\left(s_{n}\right)}^{m} Q_{\left(s_{n-1}\right)}^{m} \cdots Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}  \tag{C.13}\\
\leq & C \sum_{k=2}^{n} \varepsilon^{m+1} s_{k}^{(m+1) / 2}\|f\|_{\infty}  \tag{C.14}\\
& +C \varepsilon^{m+1} s_{1}^{(m+1) / 2}\|f\|_{\infty} . \tag{C.15}
\end{align*}
$$

Next, we obtain more explicit and compact expressions with regard to $n$ particularly for (C.4), (C.9) and (C.14).

Firstly, from the definition of $s_{k}$ for $k \in\{2, \cdots, n\}$, we have

$$
\begin{equation*}
s_{k}=\frac{\gamma T(k-1)^{\gamma-1}}{n^{\gamma}} \int_{k-1}^{k}(u /(k-1))^{\gamma-1} d u . \tag{C.16}
\end{equation*}
$$

For $k \in\{2, \cdots, n\},(u /(k-1))^{\gamma-1} \leq \max \left\{(k /(k-1))^{\gamma-1}, 1\right\} \leq \max \left\{2^{\gamma-1}, 1\right\}$. Then,

$$
\begin{align*}
s_{k}^{l / 2} & \leq\left(\frac{\gamma T(k-1)^{\gamma-1}}{n^{\gamma}} \max \left\{2^{\gamma-1}, 1\right\}\right)^{l / 2}  \tag{C.17}\\
& \leq C(1 / n)^{\gamma / / 2}(k-1)^{(\gamma-1) l / 2} \tag{C.18}
\end{align*}
$$

where $C=C(T, \gamma)$.
We consider the estimates for three different ranges of $\gamma$ that are larger than, equal to and less than $(l-2) / l$, respectively. $(\gamma=(l-2) / l$ satisfies $(\gamma-1) l / 2=-1$.)
For $0<\gamma<(l-2) / l$,

$$
\begin{equation*}
C(1 / n)^{\gamma l / 2} \sum_{k=2}^{n}(k-1)^{(\gamma-1) l / 2} \leq C(1 / n)^{\gamma l / 2} . \tag{C.19}
\end{equation*}
$$

For $\gamma=(l-2) / l$

$$
\begin{align*}
& C(1 / n)^{\gamma l / 2} \sum_{k=2}^{n}(k-1)^{(\gamma-1) l / 2}  \tag{C.20}\\
= & C(1 / n)^{(l-2) / 2} \sum_{k=1}^{n}(k-1)^{-1}  \tag{C.21}\\
\leq & C(1 / n)^{(l-2) / 2} \log n . \tag{C.22}
\end{align*}
$$

For $\gamma>(l-2) / l$

$$
\begin{align*}
& C(1 / n)^{\gamma l / 2} \sum_{k=2}^{n}(k-1)^{(\gamma-1) l / 2}  \tag{C.23}\\
= & C(1 / n)^{(\gamma-1) l / 2}(1 / n)^{l / 2} \sum_{k=2}^{n}(k-1)^{(\gamma-1) l / 2}  \tag{C.24}\\
= & C(1 / n)^{(l-2) / 2} \sum_{k=2}^{n}\left(\frac{k-1}{n}\right)^{(\gamma-1) l / 2} \frac{1}{n}  \tag{C.25}\\
\leq & C(1 / n)^{(l-2) / 2} \tag{C.26}
\end{align*}
$$

Then, by combining an estimate of $\left\|P_{t_{1}} f-Q_{\left(s_{1}\right)}^{m} f\right\|_{\infty}$ for $f \in C_{b}^{\infty}\left(\mathbf{R}^{N} ; \mathbf{R}\right)$, a Lipschitz continuous function or a bounded Borel function, we have the assertion.

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